BIRLA INSTITUTE OF TECHNOLOGY, MESRA, RANCHI (MID SEMESTER EXAMINATION)

	CLASS:	. TECH SEMES				FER: VII					
	BRANCH: ELECTRICAL AND ELECTRONICS, SESSIC ELECTRONICS AND COMMUNICATION)				IN: MO/2022						
	SUBJECT: IT420 ARTIFICIAL INTELLIGENCE										
	TIME: 2 HOURS FULL A						WARKS: 25				
	 INSTRUCTIONS: The total marks of the questions are 25. Candidates attempt for all 25 marks. Before attempting the question paper, be sure that you have got the correct question paper. The missing data, if any, may be assumed suitably. Tables/Data handbook/Graph paper etc. to be supplied to the candidates in the examination hall. 										
Q1 (a)	Define in yo -Rational ag -Bounded ra -Turing Test -Omniscienc	ur own words: ent tionality. e					[0.5x 4=2]	CO CO1	BL BL1		
Q1 (b)	For each of the following activities, give a PEAS description of the task environment and characterize it in terms of the properties:(a) Shopping for AI books on the Internet.(b) Part picking robot.							CO1	BL1, BL2		
Q2 (a)	Write down	the task environm	ent of the followir	igs:			[2]	CO1,	BL1,		
	Task Environmei	Fully / Partially overserved env.	Single/ Multiagent Env.	Deterministic / Stochastic/ Strategic	Episodic/ Sequential	Discrete/ Continuous		COS	BL3		
	Chess with clock	a									
	Medical diagnosis										
Q2 (b)	Describe ho agent to go (take vacuur	w agent architect al-based and fina n agent / automat	ures are modified lly, to utility-base ed taxi driving as	d from simple re ed agent in part an example).	eflex agent to tially observed	o model-based I environment	[3]	CO1	BL2		
Q3 (a)	The 8-puzzle A tile adjac specified go	e consists of a 3×3 cent to the blank al state, such as th 2 8 1 6 7	board with 8-PUZ space can slide the one shown on the a	ZLE eight numbe into the space he right of the fi 1 8 7	ered tiles and a gure: 2 3 4 6 5	a blank space. is to reach a	[2]	CO2, CO5	BL2, BL3		
Q3 (b)	By using left Consider 'W a. The b. The c. The d. How	right, up, and do ater Jug Problem' problem statemer production rules f starting, goal stat	e own action sequent and describe the f at (problem definit or moving within t e(s) and at least to search) works in t	ces show the one followings- tion as a state sp he search space wo solutions to t this example.	nal State e solution usin pace search). he problem.	g DFS.	[3]	CO2, CO5	BL2, BL3, BL4		

Q4 (a)	In general, iterative deepening is the preferred uninformed search method when the search space is large, and the depth of the solution is not known-explain?	[2]	CO2	BL2
Q4 (b)	ferentiate Breadth First Search and Iterative deepening depth-first search with the lp of algorithms and evaluate time complexity (TC) and space complexity (SC) . Both the ses time complexities are same, but space complexities are different, if b=10 and d=5, d out the numbers of nodes, TC and SC. (consider, 1 million nodes can be generated per send that a node requires 1000 bytes of storage.)		CO2	BL4, BL5, BL6
Q5	Define the terms NLP, NLU and NLG. Explain briefly - Morphology analysis, syntactic processing, Semantic analysis, and Pragmatic analysis of NLP.	[5]	CO4	BL1, BL2

:::::: 30/09/2022 :::::M