BIRLA INSTITUTE OF TECHNOLOGY, MESRA, RANCHI (END SEMESTER EXAMINATION)

CLASS:	ME	SEMESTER : III
BRANCH	H: EEE	SESSION : MO/19
TIME:	SUBJECT: EE601 PROCESS MEASUREMENT AND 3 HOURS	CONTROL FULL MARKS: 50
INSTRUE 1. The e 2. Atter 3. The e 4. Befor 5. Table	CTIONS: question paper contains 5 questions each of 10 marks and total 50 mpt all questions. missing data, if any, may be assumed suitably. ore attempting the question paper, be sure that you have got the co es/Data hand book/Graph paper etc. to be supplied to the candidat	marks. orrect question paper. tes in the examination hall.
Q.1(a)	Explain the objective of the process control system.	[5]
Q.1(b)	With an example explain the self-regulation and servomechanism in	control system. [5]

- A temperature sensor has a transfer function of 5 mV/ $^{\circ}$ C with an accuracy of ±1%. Find the possible Q.2(a) [5] range of transfer function when reading of 27.5 mV result from sensor. [5]
- Q.2(b)



Find the transfer function for the coupled tank.

- Q.3(a) Find the system accuracy of the flow process if transducer transfer function is $(10 \text{ mV/m}^3/\text{s}) \pm 1.5\%$ and [5] signal conditioning system transfer function is 2mA/mV±.05%.
- With proper example explain the Feedforward controller and its advantages. Q.3(b)
- Q.4(a) A sensor resistance change linearly from 100 Ω to 180 Ω for temperature change to 20°C to 120°C. find [5] the equation for R(sensor resistance).
- Q.4(b) What is ratio controller, how it works?
- Q.5(a) The open loop transfer function of unity negative feedback system is given by $G(s) = \frac{K(s+2)}{(S+1)(S-7)}$ for [5] k > 6 the stability criteria of the open loop configuration and the close loop configuration of the system find the stability. [5]
- Q.5(b) Explain the adoptive controller.

:::::25/11/2019:::::M

[5]

[5]