

BIRLA INSTITUTE OF TECHNOLOGY MESRA RANCHI, INDIA

CHOICE BASED CURRICULUM

Postgraduate Programme

M. Tech. in Instrumentation

Effective from academic year 2021 – 2022 onwards

Institute Vision

To become a Globally Recognized Academic Institution in consonance with the social, economic and ecological environment, striving continuously for excellence in education, research and technological service to the National needs.

Institute Mission

- 1. To educate students at Undergraduate, Post Graduate Doctoral and Post-Doctoral levels to perform challenging engineering and managerial jobs in industry.
- 2. To provide excellent research and development facilities to take up Ph.D. programmes and research projects.
- 3. To develop effective teaching and learning skills and state of art research potential of the faculty.
- 4. To build national capabilities in technology, education and research in emerging areas.
- 5. To provide excellent technological services to satisfy the requirements of the industry and overall academic needs of society.

Department Vision

Become a centre of excellence in teaching and research for creating technical manpower to meet the technological need of the country in the field of Electronics and Communications Engineering. Department exposes the undergraduate students to all fundamental and advanced technology in the field of Electronics and Communication.

Department Mission

- 1. To facilitate state of the art Education and Research at Undergraduate, Post Graduate and Doctoral levels to enable to perform challenging engineering and managerial jobs in the field of Electronics and Communication Engineering.
- 2. To build national capabilities in Technology, Education and Research in emerging areas in the field of Electronics and Communication Engineering.
- 3. To create an environment to provide excellent Research and Development facilities to strengthen Ph.D. programmes and Research Projects.
- 4. To provide excellent Technological Services to bridge the gap between Academics and Industry in order to fulfil the overall academic needs of the society.
- 5. To provide high quality Course Structure in order to turn out qualified professionals to meet the engineering needs of the country.
- 6. To develop effective Teaching Skills and the Research Potentials of the faculty members.
- 7. To ensure All Round Development of the students and to create a platform for turning out engineering professionals who can assume leadership position in society.

Graduate Attributes

(The Graduate Attributes are the knowledge skills and attitudes which the students have at the time of graduation. These attributes are generic and are common to all PG engineering programs. These Graduate Attributes are identified by National Board of Accreditation.)

I. **Scholarship of Knowledge**: Acquire in-depth knowledge of specific discipline or Professional area, including wider and global perspective, with an ability to discriminate, evaluate, analyze and synthesize existing and new knowledge, and integration of the same for enhancement of knowledge.

- II. **Critical Thinking**: Analyze complex engineering problems critically, apply independent judgment for synthesizing information to make intellectual and/or creative advances for conducting research in a wider theoretical, practical and policy context.
- III. **Problem Solving**: Think laterally and originally, conceptualize and solve engineering problems, evaluate a wide range of potential solutions for those problems and arrive at feasible, optimal solutions after considering public health and safety, cultural, societal and environmental factors in the core areas of expertise.
- IV. Research Skill: Extract information pertinent to unfamiliar problems through literature survey and experiments, apply appropriate research methodologies, techniques and tools, design, conduct experiments, analyze and interpret data, demonstrate higher order skill and view things in a broader perspective, contribute individually/in group(s) to the development of scientific/technological knowledge in one or more domains of engineering.
- V. **Usage of modern tools**: Create, select, learn and apply appropriate techniques, resources, and modern engineering and IT tools, including prediction and modelling, to complex engineering activities with an understanding of the limitations.
- VI. **Collaborative and Multidisciplinary work**: Possess knowledge and understanding of group dynamics, recognize opportunities and contribute positively to collaborative multidisciplinary scientific research, demonstrate a capacity for self-management and teamwork, decision-making based on open-mindedness, objectivity and rational analysis in order to achieve common goals and further the learning of themselves as well as others.
- VII. **Project Management and Finance**: Demonstrate knowledge and understanding of engineering and management principles and apply the same to one's own work, as a member and leader in a team, manage projects efficiently in respective disciplines and multidisciplinary environments after consideration of economical and financial factors.
- VIII. **Communication**: Communicate with the engineering community, and with society at large, regarding complex engineering activities confidently and effectively, such as, being able to comprehend and write effective reports and design documentation by adhering to appropriate standards, make effective presentations, and give and receive clear instructions.
- IX. Life-long Learning: Recognize the need for, and have the preparation and ability to engage in life-long learning independently, with a high level of enthusiasm and commitment to improve knowledge and competence continuously.
- X. **Ethical Practices and Social Responsibility**: Acquire professional and intellectual integrity, professional code of conduct, ethics of research and scholarship, consideration of the impact of research outcomes on professional practices and an understanding of responsibility to contribute to the community for sustainable development of society.
- XI. **Independent and Reflective Learning**: Observe and examine critically the outcomes of one's actions and make corrective measures subsequently, and learn from mistakes without depending on external feedback.

PEO1	To enable students to acquire in-depth knowledge in the field of Instrumentation with an					
	ability to integrate existing and new knowledge with the advancement of the technology.					
PEO2	To develop students to critically analyze the problems in the field of Instrumentation and					
	find optimal solution.					

PEO (Programme Educational Objectives)

PEO3	To train students to conduct research and experiments by applying appropriate techniques
	and modern tools for sustainable development of society with an understanding of the
	limitations.
PEO4	To prepare students to act as a member and leader of the team to contribute positively to
	manage projects efficiently in the field of Instrumentation and other multidisciplinary area.
PEO5	To train students to effectively communicate, write reports, create documentation and make
	presentations by adhering to appropriate standards.
PEO6	To stimulate students for life-long learning with enthusiasm and commitment to improve
	knowledge and competence continuously.

PO (Programme Outcomes)

After completion of the programme, students will be able to

PO1	Acquire in-depth knowledge in Instrumentation with an ability to evaluate existing technology			
	and integrate new technology for enhancement of knowledge.			
PO2	Analyze complex problems in the field of Instrumentation critically and conduct research.			
PO3	Conceptualize Industrial problems in the specific domain and find optimal solutions,			
	considering public health, safety, societal and environmental factors.			
PO4	To contribute to the development of scientific/technological knowledge by solving unfamiliar			
	problems through appropriate research methodologies in field of Instrumentation.			
PO5	Use virtual instruments tools for product development with an understanding of the			
	limitations/constraints.			
PO6	Demonstrate understanding as a team member and contribute positively to collaborative multi-			
	disciplinary scientific research to achieve common goals.			
PO7	Demonstrate knowledge and understanding of engineering and management principles and			
	apply the same as a member and leader in a team to manage projects efficiently in			
	Instrumentation and other multidisciplinary area in terms of cost and finance.			
PO8	Effectively communicate, write reports, create documentation and make presentations by			
	adhering to appropriate standards to the engineering community and society.			
PO9	Engage in life-long learning independently with enthusiasm and commitment to improve			
	knowledge and competence continuously.			
PO10	Demonstrate professional and intellectual integrity, professional code of conduct, and ethics			
	of research with an understanding of responsibility to contribute in the field of Instrumentation			
	for sustainable development of society.			
PO11	Observe and critically examine the outcomes of own actions, learn from own mistakes and			
	make corrective measures without depending on external feedback.			

BIRLA INSTITUTE OF TECHNOLOGY- MESRA, RANCHI NEWCOURSE STRUCTURE-To be effective from academic session 2021- 22 Based on CBCS & OBE model

Recommended scheme of study for M. Tech. in Instrumentation and Control

SEMESTER / Session of Study	Course	Category	Course Code	Courses		ode of delivery & other ture; T-Tutorial; P		Total Credits C- Credits		
(Recommended)		of course			L (Periods/week	T (Periods/week)	P (Periods/week)	С		
			EC581	Applied Industrial Instrumentation	3	0	0	3		
		Programme Core (PC)	EC520	Advanced sensing technique	3	0	0	3		
		(10)	EC522	Advanced digital signal processing	3	0	0	3		
FIRST / Monsoon	FIFTH		EC575	Artificial Intelligence System	3	0	0	3		
wonsoon	FIF I II	Programme Elective		PE-I	3	0	0	3		
				LABORAT	ORIES					
		Programme Core	EC582	Instrumentation Lab-I	0	0	4	2		
		(PC)	EC523	Advanced DSP lab	0	0	4	2		
				TOTAL				19		
			-							
		Programme Core (PC)	EC568	Process Control	3	0	0	3		
		(10)	EC570	Embedded System Design	3	0	0	3		
	FIFTH/ SIXTH		EC572	Optoelectronic Instrumentation	3	0	0	3		
SECOND / Spring		Programme Elective (PE)		PE-II	3	0	0	3		
			Programme Elective (PE)		PE-III	3	0	0	3	
			Programme Core			LABORAT	ORIES			
				EC571	Embedded System Lab.	0	0	4	2	
				EC583	Instrumentation Lab-II	0	0	4	2	
								19		
				TOTAL FOR FIFTH LEVEL				38		
		Programme Core	EC600	Thesis (Part I)				8		
THIRD /	SIXTH	Open Elective		OE I / MOOC	3	0	0	3		
Monsoon	Sintin	SIXIII			OE II / MOOC	3	0	0	3	
				TOTAL				14		
FOURTH /	SIXTH	Programme Core (PC)	EC650	Thesis (Part II)	0	0	16	16		
Spring		TOTAL					16			
				TOTAL FOR SIXTH LEVEL				30		
			GRAND	TOTAL FOR M.TECH PROGRAMME (38	+ 30)			68		

PROGRAMME ELECTIVE (PE-I) 1st Semester

Course Type	Course Code	Course Title	Pre requisites / Co requisites	Credits
PE	EC524	Measurements and Statistics	EC313 Electronics Measurement	3
PE	EC525	High Frequency Measurements	EC257 Electromagnetic field and Waves	3
PE	EE515	Control System Design	EC313 Electronic Measurement, EE 305 Control Theory	3
PE	EC526	Digital Image Processing Technique	EC305 Signal Processing Techniques, EC251 probability and Random Process	3
PE	EC527	Speech Processing and Recognition	EC305 Signal Processing Techniques	3
PE	EC528	CMOS Digital VLSI Design	EC101 BECE	3

PROGRAMME ELECTIVE (PE-II) (offered in SP session): 2nd Semester

Course Type	Course Code	Course Title	Pre requisites / Co requisites	Credits
PE	EC574	Pattern recognition and Machine Learning	EC305 Signal Processing Techniques	3
PE	EC558	Modern Optimization Techniques	EC251 Probability and Random Process	3
PE	EC576	Micro-Electro Mechanical System	EC377 Sensor and Transducer	3
PE	EC577	Photonic Integrated Circuit	EC 201 Electronics Devices, EC 257 Electromagnetic Fields and Waves	3
PE	EC578	CMOS Analog VLSI Design	EC209 Analog Circuits (AC)	3

PROGRAMME ELECTIVE (PE-III) (offered in MO session): 3rd Semester

Course Type	Course Code	Course Title	Pre requisites / Co requisites	Credits
PE	EC610	Biomedical Signal Processing	EC522 Advanced Digital Signal Processing	3
PE	EC611	Virtual Instrumentation	Fundamental of Data Structure	3
PE	EC612	Instrumentation System Design	EC518 Advanced Instrumentation System (AIS)	3
PE	EC614	Adaptive system and Signal Processing	EC 305 Signal Processing Techniques	3

Name of the Subject: Applied Industrial Instrumentation Course Code: EC581 Course Title: Applied Instrumentation System Pre-requisite(s): EC313 Electronics Measurement Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students to:

А.	Explain the concept of intelligent instrumentation and impart knowledge on automation.
B.	Develop an ability to model and analyze a real time system.
C.	Develop an ability to evaluate the performance of a Automation system.
D.	Develop an ability to design an intelligent system for industrial automation.

Course Outcomes:

After the completion of this course, students will be:

CO1	Demonstrate on the understanding of automation and functioning of various elements in a			
	real time system.			
CO2	Have an ability to identify and analyze various components of an automation system.			
CO3	Have an ability to evaluate the performance of PLC.			
CO4	Have an ability to develop a virtual instrumentation system.			

SYLLABUS

Module -1:

Introduction about Instrumentation system. Types of Instrumentation system. Industrial Instrumentation diagrams. Standards in industrial instrumentation. Data acquisition system and its uses in intelligent Instrumentation system. Detail study of each block involved in making of DAS, Signal conditioners as DA, IA, signal converters (ADC), Sample and hold. Designing application for Pressure, Temperature measurement system using DAS.

Module -2:

Data logger, DOS Computer Supervisory Control System, Direct Digital Control's Structure and Software. SCADA- Remote terminal units, Master station, Communication architectures and Open SCADA protocols. DCS- Evolution of Different architecture, Local unit, Operator Interface, Displays, Engineering interface, factors to be considered in selecting DCS, case studies in DCS.

Module -3:

Actuators: Pneumatic cylinder, Relay, solenoid (Final Control Element), Converter (I to P). PLC: PLC architecture, PLC operation, Addressing modes of PLC, Languages used in PLC Programming, Instructions used in Ladder programming, Programming examples of different processes.

Module -4:

Virtual Instrumentation- Introduction to LabVIEW, Block diagram and architecture of a virtual instrumentation, Graphical programming in data flow, comparison with conventional programming, Vis and sub-Vis, loops and charts, arrays, clusters and graph, case and sequence structures, formula nodes, local and global variables, string and file I/O. hydraulic, pneumatic and electrical circuits using automation studio.

Module -5:

Introduction about Intelligent controllers, Model based controllers, Predictive control, Artificial Intelligent Based Systems, Experts Controller, Fuzzy Logic System and Controller, Artificial Neural Networks, Neuro-Fuzzy Control system. Case study. Introduction to telemetry, Instrument interfacing, Current loop, RS232/485, Field bus, Modbus, GPIB, USB Protocol, HART communication Protocol- Communication modes and networks.

Text Books:

- 1. Computer Based Industrial Control By Krishna Kant, PHI
- 2. Process Control Instrumentation By Curtis D. Johnson, Pearson Education

Reference Books:

- 1. "Principle of Industrial Instrumentation" By D. Patranabis, TMH publications
- 2. National Instruments LabVIEW manual.
- 3. High performance Instrumentation and Automation, CRC Press, Taylor & Francis Group, 2005.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components CO1 CO2	CO3	CO4
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Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

		Program Outcomes									
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	2	3		3	1	3	3	3	3
CO2	3	3	2	3		3	1	3	3	3	3
CO3	2	2	3	3	1	3	1	2	3	3	3
CO4	3	3	2	3	2	3	1	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Mapp	Mapping Between COs and Course Delivery (CD) methods							
CD	Course Delivery methods	Course Outcome	Course Delivery Method					
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4, CO5	CD1					
CD2	Quizzes	CO1, CO2, CO3, CO4	CD2					
CD3	Assignments/Seminars	CO5	CD3					
CD4	Mini projects/Projects							
CD5	Laboratory experiments/teaching aids							
CD6	Industrial/guest lectures							
CD7	Industrial visits/in-plant training							
CD8	Self- learning such as use of NPTEL materials and internets							
CD9	Simulation							

Lecture Wise Lesson Planning Details:

Week	Lect.	Tentative	Ch.	Topics to be covered	Text	COs	Actual	Methodology	Remar
No.	No.	Date	No.	_	Book /	mappe	Content	used	ks by
					Refere	d	covered		faculty
					nces				if any
1	L1			Illustration of course	T1	1		PPT Digi	
				objectives and course				Class/Chock	
				outcomes, besides				-Board	
				detailed introduction					
				of the course syllabus.					
	L2			Review of transducer,	T1	1		do	

-	1.0		• • •				
	L3	Introduct					
		Instrume	ntation				
		system.					
	L4	Types	of	T1	1	do	
		Instrume	ntation				
		system.					
2	L5	Data	acquisition				
			nd its uses in				
		intelliger	ıt				
		Instrume	ntation				
		system.					
	L6	Detail st	udy of each				
		block	nvolved in				
		making o	f DAS,				
	L7		onditioners as				
		DĂ, IA,					
	L8	signal	converters				
			Sample and				
		hold.	•				
3	L9		g application				
		for	Pressure,				
		Tempera					
			nent system				
		using DA					
	L10	Data log					
	L11	Introduct					
		Automat	on system.				
			of Control				
		Schemes					
	L12		Controllers.				
4	L13	DAS, DO					
	L14	Converte	r (I to P)				
	L15	Actuator	5:				
	L16	cylinders					
5	L17	Relay, so	olenoid (Final				
		Control I					
	L18		r Supervisory				
		Control S					
	L19	Direct	Digital				
		Control's					
		and Soft					
	L20	SCADA	Remote				
		terminal	units, Master				
		station,					
		Commun	ication				
		architect	and and				
		Open	SCADA				
		protocols				 	
6	L21		Evolution of				
			architecture,				
			nit, Operator				
		Interface					
		Engineer	ing interface,				
	L22	factors	to be				
			ed in selecting				
			se studies in				
		DCS					
	L23		itecture, ,				
				•	•		-

	L24	PLC operation		
7	L25	Addressing modes of	f	
		PLC,		
	L26	Languages used in	1	
		PLC Programming,		
	L27	Instructions used in		
		Ladder programming,		
	L28	Programming		
8	L29	examples of different	t	
	L30	processes.		
	L31	Virtual		
		Instrumentation-		
		Introduction to		
		LabVIEW, Block diagram and		
		architecture of a		
		virtual		
		instrumentation,		
	L32	Graphical		
		programming in data	ı	
		flow, comparison with		
		conventional		
		programming,		
9	L33	, Vis and sub-Vis,	,	
	X Q (loops and charts,		
	L34	arrays, clusters and		
	L35	graph,		
	L33	case and sequence structures, formula		
		nodes,		
	L36	local and global		
	200	variables,		
10	L37	string and file I/O.		
	L38			
	L39	Programming		
	L40	Examples		
11	L41	Introduction about		
		Intelligent controllers,		
		Model based		
		controllers, Predictive		
	L42	control, Artificial Intelligent	+	
	L42	Based Systems,		
		Experts Controller,		
	L43	Fuzzy Logic System		
		and Controller,		
	L44	Artificial Neural		
		Networks, Neuro-		
		Fuzzy Control system.		
12	L45	Case study.		
	L46	Introduction to		
		telemetry, Instrument		
		interfacing, Current		
	L47	loop, RS232/485,		
	L47 L48	Field bus, Modbus, GPIB,		
L	L40	UID,		

13	L49	USB Pr commu Protoco				
	L50		nication nd networks.			

Name of the Subject: Advanced Sensing Techniques Course Code: EC520 Course Title: Advanced Sensing Techniques Pre-requisite(s): EC377 Sensor and Transducer Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students to:

A.	Describe the operation of various smart sensors and their application			
B.	Select an appropriate sensor for a given application			
C.	Compare analogue and digital transducer.			
D.	Discuss the latest technology in sensor development			

Course Outcomes:

After the completion of this course, students will be:

CO1	Understand the principle of operation of different sensors and their applications
CO2	Be updated on the recent trends in sensor technologies.
CO3	Design a wireless sensor network
CO4	Solve design and modelling issue using complex engineering mathematics

SYLLABUS

Module -1: Introduction

Introduction to smart sensors, Principles of operation, design approach, interface design, configuration supports,

Module -2 : Electroanalytical Sensors

Introduction, Electro-chemical Cell, Cell potential, Sd. Hydrogen Electrode (SHE), Liquid Junction and Other potentials, Polarization, Reference Electrodes, Sensor Electrodes, Electro-Ceramics in Gas Media. Analyzers for different gas and laboratory testing of chemicals

Module -3: sensor technologies:

MEMS sensor, Comparison between MEMS and Macro sensor, Fabrication and packaging issue in sensor design Thick film and thin film technique Physical sensors. Bio sensor, Silicon sensor, RF Sensor, sensors for robotics

Module 4: Wireless Sensing Techniques:

Wireless Sensor, principle and working, wireless sensing network, protocols used, Application of wireless sensor for weather monitoring.

Module-5:

Design and modelling issue in advanced sensing technique. Introduction of different mathematical tools used in sensor design. Optimization techniques used in sensor design. The role of PCA, LDA, Neural network in designing sensor array

Text Books:

- 1. Sensors and Transducers, by D. Patranabis. 2nd Edition
- 2. Electrical & Electronics Measurements and Instrumentation by A.K Sawhney, Dhanpat Rai & Sons.
- 3. Transducers and Instrumentation, by Murthy D. V. S., Prentice Hall, 2nd Edition, 2011.

Reference Books:

1. Sensor and signal conditioning by John G. Webster, Wiley Inter Science, 2nd edition, 2008

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1

End Sem Examination Marks	3	3	3	3
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Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

		Program Outcomes									
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	2	3		3	1	3	3	3	3
CO2	3	3	2	3		3	1	3	3	3	3
CO3	2	2	3	3	1	3	1	2	3	3	3
CO4	3	3	2	3	2	3	1	3	3	3	3

Note: 1 for fulfilling less than 40%, **2** for fulfilling less than 70% and **3** for fulfilling above 70%

Map	Mapping Between COs and Course Delivery (CD) methods				
CD	Course Delivery methods	Course Outcome	Course Delivery Method		
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4, CO5	CD1		
CD2	Quizzes	CO1, CO2, CO3, CO4	CD2		
CD3	Assignments/Seminars	CO5	CD3		
CD4	Mini projects/Projects				
CD5	Laboratory experiments/teaching aids				
CD6	Industrial/guest lectures				
CD7	Industrial visits/in-plant training				
CD8	Self- learning such as use of NPTEL materials and internets				
CD9	Simulation				

Lecture Wise Lesson Planning Details:

Week	Lec	Tentativ	Ch.	Topics to be covered	Text	COs	Actual	Methodol	Remarks
No.	No.	e	No.		Book /	mapped	Content	ogy	by
		Date			Refere		covered	used	faculty if
					nces				any
1	L1			Illustration of course	T1	1		PPT Digi	
				objectives and course				Class/Cho	
				outcomes, besides				ck	
				detailed introduction of				-Board	
				the course syllabus.					
	L2			Introduction to smart	T1	1		do	
				sensors					

L3	Principles of operation and their classification	T1	1	do
L4	design approach	T1	1	do
L5		T1	1	do
				do
				do
L7	chemical Cell		1	uo
L8	Cell potential	T1	1	do
L9	Sd. Hydrogen		1	do
L10	Saturated Calomel	T2	2	do
T 11		T 2		1
LII	Other potentials,	12	2	do
L12		Т2	2	do
	Electro-Ceramics in	12	2	
L13		Т2	2	do
	2		-	
L14		Т2	2	do
L15		Т2	C	do
				do
LIU	MEMS and Macro	12	2	
I 17		Т2	2	do
	packaging issue in sensor design	12	2	
L18	Thick film and thin film technique Physical sensors	T2	2	do
I 10		т2	1.2	do
			1,2	do
L21	and application	12	1,2	do
L22	RF Sensor principle	T2	1,2	do
L23	**	T2	1,2	do
	in robotics			
L24	Wireless Sensor,	T2	3	do
1.25		тэ	3	do
L25		12	3	do
1.26		Т2	3	do
L20	network	12	5	do
L27	protocols used in WSN	T2	3	do
L28	Application of wireless sensor for weather monitoring	T2	3	do
L29		T2	4	do
	advanced sensing technique			
L30	Modeling issue in advanced sensing	T2	4	do
	L5 L6 L7 L8 L9 L10 L11 L12 L13 L14 L15 L16 L17 L12 L13 L14 L15 L16 L17 L18 L19 L20 L21 L22 L23 L24 L25 L26 L27 L28 L29	L4and their classificationL4design approachL5interface designL6configuration supports,L7Introduction, Electro- chemical CellL8Cell potentialL9Sd.Hydrogen Electrode (SHE),L10SaturatedL11Liquid Junction and Other potentials, PolarizationL12Sensor Electrodes, Electro-Ceramics in Gas MediaL13Analysers for different gasL14Iaboratory testing of chemicalsL15MEMS sensorL16Comparison between MEMS and Macro sensorL17Fabrication and packaging issue in sensorsL18Thick film and thin film technique Physical sensorsL19Bio sensor typeL20Bio sensor principle and applicationL21Silicon sensor principle and applicationL22RF Sensor principle and applicationL24WirelessVirelessSensorL24WirelessL25WirelessL26wirelessL27protocols used in WSNL29Design issue in advanced sensing techniqueL29Design issue in advanced sensing techniqueL30Modeling issue in	Image: Laboration of the set	L4and their classificationL4design approachT1L5interface designT1L6configuration supports,T1L7Introduction, Electro- chemical CellT1L8Cell potentialT1L9Sd.HydrogenL10SaturatedCalomelElectrode (SHE),T2L11Liquid Junction and Other potentials, PolarizationT2L12Sensor Electrodes, Electro-Ceramics in Gas MediaT2L13Analysers for different gasT2L14Iaboratory testing of chemicalsT2L15MEMS and Macro sensorT2L16Comparison between packaging issue in sensor designT2L17Fabrication and macro sensorT2L18Thick film and thin film technique Physical sensorsT2L19Bio sensor typeT2L20Silicon sensor principle and applicationT2L21Silicon sensor principle and applicationT2L22RF Sensor principle and applicationT2L24Wireless workingT2L25Wireless workingT2L26wireless workingT2L27protocol used in WSN robustesT2L28Application of weather monitoringT2L29Design issue in advanced sensing techniqueT2L30Modeling issue in advanced sensingT2L30Modeling

11	L31	Introduction of different mathematical tools used in sensor design		4	do
	L32	Introduction of different mathematical tools used in sensor design		4	do
	L33	Optimization techniques used in sensor design	T2	4	do
12	L34	Optimization techniques used in sensor design	T2	4	do
	L35	The role of PCA in sensor design	The role of PCA in T2 sensor design		do
	L36	The role of LDA in sensor design	T2	4	do
13	L37	Neural network in designing sensor array	T3	4	do
	L38	Neural network in designing sensor array	T3	4	do
	L39	Case study	T3	4	do
14s	L40	Case study	T3	4	do

Name of the Subject: Advanced Digital Signal Processing Course Code: EC522 Course Title: Advanced Digital Signal Processing Pre-requisite(s): EC305 Signal Processing Techniques Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students to:

1	Understand the concept of signals and systems and filters.
2	Impart knowledge on various transformation techniques.
3	Impart knowledge on multirate signal processing and its applications.
4	Understanding on optimum linear filters and power spectral estimation.

Course Outcomes

On the completion of this course, the students will be able to:

CO1	Develop an understanding to concept of signals and systems and to design filters.					
CO2	Have an ability to analyze and apply various single and multi-domain transformation					
	techniques.					

CO3	Have an ability to apply multirate signal processing on various engineering applications.
CO4	Develop an ability to apply use optimum linear filters and power spectral estimation.

SYLLABUS

Module 1: Review of Signals and Systems, Sampling and data reconstruction processes, Z transforms. Chirp Z Algorithm, Goertzel's Algorithm, Discrete linear systems, Digital filter design and structures: Basic FIR/IIR filter design & structures, design techniques of linear phase FIR filters, IIR filters by impulse invariance, bilinear transformation, FIR/IIR Cascaded lattice structures.

Module 2: DSP Transforms: Fourier transform, Discrete sine and cosine transform, Discrete Hartely transform, short time Fourier transform, wavelet transform, Hilbert transform, Hilbert-Huang transform, Stockwell transform

Module 3: Multi rate DSP, Decimators and Interpolators, Sampling rate conversion, multistage decimator & interpolator, poly phase filters, QMF, digital filter banks, Multi resolution signal analysis, wavelet decomposition, Applications in subband coding.

Module 4: Linear prediction and Optimum Linear Filters: Random signals and power spectra, Forward and backward Linear prediction, solutions of the normal equations, AR lattice and ARMA lattice-ladder filters, Wiener filters.

Module 5: Power spectrum estimation: Estimation of Spectra from Finite-Duration Observations of Signals. Nonparametric Methods for Power Spectrum Estimation, Parametric Methods for Power Spectrum Estimation, Minimum-Variance Spectral Estimation, Eigenanalysis Algorithms for Spectrum Estimation

Text Books:

- 1. J.G.Proakis and D.G.Manolakis"Digital signal processing: Principles, Algorithm and Applications", 4th Edition, Prentice Hall, 2007.
- 2. N. J. Fliege, "Multirate Digital Signal Processing: Multirate Systems -Filter Banks Wavelets", 1st Edition, John Wiley and Sons Ltd, 1999.
- 3. D. G. Manolokis, V. K. Ingle and S. M. Kogar, "Statistical and Adaptive Signal Processing", Mc Graw Hill International Edition, 2000.
- 4. S. Haykin and T. Kailath, Adaptive Filter Theory, Pearson Education, 4th Edition, 2005.

Reference Books:

- 1. Digital Signal Processing 3/E by S.K.Mitra TMH Edition.
- 2. Fundamentals of adaptive filtering, A. H. Sayed, Wiley, 2003.
- 3. Monson H. Hayes, Statistical Digital Signal Processing and Modelling, Wiley, 2002

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids

CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

		Program Outcomes									
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	2	2	1	1		1	1	1	1	1	1
CO2	3	2	1	2		1	2	2	1	1	1
CO3	3	3	2	2		1	2	2	2	1	1
CO4	3	3	2	2	1	2	2	2	2	2	2

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70%

Map	Mapping Between COs and Course Delivery (CD) methods								
CD	Course Delivery methods	Course Outcome	Course Delivery Method						
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4, CO5	CD1						
CD2	Quizzes	CO1, CO2, CO3, CO4	CD2						
CD3	Assignments/Seminars	CO5	CD3						
CD4	Mini projects/Projects								
CD5	Laboratory experiments/teaching aids								
CD6	Industrial/guest lectures								
CD7	Industrial visits/in-plant training								

		Self- learning such as use of NPTEL materials and	
CI	28	internets	
CI	D 9	Simulation	

Lecture Wise Lesson Plan Details

We	Lec	Tentative	Mo	Topics to be covered	Text	COs	Actual	Methodol	Remark
ek	t.	Date	dul	•	Book /	mapp	Content	ogy	s by
No.	No.		e		Refere	ed	covered	used	faculty
			No		nces				if any
1	1		1	Introduction to the course	1	CO1		PPT and	
				Review of Signals and				Chock-	
			-	Systems		~~ (Board	
	2			Sampling theorem	1	CO1		Do	
	3			Z-transform, Chirp Z-	1	CO1		Do	
2	4		-	transform Goertzel's Algorithm	1	CO1		Do	
2	5			linear phase FIR filters	1	C01		Do	
	6		-	IIR filters by impulse	1	C01		Do	
	0			invariance, bilinear	1	COI		D0	
				transformation					
3	7			FIR/IIR Cascaded lattice	1	CO1		Do	
				structures.					
	8		2	Fourier transform, Discrete	2	CO1,		Do	
			-	sine and cosine transform		CO2			
	9		_	Discrete Hartely transform	2	CO1,		Do	
4	10			short time Fourier transform	2	CO1,		Do	
	11				2	CO2		D	
	11			wavelet transform	2	CO1, CO2		Do	
	12 Continuous wavelet transf		Continuous wavelet transform	2	CO2		Do		
	12			Continuous wavelet transform	2	CO1, CO2		D0	
5	13		-	Discrete wavelet transform	2	CO1,		Do	
_						CO2			
	14			Hilbert huang transform	2	CO1,		Do	
						CO2			
	15			Stockwell transform	2	CO1,		Do	
			-		_	CO2		_	
6	16			Stockwell transform	2	CO1,		Do	
	17		3	Multi voto DCD Desimestore	1	CO2		De	
	17		3	Multi rate DSP, Decimators and Interpolators	1	CO3		Do	
	18		-	Sampling rate conversion	1	CO3		Do	
7	10		1	multistage decimator	1	CO3		Do	
				&interpolator					
	20		1	multistage decimator	1	CO3		Do	
				&interpolator					
	21			poly phase filters	1	CO3		Do	
8	22			Quadrature Mirror Filter	1	CO3		Do	
	23		-	digital filter banks	1	CO3		Do	
	24			Multi resolution signal	1	CO3		Do	
9	25		-	analysis	1	CO3		Do	
9	25 26		1	wavelet analysis wavelet decomposition	1	CO3		Do Do	
	20		-	sub band coding	1	CO3		D0	
10	27		1	Applications in subband	1	CO3		Do	
10	20			coding	1	205			
L			I		I	I	I	1	1

	29	4	Random signals and power spectra	1	CO4	Do
	30		Forward and backward Linear prediction	1	CO4	Do
11	31		Forward and backward Linear prediction	1,2	CO4	Do
	32		solutions of the normal equations	1,2	CO4	Do
	33		AR lattice filter	1,2	CO4	Do
12	34		ARMA lattice-ladder filters,	1,2	CO4	Do
	35		Wiener filters.	1,2	CO4	Do
	36		Wiener filters.	1,2	CO4	Do
13	37	5	Power spectrum estimation	1,R1	CO4	Do
	38		Estimation of Spectra from Finite-Duration Observations of Signals.	1	CO4	Do
	39		NonparametricMethodsforPowerSpectrumEstimation	1,R1	CO4	Do
14	40		Parametric Methods for Power Spectrum Estimation	1,R1	CO4	Do
	41		Minimum-Variance Spectral Estimation	1,R1	CO4	Do
	42		Eigenanalysis Algorithms for Spectrum Estimation	1, R1	CO4	Do

Name of the Subject: Artificial Intelligent System

Course Code: EC575

Course Title: Artificial Intelligent System

Pre-requisite(s): Fundamental of Data Structure, EC203 Digital System Design,EC 305 Signal Processing Techniques, EC 255 Analog Communication, EC570 Embedded System Design **Co-requisite(s):**

Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students to:

А.	Define the fundamental concepts of artificial intelligence
B.	Analyze the different search algorithms
C.	Show the application of intelligent system and its functionality
D.	Recognize the constraints and suitable algorithms for artificial intelligent systems

After the completion of this course, students will be able to:

1.	Recognize the fundamental concepts of artificial intelligence
2.	Design the different search algorithms
3.	Analyze the constraint of intelligent system for solving the complex problems
4.	Outline the suitable algorithms for artificial intelligent system & its functionality

SYLLABUS

Module -1:

Introduction to Artificial Intelligence:

Definition of AI, Turing test, brief history of AI, Problem solving and search, Uninformed search, informed search, Local search, local search in continuous spaces.

Module -2: Optimization

Optimal problem formulation, Design variables constraints, Objective function. Gradient-based methods: Newton-Raphson method, Cauchy's steepest descent and Newton's method. Genetic algorithm and its working principle, GA variants, Particle swarm optimization

Module -3: Learning Models

Introduction to machine learning, Artificial neural network, radial basis functional neural network, functional link ANN, concept of deep learning, Convolutional neural network, reinforcement learning

Module -4:

Adaptive learning:

Adaptive systems, least mean square algorithm, Recursive Least Square algorithm, kalman filters and variance. System identification, inverse modelling. Optimal controller design.

Module -5:

Fuzzy logic based system design:

Fuzzy logic, fuzzy rules, membership functions, FIS, Neuro- fuzzy system, Fuzzy logic controller.

Text books:-

- 1. S.J. Russell and P. Norvig. *Artificial Intelligence: A Modern Approach (2nd edition)*, Prentice-Hall, 2010.
- 2. Optimization for Engineering Design Kalyanmoy Deb, 2006, PHI
- 3. "Neuro-Fuzzy and Soft Computing"- J.S.R. Jang, C. T. Sun and E. Mizutani, PHI, NewDelhi

Reference books:-

- **1.** ArtificialIntelligence-Definition- Wikibooks, open books for an open; https://en.wikibooks.org/wiki/Artificial Intelligence/Definition
- 2. Patterson, Dan W. Introduction to Artificial Intelligence and Expert Systems(Pearson Education)

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	2	2	2	3	2	2	2	2	2	3	3
	3	3	3	3	2	3	3	3	2	3	3
CO2	2	3	3	2	2	3	3	3	3	3	3
CO3	3	2	3	3	2	3	3	3	2	3	3
CO4	3	3	3	3	2	3	3	3	3	3	3

Mapping Between COs and Course Delivery (CD) methods								
CD	CDCourse Delivery methodsCourseCourse DeliveryCDCourse Delivery methodsOutcomeMethod							
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3	CD1					

CD2	Tutorials/Assignments	CO2, CO3	CD1
CD3	Seminars	CO3, CO4	CD1 and CD2
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets	CO4	
CD9	Simulation		

Name of the Subject: Measurements and Statistics Course Code: EC524 Course Title: Measurements and Statistics Pre-requisite(s): EC313 Electronics Measurement Co-requisite(s): Credits: L:3 T:0 P:0 Class schedule per week: 03 Class: M.E. Semester / Level: I Branch: ECE Name of Teacher:

Course Objectives:

This course enables students to

1	Understand basic statistics, and develop proficiency in the application of statistical tools and digital data acquisition and spectral analysis of data
2	Understand basic electronics and circuit analysis for filters, amplifiers, and other signal conditioning circuits and be able to build such circuits
3	Understand how various kinds of analog and digital sensors and instruments work, how they are calibrated – both statically and dynamically, and how they are applied in engineering
4	Advance proficiency in professional communications and interactions

Course Outcomes

On the completion of this course, the students will be able to:

CO1	Apply statistical analysis to data samples to calculate mean, standard deviation, etc. and to
	determine the accuracy, precision, and sensitivity of sensors and instruments and statistical and
	error analyses to measured data to identify and remove outliers and predict uncertainties.
CO2	Apply linear and nonlinear regression analysis to perform curve fits to data and to determine
	correlation of variables and trends and also Create histograms and probability density functions
	(PDFs) of data samples, demonstrate the ability to compare the results to standard PDFs such
	as the Gaussian and student's t PDFs, and demonstrate the ability to predict probabilities based
	on the PDFs
CO3	Apply differential equation analysis of first- and second-order dynamic systems to predict the
	behavior of sensors and instruments
CO4	Predict, analyze, and test the performance of sensors of various kinds, including strain gages,
	thermocouples, tachometers, displacement transducers, dynamometers, pressure gages and
	transducers, laser and Doppler velocimeters, pressure probes, and flowmeters

Syllabus

Module 1: Introduction to mechanical engineering measurements – purpose, dimensions and units, significant digits; Dimensional analysis - primary dimensions, method of repeating variables; Review of basic electronics and circuits; Errors and uncertainties - bias and precision error, accuracy, calibration; Basic statistics – mean, standard deviation, variance, median, mode, etc , Histograms; Probability density functions; The normal (Gaussian) distribution, Central limit theorem; Other PDF distributions - lognormal, student's t, chi-squared; Correlation and regression analysis (least-squares curve fits),

Module 2: Outliers - single variables and data pairs; Experimental uncertainty analysis - RSS uncertainty; Experimental design - full vs. fractional factorial tests, Taguchi design arrays, RSM - Response surface methodology - an efficient way to hunt for an optimum result; Hypothesis testing - how to use statistics to make decisions, Digital data acquisition - introduction to digital data, A/D conversion, discrete sampling, clipping, aliasing; Signal reconstruction - the Cardinal series; Spectral analysis - introduction to Fourier series, harmonic amplitude plots; Fourier transforms - introduction to Fourier transforms, DFTs and FFTs,

Module 3: FFTs (continued) - Windowing - a technique to reduce leakage in FFTs; How to analyze the frequency content of a signal, Filters - first-order low-pass filter, first-order high-pass filter, other filters, Operational amplifiers (Op-Amps) - introduction and some circuits in which op-amps are used; Clipping circuits and examples, common-mode rejection ratio, gain-bandwidth product

Module 4:Stress, strain, and strain gages - review of stress and strain, Hooke's law; Description of strain gages and how to use them; Wheatstone bridge circuits, and how they are used to measure strain, dynamic system response - dynamic measuring systems, zero-, first-, and second-order systems, Temperature measurement - types of temperature measurement including mechanical, thermoresistive, thermojunctive, and radiative methods,

Module 5: Mechanical measurements - mechanical measuring devices, such as potentiometers, linear variable displacement transducers, ultrasonic transducers, capacitance diplacement sensors, accelerometers, tachometers, and dynamometers, Fluid flow measurements - pressure, velocity, and volume flow rate measurements, Fluid flow measurements

Text Books:

1. http://www.mne.psu.edu/cimbala/me345/

Gaps in the syllabus (to meet Industry/Profession requirements): Nil

POs met through Gaps in the Syllabus: N/A

Topics beyond syllabus/Advanced topics/Design:

Current technological developments advanced image processing techniques

POs met through Topics beyond syllabus/Advanced topics/Design:

S. No.	Course Delivery Methods	Used
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors	Yes
CDM 2	Quizzes	Yes
CDM 3	Assignments/Seminars	Yes
CDM 4	Mini projects/Projects	Yes
CDM 5	Laboratory experiments/teaching aids	No
CDM 6	Industrial/guest lectures	Yes
CDM 7	Industrial visits/in-plant training	No

CDM 8	Self- learning such as use of NPTEL materials and internets	Yes
CDM 9	Simulation	No

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment				
Assignment Marks	10				
Quizzes	30				
End Sem Examination Marks	60				

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

		Program Outcomes									
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	2	1	-	2	1	1	1	1	1	2	2
CO2	3	1	-	2	1	1	1	2	1	2	2
CO3	2	2	-	2	1	1	1	1	1	1	1
CO4	2	1	2	2	1	1	1	1	1	1	1

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Lecture Wise Lesson Plan Details

Wee	Lect	Tentativ	Mo	Topics to be covered	Text	COs	Actual	Method	Remar
k		e	dule		Book /	mappe	Content	ology	ks by
No.	No.	Date	No.		Refere	d	covered	used	faculty
					nces				if any
1	1		1	Introduction to mechanical	1	CO1		PPT and	
				engineering measurements –				Chock-	
				purpose, dimensions and units,				Board	
				significant digits					
	2			Dimensional analysis - primary	1	CO1		Do	
				dimensions , method of					
				repeating variables;					

	3		Review of basic electronics and circuits	1	CO1	Do
2	4		Errors and uncertainties - bias and precision error, accuracy, calibration	1	CO1	Do
	5		Basic statistics – mean, standard deviation, variance, median, mode, etc	1	CO1	Do
	6		Histograms; Probability density functions;	1	CO1	Do
3	7	2	The normal (Gaussian) distribution, Central limit theorem	1	CO1	Do
	8		Other PDF distributions - lognormal, student's t, chi- squared	1	CO1	Do
	9		Correlation and regression analysis (least-squares curve fits)	1	CO2	Do
			Outliers - single variables and data pairs; Experimental uncertainty analysis - RSS uncertainty			
4	10		Experimental design - full vs. fractional factorial tests	1	CO2	Do
	11		Taguchi design arrays,	1	CO2	Do
	12		RSM - Response surface methodology - an efficient way to hunt for an optimum result	1	CO2	Do
5	13		Hypothesis testing - how to use statistics to make decisions	1	CO2	Do
	14		Digital data acquisition - introduction to digital data	1	CO2	Do
	15		A/D conversion, discrete sampling	1	CO2	Do
6	16	3	clipping, aliasing, Signal reconstruction - the Cardinal series	1	CO2	Do
	17		Spectral analysis - introduction to Fourier series, harmonic amplitude plots	1	CO3	Do
	18		Fourier transforms - introduction to Fourier transforms, DFTs and FFTs,	1	CO3	Do
7	19		FFTs (continued) - Windowing - a technique to reduce leakage in FFTs	1	CO3	Do
	20		How to analyze the frequency content of a signal	1	CO3	Do
	21		Filters - first-order low-pass filter, first-order high-pass filter, other filters	1	CO3	Do
8	22	4	Operational amplifiers (Op- Amps) - introduction	1	CO3	Do
	23		some circuits in which op-amps are used	1	CO3	Do

	24		Clipping circuits and examples,	1	CO3	Do
9	25		common-mode rejection ratio, gain-bandwidth product	1	CO4	Do
	26		Stress, strain, and strain gages	1	CO4	Do
	27		review of stress and strain	1	CO4	
10	28		Hooke's law; Description of strain gages and how to use them;	1	CO4	Do
	29		Wheatstone bridge circuits	1	CO4	Do
	30		how they are used to measure strain	1	CO4	Do
11	31	5	dynamic system response - dynamic measuring systems	1	CO4	Do
	32		zero-, first-, and second- order systems	1	CO4	Do
	33		Temperature measurement - types of temperature measurement including mechanical	1	CO4	Do
12	34		Thermoresistive, thermojunctive radiative methods	1	CO4	Do
	35		Mechanical measurements - mechanical measuring devices, such as potentiometers	1	CO4	Do
	36		linear variable displacement transducers, ultrasonic transducers	1	CO4	Do
13	37		capacitance displacement sensors	1	CO4	Do
	38		accelerometers, tachometers, and dynamometers,	1	CO4	Do
	39		Fluid flow measurements - pressure, velocity,	1	CO4	Do
	40		Fluid flow measurements volume flow rate measurements		CO4	D0

Name of the Subject: High Frequency Measurement Course Code: EC525 Course Title: High Frequency Measurement Pre-requisite(s): EC257 Electromagnetic field and Waves

Co-requisite(s): Credits: L:3 **T:0 P:0** Class schedule per week: 03 Class: M.E. Semester / Level: I **Branch: ECE** Name of Teacher:

Course Objectives:

This course enables students to

1	Understand various oscilloscope probes, current probes, Probe ground lead effects, wiggly scope patterns, ground loading,
2	Understand probe compensation, compensation and waveform distortion, Differential
	measurements, Magnetic loop and related loop techniques.
3	Study current probes theory and uses for current probes limitations, Magnetic core saturation
4	Study the measurement of pulsed EMI effects on Electronic circuits

Course Outcomes

On the completion of this course, the students will be able to:

CO1	Gain the knowledge of various oscilloscope probes, current probes, Probe ground lead effects,
	wiggly scope patterns, ground loading
CO2	Explain probe compensation, compensation and waveform distortion, Differential
	measurements, Magnetic loop and related loop techniques.
CO3	Gain the knowledge of current probes theory and uses for current probes limitations, Magnetic
	core saturation
CO4	Measure the pulsed EMI effects on Electronic circuits

Syllabus

Module 1:

Oscilloscope probes: types, Passive and Active oscilloscope probes, current probes, current probe specification, current probe electric field response, simple signal generator,

Probe ground lead effects, lead inductance, lead inductance and probe response, probe type with improved response, tell-tale signs of probe resonance, Wiggly scope patterns, Ground lead common impedance induced error, The null experiment, ground loading, use of ferrite on probes, More wiggly scope patterns

Module 2: High Frequency passive probe compensation, Probe compensation, compensation and measurement frequency response, compensation and waveform distortion, compensation adjustment, compensation adjustment location, when to compensate, probe compensation effects

Differential measurements, need of differential measurements, advantages of differential measurements, available options for differential measurements, FET differential probes, two hi-Z 10X passive probe using A-B, balance coaxial probe, probe correction techniques

Module 3: Magnetic loop and other noncontact measurements, Square magnetic pickup loop- theory of operation, factors affecting size and shape of pickup loop, orientation of loop, current response of the pickup loop, pickup loop null experiments, effect of the pickup loop on circuit operation, Pickup loop technique of locating noise sources, other non-contact measurements.

Module 4: Current probes theory and uses, DC coupled, AC Coupled, Theory of operation, uses for current probes, limitations and Magnetic core saturation.

Module 5: Measurement of pulsed EMI effects on Electronic circuits: introduction, Technical background, inductive and capacitive coupling, the skin effect, and Measurement pitfalts, realistic options for system level pulsed.

Text Books:

- 1. High Frequency Measurements and Noise in Electronic Circuit. Douglas C. Smith, Kluwer Academic Publishers, 1992
- 2. Noise in High-Frequency Circuits and Oscillators, Burkhard Schiek, Heinz-Jürgen Siweris, Ilona Rolfes, Wiley-Interscience, A john Wiley & sons inc. pub., 2006

Reference Book:

1. High-Frequency Circuit Design and Measurements, Peter C. L. Yip, Chapman & Hall, Delhi

Gaps in the syllabus (to meet Industry/Profession requirements): Nil

POs met through Gaps in the Syllabus: N/A

Topics beyond syllabus/Advanced topics/Design:

Current technological developments advanced image processing techniques

POs met through Topics beyond syllabus/Advanced topics/Design:

S. No.	Course Delivery Methods	Used
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors	Yes
CDM 2	Quizzes	Yes
CDM 3	Assignments/Seminars	Yes
CDM 4	Mini projects/Projects	Yes
CDM 5	Laboratory experiments/teaching aids	No
CDM 6	Industrial/guest lectures	Yes
CDM 7	Industrial visits/in-plant training	No
CDM 8	Self- learning such as use of NPTEL materials and internets	Yes
CDM 9	Simulation	No

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
AssignmentMarks	1	1	1	1
End SemExamination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

					Progra	um Outc	omes				
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	2	1	-	2	1	1	1	1	1	2	2
CO2	3	1	-	2	1	1	1	2	1	2	2
CO3	2	2	-	2	1	1	1	1	1	1	1
CO4	2	1	2	2	1	1	1	1	1	1	1

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70%

Lecture Wise Lesson Plan Details

Wee	Lect	Tentative	Mod	Topics to be covered	Text	COs	Actual	Methodol	Remark
k		Date	ule	1	Book /	map	Content	ogy	s by
No.	No.		No.		Refere	ped	covered	used	faculty
					nces	1			if any
1	1		1	Oscilloscope probes: types,	T1, T2,R1			PPT and	
				examples of Noise sources,				Chock-	
				effect of high frequency noise				Board	
	2			Electric Field Coupling,	T1, T2,R1			Do	
				Inductive Voltage drop,					
				Magnetic field coupling					
	3			Coaxial cable operation,	T1, T2,R1			Do	
				resistive/Capacitive Voltage					
				Divider					
2	4			High and low impedance	T1, T2,R1			Do	
				Passive oscilloscope probes					
				and High impedance Active					
				oscilloscope probes					
	5			Current probes, current probe	T1, T2,R1			Do	
			-	specification,					
	6			Current probe electric field	T1, T2,R1			Do	
			_	response					
3	7		2	Probe ground lead effects,	T1, T2,R1			Do	
				lead inductance, lead					
				inductance and probe					
			-	response	T1 T2 D1			D	
	8			probe type with improved	T1, T2,R1			Do	
				response, tell-tale signs of					
				probe resonance	T1 T2 D1			D	
	9			Wiggly scope patterns, Ground lead common	T1, T2,R1			Do	
				impedance induced error, The null experiment					
4	10			ground loading, use of ferrite	T1, T2,R1			Do	
4	10			on probes, More wiggly scope	11, 12,KI			D0	
				patterns					
	11			High Frequency passive	T1, T2,R1			Do	
	11			probe compensation, Probe	11, 12,111				
				compensation					
	1			compensation					

	10				
	12		compensation and	T1, T2,R1	Do
		3	measurement frequency response, compensation and		
		5	waveform distortion		
5	13			T1, T2,R1	Do
	14		compensation adjustment	T1, T2,R1	Do
	15		compensation adjustment	T1, T2,R1	Do
			location, when to compensate		
6	16		probe compensation effects	T1, T2,R1	Do
	17		Differential measurements	T1, T2,R1	Do
	18		need of differential	T1, T2,R1	Do
			measurements, advantages of		
7	19		differential measurements available options for	T1, T2,R1	Do
	19		differential measurements	11, 12, KI	Do
	20		FET differential probes,	T1, T2,R1	Do
	21		two hi-Z 10X passive probe	T1, T2,R1	Do
			using A-B		
8	22		balance coaxial probe,	T1, T2,R1	Do
	23		probe correction techniques	T1, T2,R1	Do
	24	4	Magnetic loop and other noncontact measurements	T1, T2,R1	Do
9	25		Square magnetic pickup	T1, T2,R1	Do
	26		loop- theory of operation factors affecting size and	T1, T2,R1	Do
	- 27		shape of pickup loop,	T1 T2 D1	
	27		orientation of loop	T1, T2,R1	
10	28		current response of the pickup loop	T1, T2,R1	Do
	29		pickup loop null experiments	T1, T2,R1	Do
	30		effect of the pickup loop on	T1, T2,R1	Do
11	31		circuit operation	T1, T2,R1	
11	51		Pickup loop technique of locating noise sources,	11, 12, KI	Do
	32	5	Other non-contact measurements.	T1, T2,R1	Do
	33		Current probes theory and	T1, T2,R1	Do
			uses		
12	34		DC coupled, AC Coupled,	T1, T2,R1	Do
	35		Theory of operation, uses for current probes	T1, T2,R1	Do
	36		limitations and Magnetic core saturation	T1, T2,R1	Do
13	37		Measurement of pulsed	T1, T2,R1	Do
			EMI effects on		
	- 20		Electronic circuits		
	38		Introduction, Technical background, inductive	T1, T2,R1	Do
			and capacitive coupling		
	39		the skin effect, and	T1, T2,R1	Do
			Measurement pitfalts		

40		realist	ic options for system	T1, T2,R1		D0	
		level p	pulsed				

Name of the Subject: Control System Design Course Code: EE515 Course Title: Control System Design Pre-requisite(s): EC313 Electronic Measurement, EE 305 Control Theory Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE

Name of Teacher:

Course Objectives:

1	To state the performance characteristics of control systems with specific design requirements
	and design objectives;
2	To understand the concepts of PD, PI, PID, lead, lag and lag lead controller design in time
	domain and frequency domain and apply it to specific real time numerical problems
3	To apply the state feedback controller and observer design techniques to modern control
	problems and analyse the effects on transient and frequency domain response ;
4	To realize and then design digital and analog compensators.

Course Outcomes:

At the end of the course, a student should be able to

CO1	Identify the design objectives and requirements of control systems and Interpret the concepts of PD, PI, PID, lead, lag, lag lead, and discrete data controller design and apply it to solve some design problems;
CO2	Apply the state feedback controller design and techniques and outline its effects on system's performance which includes transient response and robustness;
CO3	To develop methodologies to design real time digital and analogy compensators and reproduce the results and write effective reports suitable for quality journal and conference publications
CO4	Aspire for pursuing a carrier in control, recognize the need to learn, to engage and to adapt in a world of constantly changing technology and play role of team leader or supporter of team.

SYLLABUS

Module 1:

Performance characteristics of feedback control system & design specification of control loop. Different types of control system applications and their functional requirement. Derivation of load-locus (toque/ speed characteristics of load). Selection of motors, sensors, drives. Choice of design domain & general guidelines for choice of domain. Controller configuration and choice of controller configuration for specific design

requirement. Fundamental principles of control system design. Experimental evaluation of system dynamics in time domain and frequency domain.

Module 2:

Design with PD Controller: Time domain interpretation of PD controller, frequency domain interpretation of PD controller, summary of the effects of PD controller. Design with PI controller: Time domain interpretation of PI controller frequency domain interpretation of PI controller, summary of the effects of PI controller, design with PID controller, Ziegler Nichols tuning & other methods.

Module 3:

Design with lag/lead/lag-lead compensator, time domain interpretation of lag/lead/lag-lead compensator, frequency domain interpretation of lag/lead/lag-lead compensator, summary of the effects of lag/lead/lag-lead compensator. Forward & feed-forward controller, minor loop feedback control, concept of robust design for control system, pole-zero cancellation design.

Module 4:

Sate feedback control, pole placement design through state feedback, state feedback with integral control, design full order and reduced order state observer.

Module 5:

Design of Discrete Data Control System: Digital implementation of analog controller (PID) and lag-lead controllers, Design of discrete data control systems in frequency domain and Z plane.

Books recommended:

Text Books:

- 1. B.C. Kuo, "Automatic Control System", 7th Edition PHI. (T1)
- 2. M. Gopal, "Control Systems Principles & Design", 2nd Edition, TMH. (T2)
- 3. J.G. Truxal, "Automatic Feedback Control System", McGraw Hill, New York. (T3)
- 4. K. Ogata, "Discrete Time Control Systems", 2nd Edition, Pearson Education. (T4)

Reference Books:

- 1. Norman Nise, "Control System Engineering", 4th Edition. (R1)
- 2. M. Gopal, "Digital Control & State Variable Method", TMH. (R2)
- 3. B.C. Kuo, "Digital Control System", 2nd Edition, Oxford. (R3)
- 4. Stephanie, "Design of Feedback Control Systems", 4th Edition, Oxford. (R4)

Gaps in the syllabus (to meet Industry/Profession requirements)

POs met through Gaps in the Syllabus

Topics beyond syllabus/Advanced topics/Design

POs met through Topics beyond syllabus/Advanced topics/Design

Course Delivery methods
Lecture by use of boards/LCD projectors/OHP projectors
Tutorials/Assignments
Seminars
Mini projects/Projects
Laboratory experiments/teaching aids
Industrial/guest lectures
Industrial visits/in-plant training
Self- learning such as use of NPTEL materials and internets
Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Quizes	30
End Sem Examination Marks	60
Assignment	10

Assessment Compoents	CO1	CO2	CO3	CO4	CO5
Endterm (60%)					
Quiz (30%)					
Assignment (10%)					

Indirect Assessment -

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Overall Assessment

	CO1	CO2	CO3	CO4	CO5
Direct Assessment (DA)					
Indirect Assessment (IA)					
Overall Attainment =(0.6*DA + 0.4*IA)					

COURSE INFORMATION SHEET

Name of the Subject: Digital Image Processing Techniques Course Code: EC526 Course Title: Digital Image Processing Techniques Pre-requisite(s): EC305 Signal Processing Techniques, EC251 probability and Random Process Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

1	To gain understanding on digital image formation, characteristics and its processing steps.
2	To demonstrate the use of different spatial and frequency domain processing techniques to
	improve the image quality.
3	To apply various segmentation techniques of an image.
4	To introduce various object recognition and analysis methods for computer vision
	applications.

Course Outcomes

On the completion of this course, the students will be able to:

CO1	Develop an understanding on the image formation, pixel characteristics and processing step.
CO2	Have an ability to analyze the image quality using transformed and spatial domain filters.
CO3	Have an ability to segment and represent the image for computer vision tasks.
CO4	Develop an ability to create and apply the image processing techniques in various applications
	in many areas.

SYLLABUS

Module 1: Fundamental steps in Digital Image Processing, Components of an Image processing system, Digital Image Representation, Basic relationship between pixels, Basic Arithmetic/Logic operations on image: Image subtraction, Image averaging, Color image processing fundamentals: Color Modules, RGB,HIS, Lab colormodules, Convolution and Correlation theorems.

Module 2: Image Enhancement in Spatial and Frequency Domain: Grey Level Transformations, Histogram Processing, Smoothing and Sharpening with Spatial Domain Filters, Fourier Transform, Fast Fourier Transform, Discrete Cosine Transform, Wavelet Transforms, Smoothing and Sharpening with Frequency Domain filters, Homomorphic filtering, Pseudo Color Image Enhancement.

Module 3: Image Restoration: Noise Models, Restoration in the presence of Noise-Only Spatial filtering, Mean filters, Adaptive filters Periodic Noise Reduction by Frequency Domain filtering, Inverse Filtering, Minimum Mean Square Error (Wiener) Filtering, Geometric Mean Filter.

Module 4: Image Segmentation and Representation: Detection of Discontinuities, Point Detection, Line detection, Edge Detection, Thresholding, Optimal Global and Adaptive thresholding, Region-based Segmentation, Textural Images, Textural Feature extraction from Co-occurrence matrices, Chain codes, Signatures, Boundary Segments, Skeletons, Boundary Descriptors, Regional Descriptors.

Module 5: Object Recognition and Interpretation: Elements of Image analysis, Pattern Classifier, Minimum distance classifier, Baye's Classifier, Neural Network algorithm, Fuzzy classifier, structural methods.

Text Books:

1. Digital Image Processing. 2/E by Rafael C. Gonzalez and Richard E. Woods. Pearson Education

2. Digital Image Processing and Analysis. by B. Chanda and D. Dutta Mujumdar PHI

Reference Book:

- 1. Fundamentals of Digital Image Processing. By Anil K. Jain, PHI Publication
- 2. Image Processing, Analysis and Machine Vision. Milan Sonka and Vaclav Hlavac,

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects

CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

					Progra	um Outc	omes				
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	1	2	2	2		1		1	2		
CO2	2	3	2	3		2		1	3	1	1
CO3	3	3	1	3		2		1	3	1	1
CO4	3	3	1	3	1	3		2	3	1	1

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures

CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Lecture Wise Lesson Plan Details

Wee	Lect	Tentativ	Modul	Topics to be covered	Text	COs	Actual	Methodol	Remark
k No.	No.	e Date	e No.		Book / Refere	mappe d	Content covered	ogy used	s by faculty
NO.	110.	Date	NO.		nces	u	covereu	useu	if any
1	1		1	Introduction to Digital Image	1	CO1		PPT and	
				Processing Techniques.				Chock-	
	2		-	Course objectives Fundamental steps in Digital	1	CO1		Board Do	
	2			Image Processing,	1	001		D0	
				Components of an Image					
	2		-	processing system	1	<u>CO1</u>		D	
	3			Digital Image Representation	1	CO1		Do	
2	4			Basic relationship between	1	CO1		Do	
				pixels, Basic					
				Arithmetic/Logic operations on image: Image subtraction,					
				Image averaging,					
	5			Color image processing	1	CO1		Do	
				fundamentals: Color Modules, RGB,HIS, Lab color modules					
	6		-	Convolution and Correlation	1	CO1		Do	
	-			theorems.	_				
3	7		2	Image Enhancement in Spatial	1	CO1		Do	
	8		-	domain fundamentals. Gray Level Transformations,	1	CO1		Do	
	0			Histogram Processing	1	COI		D0	
	9			Smoothing and Sharpening	1	CO2		Do	
	10		-	with Spatial Domain Filters, ,				5	
4	10			Frequency Domain Enhancement: Fourier	1	CO2		Do	
				Transform, Fast Fourier					
			-	Transform					
	11			Discrete Cosine Transform	1	CO2		Do	
	12			Wavelet Transforms,	1	CO2		Do	
5	13		1	Smoothing and Sharpening	1	CO2		Do	
				with Frequency Domain					
	14		3	filters Homomorphic filtering,PseudoColorImage	1	CO2		Do	
	14			Enhancement.	1				
	15		1	Image Restoration: Noise	1	CO2		Do	
	1		-	Models					
6	16			Restoration in the presence of Noise-Only Spatial filtering,	1	CO2		Do	
	17			Mean filters, Adaptive filters.	1	CO3		Do	
	18			Periodic Noise Reduction by	1	CO3		Do	
7	19		-	Frequency Domain filtering,	1	CO3		Do	
/	19			Inverse Filtering.,, Geometric Mean Filter.	1	COS		D0	
J	1	1			1	1		I	I I

	20		Minimum Mean Square Error (Wiener) Filtering	1	CO3	Do
	21		Image Segmentation Fundamentals and its application	1	CO3	Do
8	22		Detection of Discontinuities: Point Detection, Line detection,	1	CO3	Do
	23	4	Edge Detection	1	CO3	Do
	24		Thresholding: , Optimal, Global , Adaptive thresholding,	1	CO3	Do
9	25		Region-based Segmentation	1	CO4	Do
	26		Textural Images, ,	1	CO4	Do
	27		Textural Feature extraction from Co-occurrence matrices	1	CO4	
10	28		Chain codes, Signatures, Boundary Segments,	1	CO4	Do
	29		Skeletons, Boundary Descriptors,	1	CO4	Do
	30		Regional Descriptors.	1	CO4	Do
11	31		Object Recognition : Fundamentals		CO4	Do
	32	5	Elements of Image		CO4	Do
	33		Pattern Classifier	1	CO4	Do
12	34		Minimum distance classifier,	1	CO4	Do
	35		Baye's Classifier	1	CO4	Do
	36		Neural Network algorithm,	1	CO4	Do
13	37		Fuzzy classifier	1	CO4	Do
	38		Structural methods.	1	CO4	Do
	39		Application of image processing techniques	1	CO4	Do
	40		Recapsulization of the course		CO4	D0

COURSE INFORMATION SHEET

Name of the Subject: Speech Processing & Recognition Course Code: EC527 Course Title: Speech Processing & Recognition Pre-requisite(s): EC305 Signal Processing Techniques Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students:

1	To explain fundamentals of speech production, its perception and inherent features.
2	To develop an ability to analyse parameter estimation and feature representations of speech signals.
3	To develop an ability to evaluate the pattern comparison and design issues of speech recognition.
4	To develop the concept and utilization of statistical and pattern recognition models. To develop the ability to apply the speech analysis and recognition methods for different real life applications.

Course Outcomes

After the completion of this course, students will be able to:

CO1	Demonstrate the understanding on the speech production, its perception and features.
CO2	Analyse various components of parameter estimation and feature representations of speech
	signals.
~ ~ •	
CO3	Illustrate various models for speech synthesis and automatic recognition.
<u>CO3</u>	Illustrate various models for speech synthesis and automatic recognition. Analyse the speech recognition and implementation issues. Develop an ability to create and

SYLLABUS

Module-I

Speech Production: Introduction, Speech Production Process, Representing Speech in Time and Frequency domains, Speech Sounds and Features, Statistical pattern recognition approach to speech recognition

Module-II

Signal Processing and Analysis Method for Speech Recognition: Introduction, Linear predictive coding model for Speech Recognition, LPC model, LPC analysis equations, Autocorrelation method, Covariance method, LPC processor for speech recognition, MFCC, Vector quantization: Elements of VQ, VQ training set, Similarity or Distance Measure, Clustering, Vector classification procedure

Module-III

Pattern comparison techniques: Introduction, Speech Detection, Distortion Measures, Spectral-Distortion Measures :Log Spectral Distance, Cepstral Distances, Weighted Cepstral Distances and Liftering, Likelihood Distortion, Variance of Likelihood distortion, Time Alignment and Normalization

Module-IV

Hidden Markov Models : Introduction, Discrete-Time Markov Process, Extensions to HMM, Three Basic Problems for HMM, Types of HMM, Implementation issues for HMMs, HMM System for Isolated Word Recognition, Gaussian Mixture Model, HMM-GMM for isolated word recognition

Module-V

Applications of Automatic Speech Recognition and Support Vector Machine: Introduction, Support Vector Machines: Linear and Non-linear classifications, Computing the SVM classifier, Properties, Speech-Recognizer Performance Scores, Characteristic of Speech-Recognition Applications, Broad classes of Speech-Recognition Applications, Command and Control Applications, Projections for Speech Recognition, Applications of Speech Recognition in Mobile Phones.

Text Book:

1. L.R. Rabiner, B.H. Juang and B. Yegnanarayana, "Fundamentals of Speech Recognition", Pearson, Education 2011.

2. Cristianini Nello and Shawe-Taylor, "An introduction to Support Vector Machines and other kernel based learning methods", Cambridge University Press, 2000.

Reference Book:

1. L.R. Rabiner and R.W. Schafer, "Digital Processing of Speech Signals", Pearson Education, 2006.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

Program Outcomes	
	Program Outcomes

Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	2	2	2	2	3	1	0	2	1	1
CO2	3	3	3	2	3	2	0	0	3	2	2
CO3	3	2	3	3	3	2	0	0	3	1	2
CO4	3	3	3	3	3	2	3	1	2	2	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1,C02,C03, C04	
CD1 CD2	Tutorials/Assignments	C04 C02,C03,C04	
CD3	Seminars	CO3,C04	
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids	CO1,C02,C03, C04	
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets	CO1,C02,C03, C04	
CD9	Simulation	CO1,C02,C03, C04	

Lecture wise Lesson planning Details.

Week	Lect.	Tent	Ch.	Topics to be covered	Text	COs	Actual	Methodol	Remar
No.	No.	ativ	No.		Book	mappe	Conten	ogy	ks by
		e				d	t	used	faculty
		Dat			Refer		covere		if any
		e			e		d		
					nces				
1	L1			Illustration of course	T1	1		PPT,	
				objectives and course				Board,	
				outcomes, besides detailed				Notes	
				introduction of the course					
				syllabus.					
	L2			Speech production process	T1	1		do	
	L3			Representation of speech in time and frequency domain	T1	1		do	
2	L4			Speech sound and features	T1	1		do	
	L5			Speech sound and features	T1	1		do	
	L6			Approaches to automatic speech recognition	T1	1		do	
3	L7			Approaches to automatic speech recognition	T1	1		do	
	L8			Introduction to signal processing techniques for speech analysis	T1	1		do	

r	1				
	L9	Linear predictive coding model for Speech	T1	2	do
		Recognition			
4	L10	Linear predictive coding :	T1	2	do
•	LIU	LPC model, Analysis		2	40
		equations			
	L11	Linear predictive coding :	T1	2	do
	LII	Autocorrelation method	11	2	
	L12	Linear predictive coding :	T1	2	do
	LIZ	Covariance method,	11	2	
		Analysis Parameters			
5	1.12	Vector quantization	T1	2	do
3	L13				
	L14	Introduction to pattern recognition	T1	2	do
	L15	Speech detection methods	T1	2	do
6	L16	Various distortion measures	T1	2	do
U		Spectral distortion measures	T1	2	do
	L17	- -			
	L18	Spectral dynamic features to distortion measure	T1	2	do
7	L19	Time alignment	T1	2	do
		&normalization : Dynamic			
		Programming, Constraints			
	L20	Time alignment	T1	2	do
	120	&normalization : Dynamic			
		Time – Warping Solutions			
	L21	Discrete-Time Markov	T1	3	do
		Process		C	
8	L22	Hidden Markov Model	T1	3	do
U	L22 L23	Types of HMMs	T1	3	do
		Continuous observation	T1	3	do
	L24	densities in HMM	11	3	00
9	L25	Auto regressive HMMs	T1	3	do
,			T1	3	do
	L26		11	3	
		structures	T 1	2	1.
	L27	Explicit state duration	T1	3	do
10		density in HMMs	T 1	3	
10	L28	Comparison of HMMs	T1	_	do
	L29	Implement issues for HMM	T1	3	do
	L30	Model clustering and	T1	3	do
		Splitting			
11	L31	HMM for isolated word	T1	3	do
		recognition			
	L32	Gaussian Mixture Model,	T1	3	do
		Speaker recognition using			
		GMM			
	L33	Introduction to Kaldi toolkit	RB2	3	do
12	L34	Introduction to SVM,	T2	3	do
	231	Linear and Non-linear			
		classifications			
	L35	Computing the SVM	T2	3	do
		classifier, Properties,	_	-	
		Implementation			
	L36	Speech –recognizer	T1	4	do
	1.50	performance score			
13	L37	Characteristics of speech	T1	4	do
		recognition applications			
			I	1	

	L38	Classes of speech recognition applications	T1	4	do
	L39	Command and Control Applications	T1	4	do
14	L40	Speech recognition in Mobile Phones	T1	4	do

COURSE INFORMATION SHEET

Name of the Subject: CMOS Digital VLSI Design Course code: EC528 Course title: CMOS Digital VLSI Design Pre-requisite(s): EC101 BECE Co- requisite(s): Credits: L: 3 T: 0 P: 0 C: 3 Class period per week: 03 Class: M. Tech. Semester / Level: 01/01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	To apprehend Design technique of Inverter and Combinational Logic Circuits in CMOS and
	model them with VHDL/Verilog/SystemVerilog.
B.	To perceive Design technique of Sequential Logic Circuits in CMOS and model them using
	VHDL/Verilog/ SystemVerilog.
C.	To understand Timing Issues in Digital Circuits, model Clock Generator, Test Bench using
	VHDL/Verilog/System-Verilog Modelling,s data path, memory and control structure design
	techniques
D.	To grasp CMOS Fabrication Process and Manufacturing Issues.

Course Outcomes:

After the completion of this course, students will be able to:

1	Design and analyze Inverter and Combinational Logic Circuits in CMOS with given design
	specification such as propagation delay, power dissipation, PDP and EDP.
CO2	Design and analyze Sequential Logic Circuits in CMOS with given design specification.
CO3	Synthesize Digital Circuits using VHDL/Verilog/SystemVerilog and model Clock Generator
	and Test Bench.
CO4	Appraise CMOS Fabrication Process and Manufacturing Issues.

SYLLABUS

Module -1:

Design of Inverter and Combinational Logic Circuits in CMOS and their VHDL/Verilog/ SystemVerilog Modelling:

Static and Dynamic Behaviour of CMOS Inverter: Switching Threshold, Noise Margin formulation, computing capacitance, Propagation Delay, Power, Delay, Power-Delay Product, Energy-Delay Product. Design of CMOS Combinational Logic Circuits: Static CMOS Design: Complementary CMOS, Ratioed Logic, Pass-Transistor Logic; Dynamic CMOS Design: Basic Principles of Dynamic Logic, Speed and

Power Dissipation of Dynamic Logic, Signal Integrity Issues in Dynamic Design Cascading Dynamic Gates. Introduction to the SPICE/VHDL/Verilog/SystemVerilog with Design examples of inverter, NAND and NOR gates.

Module -2:

Design of Sequential Logic Circuits in CMOS and their VHDL/Verilog/ SystemVerilog Modelling: Timing Metrics for sequential Circuits, Static Latches and Registers: Bistability Principle, Multiplexer-Based Latches, Master-Slave Edge-Triggered Register, Low-Voltage Static Latches; Dynamic Latches and Registers: Dynamic Transmission-Gate Edge-triggered Registers, C2MOST – A Clock-Skewed Insensitive Approach, True Single-Phase Clocked Register (TSPCR), Alternative Register Styles: Pulse Registers, Sense-Amplifier Based Registers, Pipelining: Latch- versus Register-Based Pipelines, NORA-CMOS—A Logic Style for Pipelined Structures, Nonbistable Sequential Circuits: The Schmitt Trigger, Monostable Sequential Circuits, Astable Circuits, Clocking Strategy; Design examples of latch, flip-flop, register and Memory (RAM, ROM) using SPICE/VHDL/Verilog/SystemVerilog HDL.

Module -3:

Timing Issues in Digital Circuits and VHDL/Verilog/SystemVerilog Modelling of Clock Generator and Test Bench:

Timing Classification of Digital Systems: Synchronous Interconnect – Mesochronous interconnect, Plesiochronous Interconnect, Asynchronous Interconnect; Synchronous Design — An In-depth Perspective - Synchronous Timing Basics, Sources of Skew and Jitter, Clock-Distribution Techniques, Latch-Based Clocking; Self-Timed Circuit Design: – Self-Timed Logic - An Asynchronous Technique, Completion-Signal Generation, Self-Timed Signalling, Practical Examples of Self-Timed Logic; Synchronizers and Arbiters: Synchronizers—Concept and Implementation, Arbiters; Clock Synthesis and Synchronization Using a Phase-Locked Loop: Basic Concepts. Building Blocks of a PLL; Future Directions and Perspectives: Distributed Clocking Using DLLs, Optical Clock Distribution, Synchronous versus Asynchronous Design, Design examples of clock and test bench using SPICE/VHDL/Verilog/SystemVerilog HDL.

Module -4:

CMOS Fabrication Process and Manufacturing Issues:

CMOS Technologies, Layout Design Rules, CMOS Process Enhancements, Design Rule Checking (DRC), Inverter cross-section, Layout of CMOS Inverter, Layout of 2-input NAND gate, Layout of 2-input NOR gate, Layout of Complex logic gate, Layout of Domino AND gate, Stick Diagrams, Design Partitioning, Floor Planning; Estimation of parasitics: diffusion capacitance and interconnect parasitics, package parasitics, impact of parasitics on circuit performance. Manufacturing Issues: Antenna Rules, Layer Density Rules, Resolution Enhancement Rules, Metal Slotting Rules, Interconnect Wearout: Electromigration, Selfheating, Yield Enhancement Guidelines.

Module -5:

Design of Datapath, Memory and Control in CMOS and their VHDL/Verilog/SystemVerilog Modelling: Data operators: single-bit addition, carry-propagate addition, subtraction, multi-input addition, One/Zero detectors, magnitude comparators, equality comparators, counters, Boolean logic operators, Funnel shifters, Barrel Shifter, Array multiplier, Wallace tree multiplier; Shifter: Barrel Shifter, Logarithmic Shifter, Power and Speed Trade-off's in Datapath Structures: Design Time Power-Reduction Techniques, Run-Time Power Management, Reducing the Power in Standby (or Sleep) Mode; Memory: SRAM, DRAM, ROM, Flash memory, FIFO; Control Structure Design: Mealy and Moore FSM, state-transition diagram, state reduction technique, control logic implementation, Design examples of Datapath (adder, subtractor, multiplier, comparator, counter, decoder, multiplexer) and control unit (Mealy and Moore FSM) using SPICE/VHDL/Verilog/ SystemVerilog HDL.

Text Books:

- 1. J. M. Rabaey, A. Chandrakasan, B. Nikolic, "Digital Integrated Circuits A Design Perspective," 2nd ed., Upper Saddle River, New Jersey, USA: PHI, 2003.
- N. H. E. Weste and D. M. Harris, "CMOS VLSI Design A Circuits and Systems Perspective," 4th ed., Boylston Street, Boston, USA: PHI, 2011.
- 3. S. Palnitkar, "Verilog HDL: A guide to Digital Design and Synthesis," 1st ed., SunSoft Press, 1996.

Reference Book:

- 1. D. L. Perry, "VHDL Programming," 4th ed., Tata McGraw Hill, 2012.
- 2. Stuart Sutherland, Simon Davidmann, Peter Flake, SystemVerilog Design A Guide to Using SystemVerilog for Hardware Design and Modeling, 2/e, Springer, 2006.

Gaps in the syllabus (to meet Industry/Profession requirements): N/A

POs met through Gaps in the Syllabus: PO8 will be met though report-writing/presentation-based assignment

Topics beyond syllabus/Advanced topics/Design: Teaching through paper

POs met through Topics beyond syllabus/Advanced topics/Design: Teaching through paper

CD #	Course Delivery methods
CD1	Lecture by use of boards/LCD projectors/OHP projectors
CD2	Quizzes
CD3	Assignments/Seminars
CD4	Mini projects/Projects
CD5	Laboratory experiments/teaching aids
CD6	Industrial/guest lectures
CD7	Industrial visits/in-plant training
CD8	Self- learning such as use of NPTEL materials and internets
CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End SEM Examination Marks	60

CO1	CO2	CO3	CO4
3	3	3	
			3
3	3	3	3
	CO1 3 3	CO1 CO2 3 3 3 3	CO1 CO2 CO3 3 3 3 3 3 3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Indirect Assessment -

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO1
						6				0	1
C01	3	3	3	3	1	2	3	1	1	3	3

	•	•	-
	2	3	3
CO4 3 3 3 3 3 2 3 3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Марр	Mapping Between COs and Course Delivery (CD) methods									
CD	Course Delivery methods	Course Outcome	Course Delivery Method							
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1							
CD2	Quizzes	CO1, CO2, CO3	CD2							
CD3	Assignments/Seminars	CO3	CD3							
CD4	Mini projects/Projects									
CD5	Laboratory experiments/teaching aids									
CD6	Industrial/guest lectures									
CD7	Industrial visits/in-plant training									
CD8	Self- learning such as use of NPTEL materials and internets									
CD9	Simulation									

Lecture Wise Lesson Planning Details:

Week	Lect.	Tentati	Ch.	Topics to be covered	Text	COs	Methodology	Remarks
No.	No.	ve	No.		Book /	map	used	by
		Date			Refere	ped		faculty
					nces			if any
1	L1		3	Static and Dynamic Behaviour of	T1,	1	PPT Digi	
				CMOS Inverter: Switching	T2, T3		Class/Chock	
				Threshold,			-Board	
	L2		5	Noise Margin formulation,	T1,	1	do	
				computing capacitance, Propagation	T2, T3			
				Delay, Power				
	L3		5	Delay, Power-Delay Product,	T1,	1	do	
				Energy-Delay Product.	T2, T3			
2	L4		6	Design of CMOS Combinational	T1,	1	do	
				Logic Circuits: Static CMOS	T2, T3			
				Design: Complementary CMOS,				
				Ratioed Logic, Pass-Transistor				
				Logic;				
	L5		6	Dynamic CMOS Design: Basic	T1,	1	do	
				Principles of Dynamic Logic, Speed	T2, T3			
				and Power Dissipation of Dynamic				
				Logic				
	L6		6	Signal Integrity Issues in Dynamic	T1,	1	do	
				Design Cascading Dynamic Gates	T2, T3			
3	L7		1	Introduction to the VHDL with	R1	1	do	
				design examples of inverter, NAND				
				and NOR gates				
	L8		1	Introduction to the Verilog with	T3	1	do	
				design examples of inverter, NAND				
				and NOR gates				
	L9		1	Introduction to the SystemVerilog	R2	1	do	
				with design examples of inverter,				
				NAND and NOR gates				
4	L10		7	Timing Metrics for sequential	T1,	2	do	
				Circuits, Static Latches and	T2, T3			
				Registers: Bistability Principle				

	T 1 1		Multiplayan Desert Let 1 Mar	TT1	2	
	L11	7	Multiplexer-Based Latches, Master-	T1, T2 T2	2	do
			Slave Edge-Triggered Register,	T2, T3		
			Low-Voltage Static Latches			
	L12	7	Dynamic Latches and Registers:	T1,	2	do
			Dynamic Transmission-Gate Edge-	T2, T3		
			triggered Registers			
5	L13	7	C ² MOST – A Clock-Skewed	T1,	2	do
			Insensitive Approach, True Single-	T2, T3		
			Phase Clocked Register (TSPCR)			
	L14	7	Alternative Register Styles: Pulse	T1,	2	do
		-	Registers, Sense-Amplifier Based	T2, T3		
			Registers	,		
	L15	7	Pipelining: Latch- versus Register-	T1,	2	do
	L15	'	Based Pipelines, NORA-CMOS—A	T2, T3	-	
			Logic Style for Pipelined Structures	12, 13		
6	L16	7		TT1	2	do
0	L10	/	Nonbistable Sequential Circuits:	T1,	2	do
	I 17		The Schmitt Trigger	T2, T3	2	
	L17	7	Monostable Sequential Circuits,	T1,	2	do
			Astable Circuits, Clocking Strategy;	T2, T3		
	L18	7	Design examples of latch, flip-flop,	T1,	2	do
			register and Memory (RAM, ROM)	T2, T3		
			using			
			VHDL/Verilog/SystemVerilog			
			HDL			
7	L19	10	Timing Classification of Digital	T1,	3	do
			Systems: Synchronous Interconnect	T2, T3		
			– Mesochronous interconnect			
	L20	10	Plesiochronous Interconnect,	T1,	3	do
	-	-	Asynchronous Interconnect;	T2, T3		
			Synchronous Design — An In-depth	-, 20		
			Perspective - Synchronous Timing			
			Basics			
	L21	10	Sources of Skew and Jitter, Clock-	T1,	3	do
	1221	10	Distribution Techniques, Latch-	T2, T3	5	uv
			Based Clocking	12, 13		
8	L22	10		T1,	3	do
0	LZZ	10	Self-Timed Circuit Design: – Self-	· ·	5	do
			Timed Logic - An Asynchronous	T2, T3		
	X 22		Technique	T 1		
	L23	10	Completion-Signal Generation,	T1,	3	do
			Self-Timed Signalling, Practical	T2, T3		
			Examples of Self-Timed Logic			
	L24	10	Synchronizers and Arbiters:	T1,	3	do
			Synchronizers—Concept and	T2, T3		
			Implementation, Arbiters			
9	L25	10	Clock Synthesis and	T1,	3	do
			Synchronization Using a Phase-	T2, T3		
			Locked Loop: Basic Concepts.			
			Building Blocks of a PLL			
	L26	10	Future Directions and Perspectives:	T1,	3	do
			Distributed Clocking Using DLLs,	T2, T3		
			Optical Clock Distribution,	, 10		
			Synchronous versus Asynchronous			
			Design			
	L27	10	Design examples of clock and test	T1,	3	do
	L2/	10			5	uo
			e	T2, T3		
			VHDL/Verilog/SystemVerilog			
1	1		HDL		1	

10	L28	2	CMOS Technologies, Layout Design Rules, CMOS Process	T1, T2	4	do
			Enhancements			
	L29	2	Design Rule Checking (DRC), Inverter cross-section, Layout of CMOS Inverter	T1, T2	4	do
	L30	2	Layout of 2-input NAND gate, Layout of 2-input NOR gate, Layout of Complex logic gate	T1, T2	4	do
11	L31	2	Layout of Domino AND gate, Stick Diagrams, Design Partitioning, Floor Planning	T1, T2	4	do
	L32	2	Estimation of parasitics: diffusion capacitance and interconnect parasitics, package parasitics	T1, T2	4	do
	L33	2	impact of parasitics on circuit performance	T1, T2	4	do
12	L34	2	Manufacturing Issues: Antenna Rules, Layer Density Rules	T1, T2	4	do
	L35	2	Resolution Enhancement Rules, Metal Slotting Rules	T1, T2	4	do
	L36	2	InterconnectWearout:Electromigration,Self-heating,Yield Enhancement Guidelines	T1, T2	4	do
13	L37	11	Data operators: single-bit addition, carry-propagate addition, subtraction, multi-input addition	T1, T2, T3	4	do
	L38	11	One/Zero detectors, magnitude comparators, equality comparators, counters, Boolean logic operators	T1, T2, T3	4	do
	L39	11	Funnel shifters, Barrel Shifter	T1, T2, T3	4	do
14	L40	11	Array multiplier, Wallace tree multiplier	T1, T2, T3	4	do
	L41	11	Shifter: Barrel Shifter, Logarithmic Shifter	T1, T2, T3	4	do
	L42	11	Power and Speed Trade-off's in Datapath Structures: Design Time Power-Reduction Techniques	T1, T2, T3	4	do
15	L43	11	Run-Time Power Management, Reducing the Power in Standby (or Sleep) Mode	T1, T2, T3	4	do
	L44	12	Memory: SRAM, DRAM, ROM, Flash memory, FIFO, Control Structure Design: Mealy and Moore FSM, state-transition diagram, state reduction technique, control logic implementation	T1, T2, T3	4	do
	L45	11, 12	Design examples of Datapath (adder, subtractor, multiplier, comparator, counter, decoder, multiplexer) and control unit (Mealy and Moore FSM) using Verilog/ SystemVerilog HDL.	T1, T2, T3	4	do

COURSE INFORMATION SHEET

Name of the Subject: Instrumentation Lab-1 Course Code: EC582 Course Title: Instrumentation Lab-1 Pre-requisite(s): Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objective: This course enables the students:

А.	To understand the basics of Instrumentation.
B.	To develop basic and advanced techniques in Instrumentation.
C.	To implement various basic Instrumentation and Virtual Instrumentation Devices.
D.	To develop Ladder diagram for different applications

Course Outcome: After the completion of this course, students will be able to:

CO1	Develop virtual instruments using LabVIEW
CO2	Use Data acquisition system with LabVIEW
CO3	Implement PLC for different applications
CO4	Use of automation studio for interfacing PLC

List of experiments

- 1. Logic gates implementation using case structure in LabVIEW.
- 2. Implementation of mathematical operations using Maths block in LabVIEW.
- 3. Design of function generator and CRO using case structure and for-loop in LabVIEW.
- 4. To blink LED externally using myRIO DAC card and LabVIEW.
- 5. To interface a seven-segment LED with myRIO in LabVIEW.
- 6. To implement a servo feedback control system using myRIO in LabVIEW.
- 7. To implement an IR range finder in the range of 0cm and 80cm using myRIO in LabVIEW.
- 8. To implement a sonic range finder with maximum range of 6m using myRIO in LabVIEW.
- 9. Use of automation studio for interfacing PLC
- 10. Study of Application of automation studio
- 11. Logic-gate simulation using PLC.
- 12. Drink dispenser simulation using PLC

Text Books:

- 1. Computer Based Industrial Control By Krishna Kant, PHI
- 2. Process Control Instrumentation By Curtis D. Johnson, Pearson Education
- 3. National Instruments LabVIEW manual.

Reference Books:

- 1. "Principle of Industrial Instrumentation" By D. Patranabis, TMH publications
- 2. High performance Instrumentation and Automation, CRC Press, Taylor & Francis Group, 2005

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, *2* for fulfilling less than 70% and *3* for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO11
						6				0	
CO1	3	2	1	1	3	1	2	3	1	2	2
CO2	2	2	1	2	3	2	2	1	1	2	2
CO3	2	2	3	2	1	1	1	2	3	2	2
CO4	2	3	3	3	3	1	2	2	1	2	2

Mapping Between COs and Course Delivery (CD) methods						
CD	Course Delivery methods	Course Outcome	Course Delivery Method			
CD1	Lecture by use of boards/LCD projectors/OHP projectors					
CD2	Tutorials/Assignments/Quiz (s)					
CD3	Seminars					
CD4	Mini projects/Projects					
CD5	Laboratory experiments/teaching aids	CO1, CO2, CO3, CO4	CD5			
CD6	Industrial/guest lectures					
CD7	Industrial visits/in-plant training					
CD8	Self- learning such as use of NPTEL materials and internets					
CD9	Simulation	CO1, CO2, CO3, CO4	CD9			

Lab Turn Wise Experiment Planning Details:

Week	Exp.	Tentativ	Ch.	Topic/experi	Text	COs	Actual	Methodolog	Remarks
No.	No.	e	No.	ment to be	Book /	mapped	Content	у	by
		Date		covered	Refere		covered	used	faculty if
					nces				any
1	-		-		-	-		CAD tools	
2	Exp. 1		App. – A & B		T3, T2	1		do	
3	Exp. 2		6		T1, T2	2		do	
4	Exp. 3		App. – A & B		T3, T2	1		do	
5	Exp. 4		App. – A & B		T3, T2	1		do	
6	Exp. 5		App. – A & B		T3, T2	1		do	
7	Exp. 6		App. – A & B		T3, T2	1		do	
8	Exp. 7		2		T2	3		do	
9	Exp. 8		2		T2	3		do	
10	Exp. 9		6		T1	2		do	
11	Exp. 10		7		R1	4		do	
12	Exp. 11		10		R1	4		do	
13	Exp. 12		8		R1	4		do	

COURSE INFORMATION SHEET

Course Code: EC521 Course Title: Advanced Sensing Techniques Lab Pre-requisite(s): EC208 Electronics Measurement Lab Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objective: This course enables the students:

А.	To understand the principle of operations of different sensors .
B.	To use of Test bench for calibration.
C.	To design fiber optic sensor
D.	Understand sensitivity and crosss-ensitivity

Course Objective: After the completion of this course, students will be able to:

CO1	Physical parameters measurement and control using respective sensorr
CO2	Use testbench for calibration
CO3	Design fiber optic sensor
CO4	Calculate sensitivity and cross-sensitivity

List of experiments

- 1. Measurement of vibration
- 2. Measurement of torque
- 3. Measurement of conductivity of the liquid.
- 4. Design of wireless sensor network for room temp measurement.
- 5. Design of wireless sensor network for pressure ar different points in a process
- 6. Use of Test bench for calibration of temperature
- 7. Use of Test bench for calibration of Pressure
- 8. Use of Test bench for calibration of level
- 9. Measurement of speed using tacho-generator
- 10. Design of pressure sensor using fiber optic sensor.
- 11. Design temperature sensor using fiber optic sensor
- 12. Find sensitivity and cross sensitivity for pressure sensor at different temperature

Text Books:

- 1. Sensors and Transducers, by D. Patranabis. 2nd Edition
- 2. Electrical & Electronics Measurements and Instrumentation by A.K Sawhney, Dhanpat Rai & Sons.
- 3. Transducers and Instrumentation, by Murthy D. V. S., Prentice Hall, 2nd Edition, 2011.

Reference Books:

1. Sensor and signal conditioning by John G. Webster, Wiley Inter Science, 2nd edition, 2008

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, **2** for fulfilling less than 70% and **3** for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO11
						6				0	
CO1	3	2	3	3	2	1	2	2	3	1	2
CO2	2	3	3	2	2	1	2	2	1	2	1
CO3	2	2	3	2	1	2	3	2	1	1	1
CO4	2	3	3	2	1	1	2	1	2	2	1

Mapping Between COs and Course Delivery (CD) methods					
CD	Course Delivery methods	Course Outcome	Course Delivery Method		
CD1	Lecture by use of boards/LCD projectors/OHP projectors				
CD2	Tutorials/Assignments/Quiz (s)				
CD3	Seminars				
CD4	Mini projects/Projects				
CD5	Laboratory experiments/teaching aids	CO1, CO2, CO3, CO4	CD5		
CD6	Industrial/guest lectures				
CD7	Industrial visits/in-plant training				
CD8	Self- learning such as use of NPTEL materials and internets				
CD9	Simulation	CO1, CO2, CO3, CO4	CD9		

Lab Turn Wise Experiment Planning Details:

Wee	Exp.	Tentative	Ch.	Topic/experi	Text	COs	Actual	Methodolog	Remarks
k	No.	Date	No.	ment to be	Book /	mapped	Content	у	by
No.				covered	Refere		covered	used	faculty if
					nces				any
1	-		-		-	-			
2	Exp. 1		App. – A & B		T3, T2	1		do	
3	Exp. 2		6		T1, T2	2		do	
4	Exp. 3		App. – A & B		T3, T2	1		do	
5	Exp. 4		App. – A & B		T3, T2	1		do	
6	Exp. 5		App. – A & B		T3, T2	1		do	
7	Exp. 6		App. – A & B		T3, T2	1		do	
8	Exp. 7		2		T2	3		do	
9	Exp. 8		2		T2	3		do	
10	Exp. 9		6		T1	2		do	
11	Exp. 10		7		R1	4		do	
12	Exp. 11		10		R1	4		do	
13	Exp. 12		8		R1	4		do	

COURSE INFORMATION SHEET

Name of the Subject: Advanced Digital Signal Processing Lab Course Code: EC523 Course Title: Advanced Digital Signal Processing Lab Pre-requisite(s): EC305 signal Processing techniques Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students:

	L.	
	Г	

A.	To understand the basics of DSP.
B.	To develop basic and advanced techniques in signal processing.
C.	To implement various basic DSP and Advanced DSP techniques in Hardware Platform
	(DSP Processor kit).
D.	To develop to apply advanced DSP techniques to various engineering applications.

Course Outcomes

After the completion of this course, students will be able to:

CO1	To implement the theoretical knowledge acquired in DSP.
CO2	To illustrate various models signal modelling, representation, synthesis and analysis.
CO3	To apply various DSP algorithms in real life applications.
CO4	Have the ability to prepare reports and analyze the results.

List of Compulsory experiments:

- 1. Computation of the linear convolution and circular convolution of two finite-length sequences using MATLAB.
- 2. Obtain the Partial Fraction Expansion of the Z-Transform expression and to find its Inverse Z-Transforms using MATLAB.
- 3. Testing for the stability of given Discrete Time Systems using MATLAB
- 4. To write a program for finding the DFT and FFT of a Discrete time finite length sequence.
- 5. To write a program and simulate using C language for computation of Linear Convolution using TMS 320C6713 DSK Processor.
- 6. Development of the program for finding out DFT and FFT of a finite length sequence using TMS 320C6713 DSK Processor.
- 7. To write a program and simulate using C language for designing a Digital Filter (LP/ HP / BP / BR) using TMS 320C6713 DSK Processor.
- 8. To write a program to implement LMS and RLS algorithm using MATLAB.
- 9. Representation of stationary and non-stationary signals using wavelet transformation.
- 10. Implementation of sub-band filtering approach using MATLAB.
- 11. To write a program for system identification using MATLAB and also implement in TMS 320C6713 DSK Processor.
- 12. To write a program for channel equalization using MATLAB and also implement in TMS 320C6713 DSK Processor.
- 13. Signal Processing of ECG Signals and Measuring Heart Rate, Spectrum analysis of Noisy and pure Biosignal
- 14. Noise cancellation using Adaptive filtering

- 15. Study and observation of full precision, low precision and differential error between two using precision filter.
- 16. Noise control using a combination of Low pass and High pass filters.

Text Books:

- 1. Digital Signal Processing 3/E by Proakis & Manolakis, PHI Edition
- 2. Adaptive Signal Processing, Widrow and Stearns, Pearson Education

Reference Books:

- 1. Digital Signal Processing 3/E by S.K.Mitra TMH Edition.
- 2. Discrete-Time Signal Processing 2/E by Oppenheim, Schafer & Buck, PHI Edition.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment			
Assignment Marks	10			
Quizzes	30			
End Sem Examination Marks	60			

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO11
						6				0	
CO1	1	2	3	2		1		1	3		1
CO2	2	3	3	2		2	1	2	3	1	2
CO3	2	3	3	2		2	1	2	3	2	2
CO4	3	3	3	3		2	1	2	3	1	2

Mapping of Course Outcomes onto Program Outcomes

Марр	Mapping Between COs and Course Delivery (CD) methods							
CD	Course Delivery methods	Course Outcome	Course Delivery Method					
CD1	Lecture by use of boards/LCD projectors/OHP projectors							
CD2	Tutorials/Assignments/Quiz (s)							
CD3	Seminars							
CD4	Mini projects/Projects							
CD5	Laboratory experiments/teaching aids	CO1, CO2, CO3, CO4	CD5					
CD6	Industrial/guest lectures							
CD7	Industrial visits/in-plant training							
CD8	Self- learning such as use of NPTEL materials and internets							
CD9	Simulation	CO1, CO2, CO3, CO4	CD9					

Lab Turn Wise Experiment Planning Details:

Week	Exp.	Tentativ	Ch.	Topic/experi	Text	COs	Actual	Methodolog	Remarks
No.	No.	e	No.	ment to be	Book /	mapped	Content	у	by
		Date		covered	Refere		covered	used	faculty if
					nces				any
1	-		-		-	-		CAD tools	
2	Exp. 1				T3, T2	1		do	
3	Exp. 2				T1, T2	2		do	
4	Exp. 3				T3, T2	1		do	
5	Exp. 4				T3, T2	1		do	
6	Exp. 5				T3, T2	1		do	
7	Exp. 6				T3, T2	1		do	
8	Exp. 7				T2	3		do	
9	Exp. 8				T2	3		do	
10	Exp. 9				T1	2		do	
11	Exp. 10				R1	4		do	
12	Exp. 11				R1	4		do	
13	Exp. 12				R1	4		do	

II-Semester

COURSE INFORMATION SHEET

Name of the Subject: Process Control Instrumentation Course Code: EC568 Course Title: Process Control Instrumentation Pre-requisite(s): EE351 Control Theory, EC313 Electronics Measurement Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	To develop the mathematical model of the physical system
В.	To analyze the interdependency of multivariable controller.
C.	To design a controller for practical systems under different condition
D.	Explain the different processes involved in power generation

Course Outcomes:

After the completion of this course, students will be:

CO1	Analyze a physical system and develop the mathematical model of the physical
	system
CO2	Design a controller for practical systems under different condition.
CO3	Understand the operation of different complex control schemes.
CO4	Understand the need of process control in different plants and industries

SYLLABUS

Module -1: Introduction

Introduction to process control, Examples of surge tank, shower, Use of instrumentation in Process control, Process model and dynamic behaviour. Reason of modelling, Lumped parameter system models, Balanced equation, Material balances, Form of dynamic model.

Module -2: Design of Controller

Closed loop controller design procedure. PID controller, tuning of PID controller. Internal model control: Introduction to model control, Static control law, Dynamic control law, Practical open loop controller design, Generation of open-loop controller design procedure, model uncertainty and disturbances.

Module -3: Complex Control Schemes

Complex control schemes: Background, Introduction to cascade control, cascade control analysis and design, feed forward control, feed forward control design, examples of feed forward control. Ratio control, selective and override control, split -range control. Multivariable control, general pairing problem, Steady state effective gain, Relative Gain Array (RGA), Properties and application of RGA, Use of RGA to determine variable pairing,

Module -4: Plant wide control and Model predictive control:

Steady state and dynamic effect of recycle, compressor control, Heat exchanger, the control and optimisation hierarchy. Optimisation problem, dynamics matrix control (DMC).

Module -5: Application of Process Control

Application of process control in thermal power plant: Process of power generation in coal –fired and oilfired thermal power plants, types of boilers, Combustion process, Super heater, Turbine. Application of process control in Petrochemical Industries: Introduction to Refinery and Petrochemical processes, Control of distillation column, Catalytic cracking unit, Catalytic reformer, Pyrolysis unit, Automatic Control of polyethylene production, Control of vinyl chloride and PVC production.

Text Books:

1. . "Process control: Modelling Design and simulation" By B.Wayne Bequette,

Reference Books:

1. "Principle of Industrial Instrumentation" By D. Patranabis, TMH publications

- 2. "Principles of Process Control" By D. Patranabis, TMH publication
- 3. "Power plant performance" By A. B. Gill, Elsevier, India, New Delhi.

4. J.G. Balchan. and K.I. Mumme, 'Process Control Structures and Applications', Van Nostrand Reinhold Company, New York, 1988.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

Student Feedback on Faculty
 Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Course Outcome #		Program Outcomes											
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO1		
						6				0	1		
CO1	3	3	2	3		3	1	3	3	3	3		
CO2	3	3	2	3		3	1	3	3	3	3		
CO3	2	2	3	3	1	3	1	2	3	3	3		
CO4	3	3	2	3	2	3	1	3	3	3	3		

Mapping between COs and Course Delivery (CD) methods

CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4, CO5	CD1
CD2	Quizzes	CO1, CO2, CO3, CO4	CD2
CD3	Assignments/Seminars	CO5	CD3
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets		
CD9	Simulation		

Lecture Wise Lesson Planning Details:

Week	Lect.	Tentative	Ch.	Topics	to	be	Text	COs	Actual	Methodology	Remarks
No.	No.	Date	No.	covered			Book /	mappe	Content	used	by
							Refere	d	covered		faculty if
							nces				any
1	L1			Illustratio	n	of		1		PPT Digi	
				course o	bject	ives				Class/Chock	
				and	co	urse				-Board	
				outcomes	, bes	ides					
				detailed							
				introducti	on of	f the					
				course sy		s.					
	L2			Introduct	ion	to	T1	1		do	
				process c	ontro	1					
	L3			Analyze		the					
				physical							
				with exa	-	of					
				surge tan							
	L4			Analyze		the	T1	1		do	
				physical							
				with the		nple					
				of shower	ſ						
2	L5			Use		of					
				instrumer							
				Process c	ontro	1					

	TC			
	L6	Process model and		
		dynamic		
		behaviour		
	L7	Mathematical		
		model of the		
		physical system.		
		Back ground,		
		Reason of		
		modelling,		
	L8	Lumped		
	LO	parameter system		
		models		
3	L9	Balanced		
3	L9			
		equation: Material		
		balance		
	L10	integral balance		
		and instantaneous		
		balance		
	L11	Closed loop		
		controller design		
		procedure.		
	L12	Development of		
		control system		
		block diagram		
4	L13	PID controller,		
-	L13	tuning of PID		
	1.14	controller		
	L15			
	LIS	Internal model		
		control:		
		Introduction to		
		model control		
	L16	Static control law,		
		Dynamic control		
		law		
5	L17	Practical open		
		loop controller		
		design		
	L18	Generation of		
		open-loop		
		controller design		
		procedure		
	L19	Model uncertainty		
	LIV	and disturbances.		
		and disturbances.		
	L20	Comparison		+
	L20	Comparison		
		between closed		
		loop controller		
		and open loop		
		controller.		
6	L21	Complex control		
		schemes:		
		Background,		
		multivariable		
		controller		
	L22	Introduction to		
		cascade control,		
		cascade control		
L		cuscude control	I I I	1

		 		[T	<u> </u>
		analysis and design				
	L23	feed forward				
		control, feed				
		forward control				
		design				
	L24	examples of feed				
		forward control.				
7	L25	Ratio control, selective and over				
/	L23	ride control				
	L26	split -range		 		
		control				
	L27	multivariable				
		control,				
		interdependency				
	L28	Relative gain				
8	L29	Array Departies and		 		
8	L29	Properties and application of				
		RGA,				
	L30	Use of RGA to				
	200	determine				
		variable pairing,				
	L31	Steady state and				
		dynamic effect of				
	1.20	recycle	-			
	L32	Snow ball effect in recycler				
9	L33	compressor				
-	200	control, Heat				
		exchanger				
	L34	the control and				
		optimisation				
	1.05	hierarchy	-			
	L35	Model predictive				
	L36	control Optimisation				
	1.50	problem,				
10	L37	dynamics matrix		 		
		control (DMC)		 		
	L38	Error estimation		 		
	L39	Process of power				
		generation in coal				
		-fired thermal				
	L40	power plants				
	L40	Process of power generation in oil-				
		fired thermal				
		power plants				
11	L41	types of boilers,				
		Combustion				
		process				
	L42	Super heater,				
	T 40	Turbine		 		
	L43	Importance of				
		Instrumentation in				

		thermal power
	L44	plant. Introduction
	L44	Refinery
12	L45	Introduction Petrochemical
		processes
	L46	Control of distillation column
	L47	Catalytic cracking unit, Catalytic reformer
	L48	Pyrolysis unit
13	L49	Automatic Control of polyethylene production
	L50	Control of vinyl chloride and PVC production.

COURSE INFORMATION SHEET

Name of the Subject: Embedded System Design Course Code: EC570 Course Title: Embedded System Design Pre-requisite(s): EC203 Digital System Design Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students:

A.	Define the fundamental of embedded systems
B.	Show the correlation between hardware & software in embedded system
C.	Design the highly secure optimized embedded systems and show the application of embedded system in present market
D.	Develop the suitable software for embedded system

Course Outcomes

After the completion of this course, students will be able to:

1.	Recognize the interfacing and integration of component in SoC.
2.	Design the highly secure ATM.
3.	Develop the programmable kit to check the entire components in a board.
4.	Develop the embedded systems & corresponding software as per demand of current market.

SYLLABUS

Module 1:

Introduction to Embedded System:

The concept of embedded systems design, Embedded microcontroller cores, embedded memories, Examples of embedded systems, partitioning, partition by feature, partition with CPU, finding missing interrupts.

Module 2:

Technological aspects of embedded systems:

Interfacing between analog and digital blocks, signal conditioning, digital signal processing, ISR Debugging, Measuring performance, Guessti matching performance, a poor man's performance analyzer, RTOS,

Module 3:

Sub-System Design & Interfacing:

Sub-system interfacing, interfacing with external systems, user interfacing; hacking peripheral driver, selecting stack size, the curse of Malloc(), Banking, logical to physical, hardware issues, software, predicting ROM requirements, RAM diagnostic, Inverting bits, noise issues, notes of software prototyping.

Module 4:

Design Trade Off & Hardware Musings:

Design trade-offs due to process compatibility, thermal considerations; Debug gable design, test point galore, resistors, unused inputs, clocks, reset, small CPUs, watchdog timers, making PCBs, changing PCB, Planning.

Module 5:

Software aspects of embedded systems & Trouble shooting tools:

Real time programming languages and operating systems for embedded systems; Emulators, BDMs, ROM Monitors, ROM emulators, Oscilloscopes, Scoping Tricks, Fancy tools and big bucks, Tool woes, reliable connections, nonintrusive myths, add debugging resources, ROM burnout, speed up by slowing down.

Text books:

- 1. J.W. Valvano, "Embedded Microcomputor System: Real Time Interfacing", Brooks/Cole, 2000.
- 2. Jack Ganssle, "The Art of Designing Embedded Systems", Newnes, 1999.

Reference Books:

- 1. V.K. Madisetti, "VLSI Digital Signal Processing", IEEE Press (NY, USA), 1995.
- 2. David Simon, "An Embedded Software Primer", Addison Wesley, 2000.
- 3. K.J. Ayala, "The 8051 Microcontroller: Architecture, Programming, and Applications", Penram Intl, 1996.

4. Gaps in the SYLLABUS (to meet Industry/Profession requirements):

5. POs met through Gaps in the SYLLABUS:

6. Topics beyond SYLLABUS/Advanced topics/Design:

7. POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

8. Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

- 1.Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes										
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	
CO1	2	2	2	2	2	2	2	2	2	2	2	
01	3	3	3	3	2	3	3	3	Z	3	3	
CO2	2	3	3	2	2	3	3	3	3	3	3	
CO3	3	2	3	3	2	3	3	3	2	3	3	
CO4	3	3	3	3	2	3	3	3	3	3	3	

	Mapping Between COs and Course Delivery (CD) methods								
				Course					
			Course	Delivery					
CD	Course Delivery methods		Outcome	Method					

		CO1, CO2,	
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO3	CD1
CD2	Tutorials/Assignments	CO2, CO3	CD1
CD3	Seminars	CO3, CO4	CD1 and CD2
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets	CO4	
CD9	Simulation		

Lecture wise Lesson planning Details.

Week No.	Lect No.	Tentativ e Date	Ch. No	Topics to be covered	Text Book / Refere nces	COs mapp ed	Actual Conten t covere d	Methodolog y used	Remark s by faculty if any
1	L1		1	The concept of embedded systems design	T1, R2,R3	1, 2		PPT Digi Class/Chock -Board	
	L2		1	The concept of embedded systems design	T1, R2,R3	1, 2		-do-	
	L3		1	The concept of embedded systems design	T1, R2,R3	1, 2		-do-	
2	L4		1	Embedded microcontroller cores	T1, R2,R3	1, 2		-do-	
	L5		1	Embedded microcontroller cores	T1, R2,R3	1, 2		-do-	
	L6		1	Embedded microcontroller cores	T1, R2,R3	1, 2		-do-	
3	L7		1	embedded memories	T1, R2,R3	1, 2		-do-	
	L8		1	embedded memories	T1, R2,R3	1, 2		-do-	
	L9		1	embedded memories	T1, R2,R3	1, 2		-do-	
4	L10		1	Examples of embedded systems	T1, R2,R3	1, 2		-do-	
	L11		1	Examples of embedded systems	T1, R2,R3	1, 2		-do-	
	L12		1	Examples of embedded systems	T1, R2,R3	1, 2		-do-	
5	L13		2	Interfacing between analog and digital blocks	T1, R1,R3	1, 2		-do-	
	L14		2	Interfacing between analog and digital blocks	T1, R1,R3	2, 3		-do-	

	T 1 7		τ. C ' 1.	T 1		1
	L15	2	Interfacing between	T1, R1,R3	2, 3	-do-
			analog and digital	кі,кэ		
			blocks			
6	L16	2	signal conditioning	T1,	2, 3	-do-
	T 17		· 1 1'.' ·	R1,R3	0.0	1
	L17	2	signal conditioning	T1, R1,R3	2, 3	-do-
	L18	2	signal conditioning	T1,	2, 3	-do-
	L10		signal conditioning	R1,R3	2, 5	-00-
7	L19	2	digital signal	T1,	2, 3	-do-
/	L19	2	processing	R1,R3	2, 5	-40-
	L20	2		T1,	2, 3	-do-
	L20		0	R1,R3	2, 5	-00-
	I 01	2	processing		2.2	1-
	L21	2	digital signal	T1, R1,R3	2, 3	-do-
-	X 00		processing			· · · · · ·
8	L22	3	Sub-system	T2,	2, 3	-do-
			interfacing	R1,R3		
	L23	3	Sub-system	T2,	2, 3	-do-
			interfacing	R1,R3		
	L24	3	Sub-system	Τ2,	2, 3	-do-
			interfacing	R1,R3		
9	L25	3	interfacing with	Τ2,	2, 3	-do-
			external systems,	R1,R3		
	L26	3	interfacing with	Τ2,	2, 3	-do-
	_		external systems	R1,R3		
	L27	3	interfacing with	Т2,	2, 3	-do-
	227		external systems	R1,R3	2, 5	
10	L28	3	user interfacing	T2,	2, 3	-do-
10	L20	5	user interfacing	R1,R3	2, 5	-40-
	L29	3	user interfacing	T2,	2, 3	-do-
		5	user interfacing	R1,R3	2, 5	40
	L30	3	user interfacing	T2,	2, 3	-do-
	200	C		R1,R3	_, 0	
11	L31	6	Design tradeoffs due	Τ2,	3, 4	-do-
			to process	R1,R3		
			compatibility,			
			1 57			
	L32	6	Design tradeoffs due	Т2,	3, 4	-do-
	101	0	to process	R1,R3	5, 1	
			compatibility	<i>,</i>		
	L33	6	Design tradeoffs due	Т2,	3, 4	-do-
			to process	R1,R3	, т	
			compatibility	-,	1	
12	L34	6	thermal	Т2,	3, 4	-do-
12	ட34	o	considerations	12, R1,R3	5,4	-00-
	1.25			T2,	2 4	
	L35	6	thermal	12, R1,R3	3, 4	-do-
	LOC		considerations			<u>├ </u>
	L36	6	thermal	T2,	3, 4	-do-
10			considerations	R1,R3	<u> </u>	
13	L37	10	Real time	T2,	4	-do-
			programming	R1,R3	1	
			languages		1	
	L38	10	Real time	Τ2,	4	-do-
			programming	R1,R3	1	
			languages			
	L39	10	operating systems	Τ2,	4	-do-
			for embedded	R1,R3		
			systems		1	
L	1	l	<i>u</i>		1	<u> </u>

for embedded R1,R3 systems	14	L40		10	operating systems for embedded	T2, R1,R3	4		-do-	
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COURSE INFORMATION SHEET

Name of the Subject: Optoelectronic Instrumentation Course Code: EC572 Course Title: Optoelectronic Instrumentation Pre-requisite(s): EC351 Fiber Optics Communication , EC313 Electronics Measurement Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	To provide knowledge about the optical sources and Detectors
В	To provide Knowledge about Fiber Optic Instrumentation and its application for various
	measurements
C.	To provide Knowledge about LASER and its different types with their industrial and
	medical application
D.	To provide Knowledge about the Holography and its applications.

Course Outcomes:

After the completion of this course, students will be:

CO1	To provide knowledge about the optical sources and Detectors							
CO2	Gain Knowledge about Fiber Optic Instrumentation and its application for various							
	measurements							
CO3	Gain Knowledge about LASER and its different types with their industrial and medical							
	application							
CO4	Gain Knowledge about the Holography and its applications.							

SYLLABUS

Module -1:

Gaussian optics, Physical Optics, Fourier optics, optical sources, Heterojunction LED's and LASERS, semiconductor Lasers Optical interferometers, mono-chromators, Photon detectors, Photo-emissive cells, LDR, Light Activated SCR, Heterostructure solar cell, noise statistics and accuracy of measurements, Statistical approach to measurements, inaccuracy of indirect measurements.

Module -2:

Fiber optic instrumentation, Optocoupler, optoelectronic Isolator, Fiber-optic Pressure and flow sensors, optical current sensor, Fiber-optic Displacement sensor, Interferometric Fiber optic sensors, Mach-Zehnder, Michelson, Fabry perot sensor, fiber Bragg grating sensors for strain and temperature measurements, Distributed sensors based on Raleigh, Raman, Brillouin, Optical spectrum Analyser, Fiber-optic Endoscope

Module -3:

Principles of operation of Lasers, Mode locking, Q switching in Lasers, Tunable lasers, Laser for Velocity Measurement. Angular Rotation Rate, Measurement of Product Dimension Measurement of Surface Finish Profile and Surface Position Measurement, Particle Diameter Measurement, Strain and Vibration Measurement, Cylindrical Form Measurement, Defect Detection, Surface Flaw Inspection Monitor

Module -4:

Laser Doppler Anemometry, Laser microscope, Raman Spectroscopy in Medicine, Laser Doppler vibrometer, Heterodyne measurements of Air drums, Laser Lithotripsy, Laser induces thermos therapy of brain cancer, Atmospheric measurements of Lidar, Medical Applications of Lasers : Laser and Tissue Interaction, Laser Instruments for Surgery, Removal of Tumors of Vocal Cords, Brain Surgery, Plastic Surgery, Gynaecology and Oncology.

Module -5:

Holography for Non-destructive Testing, Holographic recording and Reconstruction, Holographic Interferometry and applications, Double exposer Holography, Real time holography, Holographic vibrational Analysis, Morie pattern, Speckle pattern, Measurement of in plane and out of plane deformations,

Text Books:

- 1. Amar K. Ganguly., "Optical and optoelectronic Instrumentation", Narosa Press, 2010
- 2. Dr. M N Avadhanulu & Dr. R S Hemne, An Introduction to Lasers- Theory and Applications, S. Chand.

Reference Book:

- 1. John F. Read, Industrial Applications of Lasers, Academic Press.
- 2. Keiser G., Optical Fiber Communication, McGraw-Hill.
- 3. John and Harry, Industrial Lasers and their Applications, Mc-Graw Hill, 1974.
- 4. Monte Ross, Laser Applications, McGraw-Hill

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment				
Assignment Marks	10				

Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	3	3	2	3	3	3	2	3	3
CO2	2	3	3	2	2	3	3	3	3	3	3
CO3	3	2	3	3	2	3	3	3	2	3	3
CO4	3	3	3	3	2	3	3	3	3	3	3

Mapping Between COs and Course Delivery (CD) methods							
CD	Course Delivery methods Course Outcome		Course Delivery Method				
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1				
CD2	Quizzes	CO1, CO2, CO3	CD2				
CD3	Assignments/Seminars	CO3	CD3				
CD4	Mini projects/Projects						
CD5	Laboratory experiments/teaching aids						
CD6	Industrial/guest lectures						
CD7	Industrial visits/in-plant training						
CD8	Self- learning such as use of NPTEL materials and internets						
CD9	Simulation						

Lecture Wise Lesson Planning Details:

Week	Lect.	Tentative	Ch.	Topics	to	be	Text	COs	Actual	Methodology	Remarks
No.	No.	Date	No.	covered			Book /	mapped	Content	used	by
							Refere		covered		faculty if
							nces				any
1	L1			Illustratio	on	of				PPT Digi	
				course o	bject	ives				Class/Chock	
				and	co	urse				-Board	
				outcome	s,						
				besides	deta	iled					

		introduction of			
		the course			
		syllabus.			
	L2	Introduction to	T1, T2	do	
		Gaussian optics,			
		Physical Optics,			
		Fourier optics			
	L3	Discuss optical	T1, T2	do	
		sources,			
		Heterojunction			
		LED's and			
		LASERS,			
		semiconductor			
		Lasers			
2	L4	Monochromators,	T1, T2	do	
-		Photon detectors,			
	L5	Photo-emissive	T1, T2	do	
	23	cells, LDR	11, 12	uo	
	L6	Light Activated	T1, T2	do	
		SCR	11, 12	uo	
3	L7	Heterostructure	T1, T2	do	
3	L/		11, 12	do	
		solar cell,	T1 T2		
	L8	Noise statistics	T1, T2	do	
		and accuracy of			
		measurements,			
	L9	Statistical	T1, T2	do	
		approach to			
		measurements,			
		inaccuracy of			
		indirect			
		measurements.			
4	L10	Introduction to	T1, T2	do	
		Fiber optic			
		instrumentation			
	L11	Optocoupler,	T1, T2	do	
		optoelectronic			
		Isolator			
	L12	Fiber-optic	T1, T2	do	
		Pressure and flow			
		sensors,			
5	L13	Optical current	T1, T2	do	
5		sensor, Fiber-	Í		
		optic			
		Displacement			
		sensor			
	L14	Interferometric	T1, T2	do	
		Fiber optic	11, 14		
		sensors, Mach-			
		Zehnder			
	L15	Michelson, Fabry	T1, T2	do	
	LIJ	-	11, 12	do	
6	I 16	perot sensor Fiber Bragg	T1 T2	do	
6	L16	66	T1, T2	do	
		grating sensors			
		for strain and			
		temperature			
	1.17	measurements	TT1 TT2		
	L17	Distributed	T1, T2	do	
		sensors based on			

		Raleigh, Raman, Brillouin		
	L18	Optical spectrum Analyser, Fiberoptic Endoscope	T1, T2	do
7	L19	Principles of operation of Lasers	T1, T2	do
	L20	Mode locking, Q switching in Lasers	T1, T2	do
	L21	Tunable lasers	T1, T2	do
8	L22	Laser for Velocity Measurement. Angular Rotation Rate	T1, T2	do
	L23	Measurement of Product Dimension Measurement of Surface Finish Profile and Surface Position Measurement	T1, T2	do
	L24	Particle Diameter Measurement, Strain and Vibration Measurement,	T1, T2	do
9	L25	Cylindrical Form Measurement	T1, T2	do
	L26	Defect Detection,		do
	L27	Surface Flaw Inspection Monitor	T1, T2	do
10	L28	Laser Doppler Anemometry	T1, T2	do
	L29	Laser microscope	T1, T2	do
	L30	Raman Spectroscopy in Medicine	T1, T2	do
11	L31	Laser Doppler vibrometer	T1, T2	do
	L32	Heterodyne measurements of Air drums, Laser Lithotripsy	T1, T2	do
	L33	Laser induces thermos therapy of brain cancer	T1, T2	do
12	L34	Atmospheric measurements of Lidar	T1, T2	do
	L35	Laser and Tissue Interaction, Laser	T1, T2	do

		Instruments for				
	L36	Surgery Removal of	T1, T2		do	
		Tumors of Vocal				
		Cords, Brain				
		Surgery, Plastic				
		Surgery,				
		Gynaecology and				
		Oncology.				
13	L37	Introduction to	T1, T2		do	
		Holography for				
		Non-destructive				
		Testing,				
		Holographic				
		recording and				
		 Reconstruction				
	L38	Holographic	T1, T2		do	
		Interferometry,				
		Double exposer				
		Holography, Real				
		time holography				

Name of the Subject: Pattern Recognition and Machine Learning Course Code: EC574 Course Title: Pattern Recognition and Machine Learning Pre-requisite(s): EC305 Signal Processing Techniques Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students:

1	Study the parametric and linear Model for Classification.
2	Understand Design neural Network and SVM for Classification.
3	Illustrate Machine independent and Unsupervised learning Techniques.
4	Identify and apply suitable classification methods for real life data classification

Course Outcomes

After the completion of this course, students will be:

CO1.	Explain the parametric and linear Model for Classification.
CO2.	Design neural Network and SVM for Classification.

CO3.	Develop Machine independent and Unsupervised learning Techniques.
CO4.	Identify and apply suitable classification methods for real life data classification

SYLLABUS

Module 1

Introduction to Pattern Recognition: Problems, applications, design cycle, learning and adaptation, examples, Probability Distributions, Parametric Learning - Maximum likelihood and Bayesian Decision Theory- Bayes rule, discriminant functions, loss functions and Bayesian error Analysis

Module 2

Linear models: Linear Models for Regression, linear regression, logistic regression, multiple linear regression, Multivariate linear regression, Least square estimation, maximum likelihood estimation for regression, Linear Models for Classification,

Module 3

Neural Network: perceptron, multi-layer perceptron, backpropagation algorithm, error surfaces, practical techniques for improving backpropagation, additional networks and training methods, Adaboost, Reinforcement learning, Deep Learning

Module 4

Linear discriminant functions - decision surfaces, two-category, multi-category, minimum squared error procedures, the Ho-Kashyap procedures, linear programming algorithms, Support vector machine, Linear discriminant analysis, principal component analysis, Independent Component analysis

Module 5

Algorithm independent machine learning – lack of inherent superiority of any classifier, bias and variance, re-sampling for classifier design, combining classifiers, Unsupervised learning and clustering – k-means clustering, fuzzy k-means clustering, hierarchical clustering

References:

1. Richard O. Duda, Peter E. Hart, David G. Stork, "Pattern Classification", 2nd Edition John Wiley & Sons, 2001.

2. Trevor Hastie, Robert Tibshirani, Jerome H. Friedman, "The Elements of Statistical

Learning", 2nd Edition, Springer, 2009.

3. C. Bishop, "Pattern Recognition and Machine Learning", Springer, 2006.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #	Program Outcomes										
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	3	2	2	1	1	3	2	3	3
CO2	3	3	3	2	2	1	1	3	2	3	3
CO3	3	3	3	2	2	1	1	3	2	3	3
CO4	3	3	3	2	2	1	1	3	2	3	3

	Mapping Between COs and Course Delivery (CD) methods								
CD	Course Delivery methods	Course Outcome	Course Delivery Method						
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1	CD1						
CD2	Tutorials/Assignments	CO2	CD1						
CD3	Seminars	CO3	CD1 and CD2						
CD4	Mini projects/Projects								
CD5	Laboratory experiments/teaching aids								
CD6	Industrial/guest lectures								
CD7	Industrial visits/in-plant training								
CD8	Self- learning such as use of NPTEL materials and internets								
CD9	Simulation								

Wee	Lect	Tentativ	Modul	Topics to be covered	Text	COs	Actual	Methodol	Remark
k No.	No.	e Date	e No.		Book / Refere	mappe d	Content covered	ogy used	s by faculty if any
1	1		1	Introduction, Course objectives	nces 1	CO1		PPT and Chock- Board	
	2			Problems, applications,	1	CO1		Do	
	3			design cycle, learning and adaptation, examples,	1	CO1		Do	
2	4			Probability Distributions,	1	CO1		Do	
	5			Parametric Learning - Maximum likelihood and Bayesian Decision Theory-	1	CO1		Do	
	6			Bayes rule, discriminant functions,	1	CO1		Do	
3	7		2	loss functions and Bayesian error Analysis	1	CO1		Do	
	8			Linear Models for Regression,	1	CO2		Do	
	9			linear regression, logistic regression,	1	CO2		Do	
4	10			multiple linear regression, ,	1	CO2		Do	
	11		3	Multivariate linear regression,	1	CO2		Do	
	12			Least square estimation,	1	CO2		Do	
5	13			maximum likelihood estimation for regression,	1	CO2		Do	
	14			Linear Models for Classification	1	CO2		Do	
	15			perceptron,	1	CO3		Do	
6	16			multi-layer perceptron,	1	CO3		Do	
	17			backpropagation algorithm, error surfaces,	1	CO3		Do	
	18			practical techniques for improving backpropagation,	1	CO3		Do	
7	19		4	additional networks and training methods,	1	CO3		Do	
	20]	Adaboost,	1	CO3		Do	
	21			Reinforcement learning,	1	CO3		Do	
8	22		l	Deep Learning	1	CO3		Do	
	23			Deep Learning applications	1	CO3		Do	
9	24 25			decision surfaces,	1	CO4		Do	
9	25 26			two-category, multi-category, minimum squared error	1	CO4 CO4		Do	
				procedures,					
	27			the Ho-Kashyap procedures,	1	CO4			

10	28		linear programming algorithms, Support vector machine,	1	CO4	Do	
	29		Linear discriminant analysis,	1	CO4	Do	
	30		principal component analysis,	1	CO4	Do	
11	31		Independent Component analysis	1	CO4	Do	
	32		lack of inherent superiority of any classifier,	1	CO4	Do	
	33	5	bias and variance,	1	CO4	Do	
12	34		re-sampling for classifier design,	1	CO4	Do	
	35		combining classifiers,	1	CO4	Do	
	36		Unsupervised learning	1	CO4	Do	
3	37		Clustering: introduction	1	CO4	Do	
	38		clustering – k-means clustering,	1	CO4	Do	
	39		fuzzy k-means clustering,	1	CO4	Do	
	40		hierarchical clustering		CO4	D0	

Name of the Subject: Modern Optimization Techniques Course Code: EC558 Course Title: Modern Optimization Techniques Pre-requisite(s): EC251 Probability and Random Processes Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students to:

1	Gain understanding on optimization theory and its elements
2	Demonstrate single variable optimization, linear programming, dynamic programming
	concepts and techniques.
3	Demonstrate multivariable and constraint optimization concepts and techniques.
4	Understand on advance single and multi-objective optimization techniques such as GA, PSO,
	Pareto font, NSGA

Course Outcomes

On the completion of this course, the students will be able to:

CO1	Develop an understanding to formulate an optimization problem and its characteristics.
CO2	Have an ability to analyze and apply algorithms for design optimization.
CO3	Have an ability to find optimum solution to engineering optimization problem.

CO4	Develop an ability to apply use optimization techniques to finance, economics, medical	l
	applications, control, communication, power, mechanical problems, chemical and biology.	l

SYLLABUS

Module 1: Optimal problem formulation, Design variables constraints, Objective function, Variable bounds, Search methods: optimality Criteria, Bracketing methods: Exhaustive search methods, Region – Elimination methods; Interval halving method, Fibonacci search method, Golden section search method, Point-estimation method; Successive quadratic estimation method.

Module 3: Gradient-based methods: Newton-Raphson method, Bisection method, Secant method, Cauchy's steepest descent and Newton's method. Linear Programming: Graphical method, Simplex Method, Revised simplex method, Duality in Linear Programming(LP), integer linear programming, Dynamic programming, Sensitivity analysis.

Module 4: Optimality criteria, Unidirectional search, Direct search methods: Simplex search method, Hooke-Jeeves pattern search method. Gradient based method, conjugate gradient method, concept of lagrangian multiplier, complex search method. Characteristics of a constrained problem. Direct methods: The complex method, Cutting plane method, Indirect method: Transformation Technique, Basic approach in the penalty function method, Interior penalty function method.

Module 4:Genetic algorithm and its working principle, GA variants, Particle swarm optimization and its working principle, Differential evolution, Multi-objective optimization principle, pareto font, NSGA.

Module 5: Application to communication, dynamic spectrum allocation, medical, clustering, bioinformatics, control, finance, mechanical structure optimization, power system

Text Books:

1. Optimization for Engineering Design - Kalyanmoy Deb, 2006, PHI

2. S.S. Rao, Engineering Optimization, Theory and practice, New age International Publisher, 2012

3. D.E. Goldberg, genetic Algorithm in search, optimization and machine learning, Addison-Wesley Longman Publisher, 1989

Reference Book:

1. Analytical Decision Making in Engineering Design - Siddal.

2. G. Hadley, "Linear programming", Narosa Publishing House, New Delhi, 1990.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures

CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

Program Outcomes											
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	1	2	1	2	2	1			2		1
CO2	2	3	2	3	3	1		1	2		1
CO3	2	3	2	3	3	1		1	2		1
CO4	3	3	3	3	3	2	1	2	3		1

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Lecture Wise Lesson Plan Details

Wee	Lect	Tentativ	Modul	Topics to be covered	Text	COs	Actual	Methodol	Remark
k		e	e	_	Book /	mappe	Content	ogy	s by
No.	No.	Date	No.		Refere	d	covered	used	faculty
					nces				if any
1	1		1	Introduction to the course,	1,2	CO1		PPT and	
				Optimal problem formulation				Chock-	
								Board	

				1	r	
	2		Design variables constraints, Objective function, Variable	1,2	CO1	Do
			bounds,			
	3		Search methods: optimality Criteria,	1,2	CO1	Do
2	4		Bracketing methods: Exhaustive search methods,	1,2	CO1,C O2	Do
	5		Region – Elimination methods;	1,2	CO2	Do
	6		Interval halving method,	1,2	CO2	Do
3	7		Fibonacci search method, Golden section search method,	1,2	CO2	Do
	8		Point-estimation method;	1,2	CO2	Do
l	9		Successive quadratic estimation method.	1,2	CO2	Do
4	10	2	Gradient-based methods:	1,2	CO2	Do
	11		Bisection method,	1,2	CO2	Do
	12		Newton-Raphson method, Secant method,	1,2	CO2	Do
5	13		Cauchy's steepest descent and Newton's method.	1,2	CO2	Do
	14		Linear Programming:	1,2	CO2	Do
	15		Graphical method,	1,2	CO2	Do
6	16		Simplex Method, Revised simplex method,	1,2	CO2	Do
	17		Duality in Linear Programming(LP),	1,2	CO2	Do
	18		integer linear programming,	1,2	CO2	Do
7	19		Dynamic programming,	1,2	CO2	Do
	20		Sensitivity analysis.	1,2	CO2	Do
	21	3	Optimality criteria,	1,2	CO1,C O2	Do
8	22		Direct search methods: Simplex search method,	1,2	CO2	Do
	23		Unidirectional search, Hooke- Jeeves pattern search method.	1,2	CO2	Do
	24		Gradient based method, conjugate gradient method,	1,2	CO2	Do
9	25		concept of lagrangian multiplier,	1,2	CO2	Do
	26		complex search method. Characteristics of a constrained problem.	1,2	CO2	Do
	27		Direct methods: The complex method, Cutting plane method,	1,2	CO2	
10	28		Indirect method: Transformation Technique,	1,2	CO2	Do

	29		Basic approach in the penalty function method, Interior penalty function method,	1,2	CO2	Do	
	30		convex method.	1,2	CO2	Do	
		4	Genetic algorithm and its working principle,				
	32		GA variants,	1,3	CO2	Do	
	33		Particle swarm optimization and its working principle,	1,3	CO2	Do	
12	34		Differential evolution,	1,3	CO2	Do	
	35		Multi-objective optimization principle,	1,3	CO3,C 04	Do	
	36		pareto font,	1,3	CO3	Do	
13	37		NSGA.	1,3	CO3,C 04	Do	
	38	5	Application to communication	1,3	CO4	Do	
	39		dynamic spectrum allocation,	1,3	CO4	Do	
14	40		medical, clustering, bioinformatics,	1,3	CO4	Do	
	41		Application to finance, control	1,3	CO4	Do	
	42		mechanical structure optimization, power system	1,3	CO4	Do	

Course Code: EC576 Course Title: Micro-Electro Mechanical System Pre-requisite(s): EC377 Sensor and Transducer Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

This course enables the students:

A.	To develop an ability, enthusiasm critical thinking in microengineering process, materials
	and design issues
B.	To develop the Fundamental concepts of MEMS technology & their applications in
	different areas
C.	To develop an ability and understanding of microscale physics for use in designing MEMS
	devices
D.	To develop an inclination towards electronics system design and manufacturing

Course Outcomes:

After the completion of this course, students will be:

CO1 Demonstrate knowledge on fundamental principles and concepts of MEMS Technology

CO2	Have an ability to analyze various techniques for building micro-devices in silicon,
	polymer, metal and other materials
CO3	Have an ability to critically analyze micro-systems technology for technical feasibility as
	well as practicality using modern tools and relevant simulation software to perform design
	and analysis.
CO4	Have an ability to analyze physical, chemical, biological, and engineering principles
	involved in the design and operation of current and future micro-devices

SYLLABUS

Module-I:

Introduction: The History of MEMS Development ,Intrinsic characteristics of MEMS,MEMS sensors and Design complexity.

Introduction to micro-fabrication: Essential overview of frequently used micro fabrication processes. Thin film deposition techniques ,wafer bonding Silicon Based MEMS processes ,MEMS Materials

Module-II:

Essential Electrical and Mechanical Concepts: Crystal planes & orientations, General Scalazr relation between Tensile stress and strain, Mechanical properties of silicon and related thin films, Flexural Beam bending Analysis ,Dynamic System ,Resonant Frequency and quality factor ,Electromechanical and Direct Analogy in Electrical and Mechanical domain.

Module -III: Sensing and Actuation schemes: Electrostatic Sensors and Actuators, Thermal sensors and actuators, Piezoresistive Sensors, Piezoelectric Sensors and Actuators, Magnetic Actuators.

Module IV: Comparison of Major Sensing and Actuation Methods and their Applications, MEMS Packaging and Integration.

Module V: Case studies for selected MEMS Products: Blood Pressure Sensor, Microphone, Accelerometer Performance and Accuracy

Text Books:

Books/ References:

 Foundations of MEMS by Chang Liu, Second Edition ,Pearson, ISBN 978-81-317-6475-6
 RF MEMS and Their Applications, Vijay K.Varadan, K.J.Vinoy and K.A.Jose, Wiley India Pvt Ltd.,Wiley India Edition, ISBN 978-81-265-2991-9

Reference Books

 Marc Madou, Fundamentals of Microfabrication by, CRC Press, 1997.Gregory Kovacs, Micromachined Transducers Sourcebook WCB McGraw-Hill, Boston, 1998.
 M.-H. Bao, Micromechanical Transducers: Pressure sensors, accelrometers, and gyroscopes by Elsevier, New York, 2000

Gaps in the SYLLABUS (to meet Industry/Profession requirements) By attending workshop and hands on training in Industry or Institute

POs met through Gaps in the SYLLABUS

Topics beyond SYLLABUS/Advanced topics/Design –Research Paper

POs met through Topics beyond SYLLABUS/Advanced topics/Design

CD #	Course Delivery methods
CD1	Lecture by use of boards/LCD projectors/OHP projectors
CD2	Tutorials/Assignments

CD3	Seminars
CD4	Mini projects/Projects
CD5	Laboratory experiments/teaching aids
CD6	Industrial/guest lectures
CD7	Industrial visits/in-plant training
CD8	Self- learning such as use of NPTEL materials and internets
CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	3	3	3	3
Assignment Marks	1	2	3	3
End Sem Examination Marks	3	3	3	3

Indirect Assessment –

- Student Feedback on Faculty
 Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Course Outcome	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
C01	3	3	3						2	2	
CO2	3	3	3	3	2		2		2	3	1
CO3		3	3		3	2	3	1	2	3	
CO4	3	3	3	3							
4											

If satisfying < 34% = 1, 34-66% = 2, > 66% = 3

CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1	CD1
CD2	Tutorials/Assignments	CO1,CO2	CD1
CD3	Seminars	CO3	CD1 and CD2
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids	CO3,CO4	CD5,CD6
CD6	Industrial/guest lectures	CO3,CO4	CD5,CD6.
CD7	Industrial visits/in-plant training	CO1,CO2	CD7
CD8	Self- learning such as use of NPTEL materials and internets	C01,C02,C03,C04	CD8
CD9	Simulation		

Lecture wise Lesson planning Details.

Wee k No.	Lect No.	Tenta tive Date	Ch. No.	Topics to be covered	Text Book / Refere	COs mapp ed	Actual Content covered	Method ology used	Remark s by faculty
1	L1		1,1	Introduction	nces TB1, TB2	1, 2	The history of MEMS From the beginning to present	PPT Digi Class/C hock -Board	if any
1	L2		1,1	Future trends	TB1,T B2	1,2	Expectations in the next 10 years MEMS research field	PPT/Bo ard	
1	L3		1	The intrinsic characteristics of MEMS	TB1	1,2	Miniaturization ,Microelectronic s Integration and parallel fabrication	PPT/Bo ard	
2	L4		1	Miniaturization	TB1,	1,2	Scaling law analysis	PPT/Bo ard	
2	L5		1	Monolithic integration	TB1,	1,2	Wafer level process flow and parallel fabrication with precision	PPT/Bo ard	
2	L6		1	MEMS Devices and applications	TB1	1,2	Sensors and Actuators	PPT/Bo ard	
3	L7		1,1	Energy domain s and transducers	TB1,T B2,	1,2	Electrical, Mechanical, Chemical, ,Magnetic, Thermal	PPT/Bo ard	
3	L8		1,	Sensor considerations	TB1	1,2,3	Sensor characteristics	PPT/Bo ard	
3	L9		1	Sensor Noise and Design Complexity	TB1,	2,3	Electronics, Mechanical and noise in circuitry	PPT/Bo ard	
4	L10		1	Actuators Considerations	TB1	2,3	General criteria for Actuator Design and Selections	PPT/Bo ard	
4	L11		2,10,11 ,1,2	Overview of Micro fabrications	TB1,T B2	2,3	General framework of micro fabrication using silicon wafers,	PPT/Bo ard	
4	L12		2 2	Thin film Deposition Techniques	TB1,T B2	1,2,3	Physical and Chemical Vapour deposition technique	PPT/Bo ard	
5	L13		2,10 1	Isotropic and An isotropic Etching	TB1 TB2	2,3	Plasma and Reactive Ion Etching	PPT/Bo ard	

5	L14	2		TB1,T	1,2,3	Different type of	PPT/Bo	
5	L14	$\frac{2}{2}$	Wafer dicing &	B2	1,2,3	wafer bonding &	ard	
		2	Wafer bonding	52		their comparison	alu	
5	L15	2	Silicon based	TB1	2,3	Three different	PPT/Bo	
5	210	$\frac{1}{2}$	MEMS processes	TB2	2,0	forms of Silicon	ard	
		_	-				uru	
6	L16	2	MEMS fabrication	TB1		Surface	PPT/Bo	
		1	Technology	TB2		Bulk and	ard	
						Lithography		
6	L17	2	MEMS material	TB1,T	1,2,3	Metal, Insulator,	PPT/Bo	
		1		B2		Semiconductor	ard	
						,Composite material and		
						material and Polymer		
6	L18	3	Review of Essential	TB1	1,2,3	Concept of	PPT/Bo	
0	LIO	5	Electrical and	IDI	1,2,3	semiconductor	ard	
			Mechanical			crystal, planes	alu	
			concepts			and orientations,		
			· · · · · · · · · · · · · · · · · · ·			stress strain		
						relation		
7	L19	3	Mechanical	TB1	1,2,3	Bending of	PPT/Bo	
			design aspects			flexural beams	ard	
						under loading		
						conditions,		
						deformation of		
_			.		1.0.0	torsion bars		
7	L20	3,	Intrinsic stress	TB1	1,2,3	Origin of	PPT/Bo	
						intrinsic stresses	ard	
						,Methods for characterization		
						,control and		
						compensation		
7	L21	1	Electromechanical	TB2	1,2,3	Electro	PPT/Bo	
-		_	Analogies		-,-,-	mechanical	ard	
			ε			mobility		
						analogies ,Direct		
						Analogy of		
						electrical and		
						Mechanical		
	<u> </u>					domains		
8	L22	3	Dynamics Analysis	TB1,	1,2,3	Dynamic system	PPT/Bo	
			of MEMS system			and governing	ard	
						equations,		
						Resonant		
						frequency and		
8	L23	4	Flectrostatio consina	TB1	221	Quality factor	PPT/Bo	\dashv
0	L23	4	Electrostatic sensing and actuation	TB1 TB2	2,3,4	Basic principle ,Advantages and	ard	
		1		102		drawback	alu	
0	LOI	A	Tourses		224		DDT/D	\dashv
8	L24	4	Types of	TD 1	2,3,4	Parallel plate and	PPT/Bo	
			Electrostatic transducer	TB1 TB2		Inter digital comb drive & its	ard	
			u ansuucer	102		application		
9	L25	4	Thermal sensing and	TB1	2,3,4	Basic principle	PPT/Bo	
,	123	4	actuation	TB1 TB2	2,3,4	and fundamental	ard	
						of Thermal	uu	
						transfer		
l	1	l l	1	1	1			

9	L26	4	Types of thermal sensor	TB1,T B2	2,3,4	Different types & their	PPT/Bo ard
						applications	
9	L27	4	Thermal Actuation	TB1 TB2	2,3,4	Basic principle And applications	PPT/Bo ard
10	L28	5 1	Types of thermal actuator	TB1 TB2	2,3,4	Different types & their applications	PPT/Bo ard
10	L29	6 1	Piezoresistive Sensors	TB1 TB2	2,3,4	Origin and basic principle of Piezoresistivity	PPT/Bo ard
10	L30	6 1	Piezoresistive sensor materials	TB1 TB2	2,3,4	Metal strain gauges and their comparison	PPT/Bo ard
11	L31	6 1	Stress analysis of mechanical Elements	TB1 TB2	1,2,3, 4	Stress in flexural cantilevers	PPT/Bo ard
11	L32	6	Stress and deformation in Membrane	TB1	1,2,3, 4	Stress analysis in membrane	PPT/Bo ard
11	L33	6 1	Application of Piezoresistive sensors	TB1 TB2	3,4	Applications with example	PPT/Bo ard
12	L34	7 1	Piezoelectric Sensing and actuation	TB1 TB2	3,4	Basic principle and Mathematical Description	PPT/Bo ard
12	L35	7	Cantilever Piezoelectric Actuator	TB1	3,4	Actuator Model	PPT/Bo ard
12	L36	7	Properties of piezoelectric materials	TB1	1,2,3	Commonly used piezoelectric materials and comparison	PPT/Bo ard
13	L37	7	Applications of piezoelectric materials	TB1	2,3,4	Types of different sensors and applications	PPT/Bo ard
13	L38	8 1	Magnetic Actuation	TB1 TB2	2,3,4	Basic principle and essential concepts	PPT/Bo ard
13	L39	8	Magnetic materials	TB1	2,3,4	Different materials and fabrication of micro magnetic components	PPT/Bo ard
14	L41	2 9	Packaging & Integration	TB1 TB2	3,4	Integrated options And Encapsulations	PPT/Bo ard
14	L42	15	Case studies for selected MEMS Products	TB1	3,4	Blood pressure, Microphones, Accelerometer	PPT/Bo ard

Name of the Subject: Photonic Integrated Circuits Course Code: EC577 Course title: Photonic Integrated Circuits Pre-requisite(s): EC 201 Electronics Devices, EC 257 Electromagnetic Fields and Waves Co- requisite(s): Credits: L: 3 T: 0 P: 0 Class schedule per week: 03 Class: M. Tech. (Instrumentation) Semester / Level: I Name of Teacher:

Course Objectives:

This course enables the students to:

A.	Understand the light-guiding properties in optical waveguides.
В	Understand the operating principle of waveguide devices.
C.	Understand the methods for fabrication of optical waveguides in silicon.
D.	Understand the system on-chip perspective and applications of Photonic Integrated circuits
	in different fields.

Course Outcomes:

After the completion of this course, students will be able to :

CO1	Explain the key properties of Optical Waveguides.				
CO2	Explain the characteristics of silicon waveguide devices.				
CO3	Design and integrate complex systems with SoC (System on Chip)				
CO4	Apply the photonic integrated circuits in various applications.				

SYLLABUS

Module -1:

Light propagation in optical waveguide, symmetrical planar waveguide, Asymmetrical planar waveguide, Ideal slave waveguide, 3D optical waveguide, Analysis of guided modes, Loss mechanisms in waveguides, Coupling to optical circuit.

Module -2:

Waveguide devices, Directional couplers, Phase-matched and non-phase-matched couplers, Distributed Bragg reflectors, Mach- Zehnder Interferometers, Optical phase modulator, Variable optical attenuators, Arrayed Waveguide Grating (AWG), PHASER-based devices, Silicon-on-Insulator (SOI).

Module -3:

Fabrication of silicon waveguide devices, SOI substrate design, waveguide integration, Photolithography, Oxidation, Formation of submicron waveguides, Silicon doping, Metallization, Design verification and device models, Design and testing infrastructure.

Module -4:

System on-chip perspective, On-chip communication, SoC Integration Issues, On-chip optical interconnect, PICMOS, WADIMOS, High speed performance of Stand-Alone-Silicon MZM, Performance of standalone MUX/DEMUX, High speed performance of silicon PIC.

Module -5:

Green Integrated Photonics, Non-linear optical losses in integrated Photonics, Two-Photon Photovoltaic effect, Non-linear Photovoltaic effect, Silicon photonic in Biosensing, Bioreceptors, Surface chemistry and passivation for biosensing, Optical reflectors Transducers in Porous Silicon, Photoluminescence Transducers, MOEMS, Photonic bandgap structures.

Text Books:

- 1. Graham T. Reed, Silicon Photonics: An Introduction, John Willey & Sons.
- 2. M. JAMAL DEEN & P. K. BASU, Silicon Photonics Fundamentals and Devices, Willey.

Reference Book:

- 1. Sasan Fathpour & Bahram Jalali., Silcon Photonics for Telecommunications and biomedicine, CRC Press.
- 2. David J. Lockwood & Lorenzo Pavesi, Silicon Photonics II: Components and Integration, Springer.
- 3. L.A.Coldren, S.W.Corzine & M.L.Masanovic, Diode Lasers and Photonic Integrated Circuits, Willey.
- 4. Marco Pisco, Andrea Cusano and Antonello Cutolo, Photonic Bandgap Structures, Bentham Science Publishers.

Gaps in the syllabus (to meet Industry/Profession requirements): N/A

POs met through Gaps in the Syllabus: PO8 will be met though report-writing/presentation-based assignment

Topics beyond syllabus/Advanced topics/Design: Teaching through paper

POs met through Topics beyond syllabus/Advanced topics/Design: Teaching through paper

CD #	Course Delivery methods
CD1	Lecture by use of boards/LCD projectors/OHP projectors
CD2	Quizzes
CD3	Assignments/Seminars
CD4	Mini projects/Projects
CD5	Laboratory experiments/teaching aids
CD6	Industrial/guest lectures
CD7	Industrial visits/in-plant training
CD8	Self- learning such as use of NPTEL materials and internets
CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End SEM Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	3	3	3	
Assignment Marks			3	
End Sem Examination Marks	3	3	3	3

If satisfying < 34% = 1, 34-66% = 2, > 66% = 3

Indirect Assessment -

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO1
						6				0	1
CO1	3	3	2	2	2	2	2	2	1	1	2
CO2	3	3	3	3	2	2	2	2	2	1	2
CO3	3	3	3	3	3	2	2	2	3	2	2

CO4	3	2	3	3	3	3	3	2	2	2	2
If satisfying < 34% = 1, 34-66% = 2, > 66% =		56% = 3									

Mapp	bing Between COs and Course Delivery (CD) methods		
CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1
CD2	Quizzes	CO1, CO2, CO3	CD2
CD3	Assignments/Seminars	CO3	CD3
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets		
CD9	Simulation		

Lecture Wise Lesson Planning Details:

Week	Lect.	Tentative	Ch.	Topics to be covered	Text	COs	Actual	Methodo	Remarks
No.	No.	Date	No.	_	Book /	mappe	Content	logy	by
					Refere	d	covered	used	faculty if
					nces				any
1	L1			Illustration of course				PPT Digi	
				objectives and course				Class/Ch	
				outcomes, besides				ock	
				detailed introduction of				-Board	
				the course syllabus					
	L2			Light propagation in	T1,T2			do	
				optical waveguide					
	L3			Symmetrical planar	T1,T2			do	
				waveguide.					
2	L4			Asymmetrical planar	T1,T2			do	
				waveguide					
	L5			Ideal slave waveguide	T1,T2			do	
	L6			3D optical waveguide	T1,T2			do	
3	L7			Analysis of guided	T1,T2			do	
				modes					
	L8			Loss mechanisms in	T1,T2			do	
				waveguides					
	L9			Coupling to optical	T1,T2			do	
				circuit					
4	L10			Waveguide devices	T1,T2			do	
	L11			Directional couplers,	T1,T2			do	
				Phase-matched and					
				non-phase-matched					
				couplers					
	L12			Distributed Bragg	T1,T2			do	
				reflectors					
5	L13			Mach-Zender	T1,T2			do	
				Interferometers					
	L14			Optical phase	T1,T2			do	
				modulator					

	L15	Variable optical attenuators	T1,T2	do
6	L16	Arrayed Waveguide Gratting (AWG)	T1,T2	do
	L17	PHASER-based devices and Silicon-on- Insulator (SOI)	T1,T2	do
	L18	Fabrication of silicon waveguide devices, SOI substrate design	T1,T2	do
7	L19	Waveguide integration	T1,T2	do
	L20	Photolithography and Oxidation	T1,T2	do
	L21	Formation of submicrone waveguides and Silicon doping	T1,T2	do
8	L22	Metalization, Design verification and device models	T1,T2	do
	L23	Design and testing infrastructure.	T1,T2	do
	L24	System on-chip perspective On-chip communication	T1,T2	do
9	L25	SoC Integration Issues	T1,T2	do
	L26	On-chip optical interconnect	T1,T2	do
	L27	PICMOS	T1,T2	do
10	L28	WADIMOS	T1,T2	do
	L29	High speed performance of Stand- Alone-Silicon MZM	T1,T2	do
	L30	Performance of standalone MUX/DEMUX	T1,T2	do
11	L31	High speed performance of silicon PIC	T1,T2	do
	L32	Green Integrated Photonics	T1,T2 ,R1	do
	L33	Non-linear optical losses in integrated Photonics	T1,T2 ,R1	do
12	L34	Two-Photon Photovoltaic effect	T1,T2 ,R1	do
	L35	Non-linear Photovoltaic effect	T1,T2 ,R1	do
	L36	Silicon photonic in Biosensing	T1,T2 ,R1	do
13	L37	Bioreceptors	T1,T2 ,R1	do
	L38	Surface chemistry and passivation for biosensing	T1,T2 ,R1	do
	L39	Optical reflectors Transducers in Porous Silicon	T1,T2 ,R1	do

14	L40	Photoluminescence Transducers	T1,T2 ,R1	do
	L41	MOEMS	T1,T2 ,R1	do
	L42	Photonic bandgap structures	T1,T2 ,R1	do

Name of the Subject: CMOS Analog VLSI Design Course code: EC578 Course title: CMOS Analog VLSI Design Pre-requisite(s): EC209 Analog Circuits (AC) Co- requisite(s): Credits: L: 3 T: 0 P: 0 C: 3 Class period per week: 03 Class: M. Tech. Semester / Level: 02/01 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	To comprehend CMOS amplifiers.					
B.	To grasp Analog CMOS Subcircuits.					
C.	To apprehend Frequency Response of CMOS Amplifiers.					
D.	To perceive CMOS Differential Amplifier and understand CMOS Operational-					
	Transconductance Amplifier.					

Course Outcomes:

After the completion of this course, students will be able to:

CO1	Apply different biasing styles to CMOS amplifier circuits.			
CO2	Design basic building blocks like current sources, current sinks, current mirrors, voltage			
	references up to layout level.			
CO3	Appraise Frequency Response of CMOS Amplifiers.			
CO4	Design and aanalyze CMOS differential amplifier and op amp.			

SYLLABUS

Module -1:

Design and Analysis of CMOS Amplifiers:

Review of MOS Large-Signal Model, Small-Signal Model, MOS Transconductance, Determination of the small-signal resistances of diode-connected NMOS and PMOS.

MOS Amplifier Topologies, Biasing, Realization of Current Sources; Common-Source Stage: CS Core, CS stage with Current-Source Load, CS stage with Diode-Connected Load, CS Stage with Degeneration, CS Core with Biasing; Common-Gate Stage: CG Stage with Biasing; Source Follower: Source Follower Core, Source Follower with Biasing.

Module -2:

Design and Analysis of Analog CMOS Subcircuits:

Analog CMOS subcircuits: MOS Diode/ Active resistor, Current Sink and Sources, Impractical biasing of MOS current sources, Current Mirrors, Application of Current Mirror as Current Steering Circuit, illustration of NMOS and PMOS current mirrors in a typical circuit, Current and Voltage Reference, Bandgap Reference; NMOS cascode current source and its equivalent circuit, PMOS cascode current source, Cascode Stage as an Amplifier, CMOS Cascode Amplifier;

Module -3:

Frequency Response of CMOS Amplifiers:

General Considerations: Relationship Between Transfer Function and Frequency Response, Bode Rules, Association of Poles with Nodes, Miller's Theorem; High-Frequency Model of Transistor: High-Frequency Model of MOSFET, Transit Frequency; Frequency Response of Common Source Stage: Use of Miller's Theorem, Direct Analysis, Input Impedance; Frequency Response of Common Gate Stage, Frequency Response of Source Follower: Input and Output Impedances, Frequency Response of Cascode Stage: Input and Output Impedances.

Module -4:

Design and Analysis of CMOS Differential Amplifier:

General Considerations: Initial Thoughts, Differential Signals, Differential Pair; MOS Differential Pair: Qualitative Analysis, Large-Signal Analysis, Small-Signal Analysis; Cascode Differential Amplifiers, Common-Mode Rejection, Differential Pair with Active Load: Qualitative Analysis, Quantitative Analysis; Frequency Response of Differential Pairs. Variability and Mismatch: Systematic Variations Including Proximity Effects, Process Variations, Random Variations and Mismatch; Analog Layout Considerations: Transistor Layouts, Capacitor Matching, Resistor Layout, Noise Considerations.

Module -5:

Design and Analysis of CMOS Operational-Transconductance Amplifier:

Performance Analysis of Current-sink CMOS inverting Amplifier, building blocks an CMOS operationaltransconductance amplifier and Voltage Operational Amplifier, block diagram a general CMOS Operational-Transconductance Amplifier and Voltage Operational Amplifier, General Characteristics of the ideal CMOS Operational-Transconductance Amplifier, Division of a two-stage uncompensated CMOS Operational-Transconductance Amplifier into voltage-to-current and current-to-voltage stages, Functions of different stages, Characterization of two-stage CMOS Operational-Transconductance Amplifier: Slew Rate, CMRR, Design guidelines of two-stage CMOS Operational-Transconductance Amplifier based on given boundary conditions.

Text Books:

- 4. Behzad Razavi, Fundamentals of Microelectronics, Wiley, 2009.
- 5. Phillip E. Allen & Douglas R. Holberg, CMOS Analog Circuit Design, 3/e, Oxford University Press, 2012.

Reference Book:

- 1. Tony Chan Carusone, David A. Johns and Kenneth W. Martin, Analogue Integrated Circuit Design, 2/e, John Wiley & Sons, 2012.
- 2. Paul R. Gray, Paul J. Hurst, Stephen H. Lewis and Roberst G. Meyer, Analysis and Design of Analog Integrated Circuits, 5/e, Wiley, 2009

Gaps in the syllabus (to meet Industry/Profession requirements): N/A

POs met through Gaps in the Syllabus: PO8 will be met though report-writing/presentation-based assignment

Topics beyond syllabus/Advanced topics/Design: Teaching through paper

POs met through Topics beyond syllabus/Advanced topics/Design: Teaching through paper

CD #	Course Delivery methods
------	-------------------------

CD1	Lecture by use of boards/LCD projectors/OHP projectors
CD2	Quizzes
CD3	Assignments/Seminars
CD4	Mini projects/Projects
CD5	Laboratory experiments/teaching aids
CD6	Industrial/guest lectures
CD7	Industrial visits/in-plant training
CD8	Self- learning such as use of NPTEL materials and internets
CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End SEM Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	3	3	3	
Assignment Marks			3	
End Sem Examination Marks	3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Indirect Assessment -

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO1
						6				0	1
CO1	3	1	3	3		3	3	3		3	3
CO2	3	1	3	3		3	3	2	1	3	3
CO3	3	1	3	3		3	3	3	1	3	3
CO4	3	1	3	3		3	3	3	1	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Марр	Mapping Between COs and Course Delivery (CD) methods						
CD	Course Delivery methods	Course Outcome	Course Delivery Method				
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1				
CD2	Quizzes	CO1, CO2, CO3	CD2				
CD3	Assignments/Seminars	CO3	CD3				
CD4	Mini projects/Projects						
CD5	Laboratory experiments/teaching aids						
CD6	Industrial/guest lectures						
CD7	Industrial visits/in-plant training						
CD8	Self- learning such as use of NPTEL materials and internets						

CD9 Simulation

Lecture Wise Lesson Planning Details:

		Lesson Plani			r	1	1		1
Week No.	Lect. No.	Tentative Date	Ch. No.	Topics to be covered	Text Book / Refere	COs mapped	Actual Content covered	Methodology used	Remarks by faculty if
1	L1		6	Review of MOS Large-Signal Model, Small- Signal Model	nces T1	1		PPT Digi Class/Chock -Board	any
	L2		6	MOS Transconductance, Determination of the small-signal resistances of diode-connected NMOS and PMOS	T1	1		do	
	L3		6	MOS Amplifier Topologies, Biasing, Realization of Current Sources	T1	1		do	
2	L4		7	Common-Source Stage: CS Core, CS stage With Current-Source Load	T1	1		do	
	L5		7	CS stage with Diode-Connected Load	T1	1		do	
	L6		7	CS Stage with Degeneration, CS Core with Biasing	T1	1		do	
3	L7		7	Common-Gate Stage: CG Stage with Biasing	T1	1		do	
	L8		7	Source Follower: Source Follower Core	T1	1		do	
	L9		7	Source Follower with Biasing	T1	1		do	
4	L10		4	Analog CMOS subcircuits: MOS Diode/ Active resistor	T1, T2	2		do	
	L11		4	Current Sink and Sources	T1, T2	2		do	
	L12		4	Impractical biasing of MOS current sources, Current Mirrors	T1, T2	2		do	
5	L13		4	Application of Current Mirror as Current Steering Circuit	T1, T2	2		do	

	- r			1	1	
	L14	9	illustration of	T1, T2	2	do
			NMOS and PMOS			
			current mirrors in			
			a typical circuit			
	L15	9	Current and	T1, T2	2	do
			Voltage Reference	,		
6	L16	9	Bandgap	T1, T2	2	do
0	210	-	Reference		-	
	L17	9	NMOS cascode	T1, T2	2	do
	L17	,	current source and	11, 12	2	
			its equivalent			
			circuit, PMOS			
			cascode current			
	I 10	0	source	TT1 TT0	2	1
	L18	9	Cascode Stage as	T1, T2	2	do
			an Amplifier,			
			CMOS Cascode			
L			Amplifier			
7	L19	11	General	T1	3	do
			Considerations:			
			Relationship			
			Between Transfer			
			Function and			
			Frequency			
			Response			
	L20	11	Bode Rules,	T1	3	do
			Association of			
			Poles with Nodes,			
			Miller's Theorem			
	L21	11	High-Frequency	T1	3	do
			Model of		-	
			Transistor: High-			
			Frequency Model			
			of MOSFET			
8	L22	11	Transit Frequency	T1	3	do
0	L22	11	Frequency	T1	3	do
	L23	11	Response of	11	5	uo
			Common Source			
			Stage: Use of			
			Miller's Theorem			
	1.24	11		T1	3	
	L24	11	Direct Analysis,	11	3	do
	1.25	11	Input Impedance	TT1	2	
9	L25	11	Frequency	T1	3	do
			Response of			
			Common Gate			
			Stage			
	L26	11	Frequency	T1	3	do
			Response of			
			Source Follower:			
			Input and Output			
			Impedances			
	L27	11	Frequency	T1	3	do
			Response of			
			Cascode Stage:			
			Input and Output			
			Impedances			
10	L28	10	General	T1	4	do
			Considerations:			
L		i – I				ı I I

		1		1			1
			Initial Thoughts,				
			Differential				
			Signals,				
			Differential Pair				
	L29	10		T1	4	do	
			Pair: Qualitative				
			Analysis, Large-				
			Signal Analysis				
	L30	10		T1	4	do	
	200	10	Analysis		•		
11	L31	10		T1	4	do	
11	LJI	10	Differential	11	4	uo	
			Amplifiers,				
			Common-Mode				
			Rejection				
	L32	2	Differential Pair	R1	4	do	
			with Active Load:				
			Qualitative				
			Analysis,				
			Quantitative				
			Analysis				
	L33	2	Frequency	R1	4	do	
	200	-	Response of		-		
			Differential Pairs				
12	L34	2	Variability and	R1	4	do	
12	L34	2	Mismatch:	K1	4	uo	
			Systematic				
			Variations				
			Including				
			Proximity Effects				
	L35	2	Process	R1	4	do	
			Variations,				
			Random				
			Variations and				
			Mismatch				
	L36	2	Analog Layout	R1	4	do	
			Considerations:				
			Transistor				
			Layouts,				
			Capacitor				
			Matching,				
			Resistor Layout,				
			Noise				
			Considerations				
12	1.27	6		T2	5	d -	
13	L37	6	Performance	12	3	do	
			Analysis of				
			Current-sink				
			CMOS inverting				
			Amplifier,				
			building blocks an				
			CMOS				
			operational-				
			transconductance				
			amplifier and				
			Voltage				
			Operational				
			Amplifier				
			Ampliner		1		

	L38 L39	6	block diagram a general CMOS Operational- Transconductance Amplifier and Voltage Operational Amplifier General Characteristics of	T2 T2	5	do do
			the ideal CMOS Operational- Transconductance Amplifier			
14	L40	6	Division of a two- stage uncompensated CMOS Operational- Transconductance Amplifier into voltage-to-current and current-to- voltage stages	T2	5	do
	L41	6	Functions of different stages, Characterization of two-stage CMOS Operational- Transconductance Amplifier	T2 T2	5	do
15	L42 L43	6	Slew Rate, CMRR Design guidelines of two-stage CMOS Operational-Trans conductance Amplifier based on given boundary conditions	T2	5	do

Name of the Subject: Instrumentation Lab-II Course Code: EC583 Course Title: Instrumentation Lab-II Pre-requisite(s): Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher: Course Objective: This course enables the students:

А.	To understand the basics of process control.
B.	To develop basic and advanced pneumatic circuits.
C.	To implement complex control scheme using labview.
D.	To use automation studio for pneumatic devices

Course Outcome: After the completion of this course, students will be able to:

CO1	Physical parameters measurement and control using respective trainer
CO2	Use automation studio for pneumatic devices
CO3	Design complex contro schemes using LabVIEW
CO4	Perform advance pneumatic operations

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome		Program Outcomes									
#	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1	PO11
										0	
C01	3	2	3	3	2	1	2	2	3	1	2
CO2	2	3	3	2	2	1	2	2	1	2	1
CO3	2	3	3	2	1	2	3	2	1	1	1
CO4	2	3	3	2	1	1	2	1	2	2	1

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

List of experiments

- 1. Flow-measurement and control using flow-loop control trainer.
- 2. Liquid-level measurement and control using level loop control trainer.
- 3. Pressure control loop using Pressure loop trainer
- 4. Operation of Cyliners using Advanced Pneumatic setup.
- 5. Opeartion of valves using Advanced Pneumatic setup.
- 6. Design of Pneumatic setup.
- 7. Design of Electro pneumatic relays using Advanced Pneumatic setup.
- 8. Use of automation studio for pneumatic devices
- 9. Use of automation studio for Electrical devices
- 10. Design of feedforward controller using LabVIEW
- 11. Design of cascade controller using Labview
- 12. Design of IMC structure using Lab VIEW

Text Books:

1. . "Process control: Modelling Design and simulation" By B.Wayne Bequette,

Reference Books:

- 1. "Principle of Industrial Instrumentation" By D. Patranabis, TMH publications
- 2. "Principles of Process Control" By D. Patranabis, TMH publication
- 3. "Power plant performance " By A. B. Gill, Elsevier, India, New Delhi.

4. J.G. Balchan. and K.I. Mumme, 'Process Control Structures and Applications', Van Nostrand Reinhold Company, New York, 1988.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:
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S. No.	Course Delivery Methods	
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors	
CDM 2	Quizzes	
CDM 3	Assignments/Seminars	Direct
CDM 4	Mini projects/Projects	
CDM 5	Laboratory experiments/teaching aids	
CDM 6	Industrial/guest lectures	
CDM 7	Industrial visits/in-plant training	
CDM 8	Self- learning such as use of NPTEL materials and internets	
CDM 9	Simulation	

Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, **2** for fulfilling less than 70% and **3** for fulfilling above 70 %

Indirect Assessment

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #		Program Outcomes									
	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO1	PO11
						6				0	
CO1	3	2	3	3	2	1	2	2	3	1	2
CO2	2	3	3	2	2	1	2	2	1	2	1
CO3	2	3	3	2	1	2	3	2	1	1	1
CO4	2	3	3	2	1	1	2	1	2	2	1

Lecture wise Lesson planning Details.

Week No.	Lect	Tentativ e	Ch. No	Topics to be covered	Text Book /	COs	Actual Content	Methodology used	Remar ks by
INO.	No.	Date			Refere nces	mapp ed	covered	used	faculty if any
1	L1		5,6	Demonstration of Experiments	T1, R1, R2	1, 2		PPT Digi Class/Chock -Board	
	L2		9,1 0	Demonstration of Experiments	T1, R1, R2	1, 2		-do-	
	L3		14, 15	Demonstration of Experiments	T1, R1, R2	1, 2		-do-	
2	L4		5	Experiment 1	T1, R1, R2	1, 2		-do-	
	L5		5	Experiment 1	T1, R1, R2	1, 2		-do-	
	L6		5	Experiment 1	T1, R1, R2	1, 2		-do-	
3	L7		5	Experiment 2	T1, R1, R2	1, 2		-do-	
	L8		5	Experiment 2	T1, R1, R2	1, 2		-do-	
	L9		5	Experiment 2	T1, R1, R2	1, 2		-do-	
4	L10		6	Experiment 3	T1, R1, R2	1, 2		-do-	
	L11		6	Experiment 3	T1, R1, R2	1, 2		-do-	
	L12		6	Experiment 3	T1, R1, R2	1, 2		-do-	
5	L13		6	Experiment 4	T1, R1, R2	1, 2		-do-	
	L14		6	Experiment 4	T1, R1, R2	2, 3		-do-	
	L15		6	Experiment 4	T1, R1, R2	2, 3		-do-	
6	L16		6	Experiment 5	T1, R1, R2	2, 3		-do-	
	L17		6	Experiment 5	T1, R1, R2	2, 3		-do-	
	L18		6	Experiment 5	T1, R1, R2	2, 3		-do-	
7	L19		9	Experiment 6	T1, R1, R2	2, 3		-do-	
	L20		9	Experiment 6	T1, R1, R2	2, 3		-do-	
	L21		9	Experiment 6	T1, R1, R2	2, 3		-do-	
8	L22		9	Experiment 7	T1, R1, R2	2, 3		-do-	
	L23		9	Experiment 7	T1, R1, R2	2, 3		-do-	
	L24		9	Experiment 7	T1, R1, R2	2, 3		-do-	
9	L25		13	Experiment 8	T1, R1, R2	2, 3		-do-	

	L26	13	Experiment 8	T1,	2, 3	-do-	
				R1, R2			
	L27	13	Experiment 8	T1,	2, 3	-do-	
				R1, R2			
10	L28	13	Experiment 9	T1,	2, 3	-do-	
				R1, R2			
	L29	13	Experiment 9	T1,	2, 3	-do-	
			_	R1, R2			
	L30	13	Experiment 9	T1,	2, 3	-do-	
			•	R1, R2			
11	L31	14	Experiment 10	T1,	3, 4	-do-	
				R1, R2			
	L32	14	Experiment 10	T1,	3, 4	-do-	
			1	R1, R2	, i i i i i i i i i i i i i i i i i i i		
	L33	14	Experiment 10	T1,	3, 4	-do-	
			1	R1, R2	<i>,</i>		
12	L34	15	Experiment 11	T1,	3, 4	-do-	
		_	I	R1, R2	- 7		
	L35	15	Experiment 11	T1,	3, 4	-do-	
		_	I	R1, R2	- 7		
	L36	15	Experiment 11	T1,	3, 4	-do-	
		_	I	R1, R2	- 7		
13	L37	15	Experiment 12	T1,	4	-do-	
_		_	I	R1, R2			
	L38	15	Experiment 12	T1,	4	-do-	
		10	r	R1, R2			
	L39	15	Experiment 12	T1,	4	-do-	
		10		R1, R2			
14	L40	10	Examination	T1,	4	-do-	
		10	Latannation	R1, R2			
				N1 , N 2			

Name of the Subject: Embedded System Lab Course Code: EC571 Course Title: Embedded System Lab

Pre-requisite(s): Fundamental knowledge of VLSI Design, Digital Electronics, signals processing, signal conditioning, microcontroller & microprocessor, I/O Interfacing.

Co-requisite(s):

Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE

Name of Teacher:

Course Objectives

This course enables the students:

A.	Recognize the programmable hardware and its programming.
B.	Develop an ability to write 8051based assembly language/ C programs.
C.	Write the program for different-2 on-chip peripherals to work with Microcontroller.

D.	Develop industrial potentials to develop product in prototype as per demand of market and
	program for complex chip debugging

Course Outcomes

After the completion of this course, students will be able to:

1.	Recognize the concept of programmable hardware and its programming.
2.	Recognize to write 8051based assembly language/ C programs.
3.	Write the efficient program for various on-chip peripherals to work with Microcontroller.
4.	Develop industrial competency to develop product in prototype as per demand of market
	and capability to debug the complex chip problems.

List of Experiments

- 1.(a). Assume that ROM space starting at 250H contains "INDIA"; write a program to transfer the bytes into RAM locations starting at 40H.
 - (b). Write a program to get the X value from P1and transmit toP2, continuously.
- **2.** Design a counter for counting the pulses of an input signal. The pulses to be counted are fed to pin P3.4. Assume an XTAL frequency of 4MHz.
- 3. (a) Two numbers are stored in registers R0 and R1. Verify if their sum is greater than FFH.
 - (b) Write programs to (i). add two 16-bit numbers, the numbers are FC45H and 02ECH, and (ii). Add two 32-bit numbers stored in RAM locations.
- **4.** (a) In a semester, a student has to take six courses. The marks of the student (out of 25) are stored in RAM locations 47H onwards. Find the average marks, and output it on port l.

(b) Ten hex numbers are stored in RAM locations 50H onwards. Write a program to find the biggest number in the set. The biggest number should finally be saved in 60H.

- 5. (a) Write the assembly code for Intelligent Traffic Light Controllers QTLC) at Zebra Crossing.(b) Design an Auto Toll Billing System.
- **6.** (a) Design a system using AT89S51, ADC0848, LM34135, LM336 & POT 10K for reading the output of temperature sensor.

(b) Write assembly code to control the speed of DC and Stepper motors.

- 7. Generate a square wave with an ON time of 4ms and an OFF time of 10ms on all pins of Port 0. Assume an XTAL frequency of 4MHz.
- 8. Design a microcontroller based embedded system for agricultural surveillance.
- 9. Design a system using AT89S51, ADC0848, LM34135, LM336 & POT 10K for reading the output of temperature sensor.
- 10. (a) Design a system using AT89S51, DS 1887 & 1C7400 and assemble code to control the buzzer.(b) Write assembly code to control the speed of DC and Stepper motors.
- 11. Design a microcontroller based embedded system for smart power grids.
- 12. Write a assemble program to generate saw tooth wave & triangular wave using DAC.

Reference Books:

1. 8051 Microcontroller and Embedded Systems using Assembly and C, 3/E by Muhammad Ali Mazidi, Pearson Publications.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars

CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #					Program Outcomes						
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	3	3	2	3	3	3	2	3	3
CO2	2	3	3	2	2	3	3	3	3	3	3
CO3	3	2	3	3	2	3	3	3	2	3	3
CO4	3	3	3	3	2	3	3	3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

	Mapping Between COs and Course Delivery (CD) methods						
CD	Course Delivery methods	Course Outcome	Course Delivery Method				
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1	CD1				
CD2	Tutorials/Assignments	CO2	CD1				
CD3	Seminars	CO3	CD1 and CD2				
CD4	Mini projects/Projects						
CD5	Laboratory experiments/teaching aids						
CD6	Industrial/guest lectures						
CD7	Industrial visits/in-plant training						
CD8	Self- learning such as use of NPTEL materials and internets						
CD9	Simulation						

Lecture wise Lesson planning Details.

Week No.	Lect No.	Tentativ e Date	Ch. No	Topics to be covered	Text Book / Refere nces	COs mapp ed	Actual Conten t covere d	Methodolog y used	Remark s by faculty if any
1	L1		5,6	Demonstration of Experiments	R1	1, 2	u	PPT Digi Class/Chock -Board	
	L2		9,1 0	Demonstration of Experiments	R1	1, 2		-do-	
	L3		14, 15	Demonstration of Experiments	R1	1, 2		-do-	
2	L4		5	Experiment 1	R1	1, 2		-do-	
	L5		5	Experiment 1	R1	1, 2		-do-	
	L6		5	Experiment 1	R1	1, 2		-do-	
3	L7		5	Experiment 2	R1	1, 2		-do-	
	L8		5	Experiment 2	R1	1, 2		-do-	
	L9		5	Experiment 2	R1	1, 2		-do-	
4	L10		6	Experiment 3	R1	1, 2		-do-	
	L11		6	Experiment 3	R1	1, 2		-do-	
	L12		6	Experiment 3	R1	1, 2		-do-	
5	L13		6	Experiment 4	R1	1, 2		-do-	
	L14		6	Experiment 4	R1	2, 3		-do-	
	L15		6	Experiment 4	R1	2, 3		-do-	
6	L16		6	Experiment 5	R1	2, 3		-do-	
	L17		6	Experiment 5	R1	2, 3		-do-	
	L18		6	Experiment 5	R1	2, 3		-do-	
7	L19		9	Experiment 6	R1	2, 3		-do-	
	L20		9	Experiment 6	R1	2, 3		-do-	
	L21		9	Experiment 6	R1	2, 3		-do-	
8	L22		9	Experiment 7	R1	2, 3		-do-	
	L23		9	Experiment 7	R1	2, 3		-do-	
	L24		9	Experiment 7	R1	2, 3		-do-	
9	L25		13	Experiment 8	R1	2, 3		-do-	
	L26		13	Experiment 8	R1	2, 3		-do-	
	L27		13	Experiment 8	R1	2, 3		-do-	
10	L28		13	Experiment 9	R1	2, 3		-do-	
	L29		13	Experiment 9	R1	2, 3		-do-	

	L30	13	Experiment 9	R1	2, 3	-do-
11	L31	14	Experiment 10	R1	3, 4	-do-
	L32	14	Experiment 10	R1	3, 4	-do-
	L33	14	Experiment 10	R1	3, 4	-do-
12	L34	15	Experiment 11	R1	3, 4	-do-
	L35	15	Experiment 11	R1	3, 4	-do-
	L36	15	Experiment 11	R1	3, 4	-do-
13	L37	15	Experiment 12	R1	4	-do-
	L38	15	Experiment 12	R1	4	-do-
	L39	15	Experiment 12	R1	4	-do-
14	L40	10	Examination	R1	4	-do-

Name of the Subject: Optoelectronic Instrumentation Lab Course Code: EC573 Course Title: Optoelectronic Instrumentation Lab Pre-requisite(s): Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 01 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students:

A.	To understand the Losses in optical Fiber
В.	To Characteristics of optical fiber source and detector
C.	To understand the analog, Digital TDM, WDM Mux and DMUX
D.	To understand the various fiber optic sensors

Course Outcomes

After the completion of this course, students will be able to:

CO1	Compute the Losses in optical Fiber
CO2	Compute the parameters of optical source and detector
CO3	Demonstrate the analog, Digital TDM, WDM Mux and DMUX
CO4	Demonstrate the various fiber optic sensors

List of Compulsory experiments:

1. To measure attenuation of optical fiber.

- 2. To measure Numerical Aperture (NA) of a multimode fiber using He-Ne Laser source.
- 3. To visualize fiber modes using He-Ne laser.
- 4. To measure coupling losses due to
 - a) Lateral offset
 - b) Angular Offset and
 - c) Longitudinal Offset
- 5. To demonstrate analog TDM and digital TDM in fiber optic link.
- 6. To demonstrate Interferometric Fiber Optic sensor.
- 7. To demonstrate Wavelength Division Multiplexing and Demultiplexing in optical fiber system.
- 8. To measure gain of Erbium doped fiber amplifier.
- 9. To measure strain using fiber Bragg grating sensor.
- 10. To determine the beat length of an elliptical core fiber.
- 11. To implement Mach-Zehnder Electro-Optic Modulator.
- 12. To determine output characteristics of laser diode and spectral response of photodiode.

Text Books:

- 1. Amar K. Ganguly., "Optical and optoelectronic Instrumentation", Narosa Press, 2010
- 2. Keiser G., Optical Fiber Communication, McGraw-Hill. d.

Reference Book:

- 1. John F. Read, Industrial Applications of Lasers, Academic Press.
- 2. Dr. M N Avadhanulu & Dr. R S Hemne, An Introduction to Lasers- Theory and Applications, S. Chan
- 3. John and Harry, Industrial Lasers and their Applications, Mc-Graw Hill, 1974.
- 4. Monte Ross, Laser Applications, McGraw-Hill

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
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Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #	Program Outcomes										
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	3	3	2	3	3	3	2	3	3
CO2	2	3	3	2	2	3	3	3	3	3	3
CO3	3	2	3	3	2	3	3	3	2	3	3
CO4	3	3	3	3	2	3	3	3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

	Mapping Between COs and Course Delivery (CD) methods							
CD	Course Delivery methods	Course Outcome		Course Delivery Method				
CD1	Lecture by use of boards/LCD projectors/OHP projectors	0	CO1	CD1				
CD2	Tutorials/Assignments	0	CO2	CD1				
CD3	Seminars	0	203	CD1 and CD2				
CD4	Mini projects/Projects							
CD5	Laboratory experiments/teaching aids							
CD6	Industrial/guest lectures							
CD7	Industrial visits/in-plant training							
CD8	Self- learning such as use of NPTEL materials and internets							
CD9	Simulation							

Lecture wise Lesson planning Details.

Week	Lect	Tentativ	Ch.	Topics to be covered	Text	COs	Actual	Methodolog	Remark
No.		e	No		Book /	mapp	Conten	у	s by
	No.	Date			Refere	ed	t	used	faculty
					nces		covere		if any
							d		
1	L1		5,6	Demonstration of	T1, T2	1, 2		PPT Digi	
				Experiments				Class/Chock	
								-Board	
	L2		9,1	Demonstration of	T1, T2	1, 2		-do-	
			0	Experiments					
	L3		14,	Demonstration of	T1, T2	1, 2		-do-	
			15	Experiments					
2	L4		5	Experiment 1	T1, T2	1, 2		-do-	
				<u>^</u>					

	L5	5	Experiment 1	T1, T2	1, 2	-do-	
	L6	5	Experiment 1	T1, T2	1, 2	-do-	
3	L7	5	Experiment 2	T1, T2	1, 2	-do-	
	L8	5	Experiment 2	T1, T2	1, 2	-do-	
	L9	5	Experiment 2	T1, T2	1, 2	-do-	
4	L10	6	Experiment 3	T1, T2	1, 2	-do-	
	L11	6	Experiment 3	T1, T2	1, 2	-do-	
	L12	6	Experiment 3	T1, T2	1, 2	-do-	
5	L13	6	Experiment 4	T1, T2	1, 2	-do-	
	L14	6	Experiment 4	T1, T2	2, 3	-do-	
	L15	6	Experiment 4	T1, T2	2, 3	-do-	
6	L16	6	Experiment 5	T1, T2	2, 3	-do-	
	L17	6	Experiment 5	T1, T2	2, 3	-do-	
	L18	6	Experiment 5	T1, T2	2, 3	-do-	
7	L19	9	Experiment 6	T1, T2	2, 3	-do-	
	L20	9	Experiment 6	T1, T2	2, 3	-do-	
	L21	9	Experiment 6	T1, T2	2, 3	-do-	
8	L22	9	Experiment 7	T1, T2	2, 3	-do-	
	L23	9	Experiment 7	T1, T2	2, 3	-do-	
	L24	9	Experiment 7	T1, T2	2, 3	-do-	
9	L25	13	Experiment 8	T1, T2	2, 3	-do-	
	L26	13	Experiment 8	T1, T2	2, 3	-do-	
	L27	13	Experiment 8	T1, T2	2, 3	-do-	
10	L28	13	Experiment 9	T1, T2	2, 3	-do-	
	L29	13	Experiment 9	T1, T2	2, 3	-do-	
	L30	13	Experiment 9	T1, T2	2, 3	-do-	
11	L31	14	Experiment 10	T1, T2	3, 4	-do-	
	L32	14	Experiment 10	T1, T2	3, 4	-do-	
	L33	14	Experiment 10	T1, T2	3, 4	-do-	
12	L34	15	Experiment 11	T1, T2	3, 4	-do-	
	L35	15	Experiment 11	T1, T2	3, 4	-do-	
	L36	15	Experiment 11	T1, T2	3, 4	-do-	
13	L37	15	Experiment 12	T1, T2	4	-do-	

	L38	15	Experiment 12	T1, T2	4	-do-	
	L39	15	Experiment 12	T1, T2	4	-do-	
14	L40	10	Examination	T1, T2	4	-do-	

III-Semester

COURSE INFORMATION SHEET

Name of the Subject: Industrial Instrumentation Course Code: EC609 Course Title: Industrial Instrumentation Pre-requisite(s): EC518 Advanced Instrumentation System Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	Explain the role of instrumentation in Industrial Automation and Control
В.	To classify the various control schemes used in industry for process control
C.	To discuss the working of PLC and CNC machines for controlling various Industrial
	processes
D.	To outline the construction and working of commonly used Actuators and Control Elements
	in industry and to state and outline the networking of sensors and actuators.

Course Outcomes:

After the completion of this course, students will be:

CO1	Explain the role of various instruments used in process industry.
CO2	Analyze the select suitable control scheme for controlling a given process.
CO3	Demonstrate the working of PLC and CNC machines.
CO4	Will be able to suggest the suitable actuator and valve for give control action and Architect
	and design networking of sensors and actuators on field bus

SYLLABUS

Module -1:

Industrial Instrumentation:

Introduction to Industrial Automation and Control, Architecture, Sensors for Industrial measurement Measurement of Temperature, Pressure, Force, Displacement, Speed, Flow, Level, Humidity and PH. Signal conditioning and processing, Estimation of Errors and Calibration

Module -2:

Process Control:

On /off control, PID control, Controller Tuning, Implementation of PID Controllers, feed forward control, ratio control, Predictive Control, Control of Systems with Inverse Response, Cascade Control, Overriding Control, Selective Control, Split Range Control

Module -3:

Programmable Logic Controller:

Introduction to Sequence Control, PLCs and Relay Ladder Logic, PLC Architecture, Scan Cycle, Structured Design Approach, RLL syntax and programming. Hardware, CNC Machine tools

Module -4: Actuators and Final Control Elements:

Flow control valves, Hydraulic actuators, Pumps and Motors, Servo valves, Pneumatic, controllers, Electric drives, DC motor drives, Induction motor drives, adjustable speed and servo drives.

Module -5:

Introduction to Field bus Network:

Networking of sensors, Actuators and field bus, Communication protocol, Production control

Text Books:

- 1. Industrial Instrumentation, Control and Automation, S. Mukhopadhyay, S.Sen and A.K. Deb, Jaico Publishing House
- 2. Electric Motor Drives, Modelling, Analysis and Control, R.Krishnan, Prentice Hall India,
- 3. Hydraulic Control Systems, Herbert E. Merritt, Wiley

Reference Book:

- 1. Process control Instrumentation Technology by CD Johnson, PHI Learning
- D. M. Considine, Process/Industrial Instruments and Control Handbook, Fourth Edition, McGraw-Hill Inc., 1993.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, **2** for fulfilling less than 70% and **3** for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #	Program Outcomes										
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
C01	3	3	2	3	2	3	3	3	2	3	3
CO2	2	2	2	2	2	3	3	3	3	3	3
CO3	3	2	3	3	2	3	3	3	2	3	3
CO4	3	3	3	3	2	3	3	3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Mapping Between COs and Course Delivery (CD) methods						
CD	Course Delivery methods	Course Outcome	Course Delivery Method			
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1			
CD2	Quizzes	CO1, CO2, CO3	CD2			
CD3	Assignments/Seminars	CO3	CD3			
CD4	Mini projects/Projects					
CD5	Laboratory experiments/teaching aids					
CD6	Industrial/guest lectures					
CD7	Industrial visits/in-plant training					
CD8	Self- learning such as use of NPTEL materials and internets					
CD9	Simulation					

Lecture Wise Lesson Planning Details:

Week No.	Lect. No.	Tentat ive Date	Ch. No.	Topics to be covered	Text Book / Refer e nces	COs mapped	Actual Content covered	Methodolo gy used	Remar ks by faculty if any
1	L1			Explain the syllabus if detail, list course objectives and outcomes.	T1			PPT Digi Class/Choc k -Board	
	L2			Introduction to Industrial Automation and Control	T1			do	
	L3			Architecture of Industrial Automation Systems	T1			do	
2	L4			Introduction to sensors and measurement systems, Temperature measurement	T1			do	
	L5			Pressure, Force, and Displacement measurements	T1			do	
	L6			speed measurement, Flow Measurement	T1			do	
3	L7			Measurement of level, humidity, pH	T1			do	

	L8	Signal Conditioning and Processing	T1	do
	L9	Estimation of errors and Calibration	T1	do
4	L10	Introduction to Process Control, Control Schemes	T2	do
	L11	P I D Control	T2	do
	L12	Controller Tuning	T2	do
5	L13	Implementation of PID Controllers	T2	do
	L14	Feedforward and Ratio Control	T2	do
	L15	Predictive Control,	T2	do
6	L16	Control of Systems with Inverse Response	T2	do
	L17	Cascade Control, Overriding Control,	T2	do
	L18	Selective Control, Split Range Control	T2	do
7	L19	Introduction to Sequence Control, PLCs and Relay Ladder Logic,	T2	do
	L20	PLC Architecture,	T2	do
	L21	Scan Cycle, RLL Syntax	T2	do
8	L22	Structured Design Approach	T2	do
	L23 RLL Programming Examples		T2	do
	L24	RLL Programming Examples ctd.	T2	do
9	L25	Introduction to CNC Machines tools	T2	do
	L26	Analysis of a control loop	T2	do
	L27	Analysis of a control loop cts	T2	do
10	L28	Introduction to Actuators	T2	do
	L29	Flow Control Valves	T2	do
	L30	Hydraulic Actuator Systems	T2	do
11	L31	Pumps and Motors	T2	do
	L32	Proportional and Servo Valves	T2	do
	L33	Pneumatic Control Systems	T2	do
12	L34	Electric Drives : Introduction, Energy Saving with Adjustable Speed Drives	T2	do
	L35	Step motors : Principles, Construction and Drives	T2	do
	L36	AC Motor Drives and Adjustable speed Drives	T2	do
13	L37	The Fieldbus System	T3	do
	L38	Networking of Sensors	T3	do
	L39	Actuators and Controllers	T3	do
14	L40	The Fieldbus Communication Protocol	T3	do
	L41	Introduction to Production control System	T3	do
	L42	Concluding Lecture	T3	do

Name of the Subject: Biomedical Signal Processing Course Code: EC610 Course Title: Biomedical Signal Processing Pre-requisite(s): EC522 Advanced Digital Signal Processing Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objectives

This course enables the students:

1	Understand the fundamentals of Digital Signal Processing and Biomedical Signal
	Processing.
2	Grasp the concept of stochastic processes to develop advanced Biomedical signal
	processing concept.
3	Comprehend Digital Signal Processing and Biomedical Signal Processing.
4	Grasp how to integrate the concept of matrix algebra, probability models, random processes
	and linear algebra to Separate information Source using Spatial filters.

Course Outcomes

After the completion of this course, students will be able to:

CO1.	Distinguish Digital Signal Processing and Biomedical Signal Processing.
CO2.	Use the concept of stochastic processes to develop advanced Biomedical signal processing
	concept.
CO3.	Analyse Biomedical signals using PCA, BSS and ICA to separate or decorrelate the
	Multichannel Biomedical Signal.
CO4.	Integrate the concept of matrix algebra, probability models, random processes and linear
	algebra to develop Spatial filters for pattern classification.

SYLLABUS

Module-1

Acquisition, Generation of Bio-signals, Origin of bio-signals, Types of bio-signals, Study of diagnostically significant bio-signal parameters, Electrodes for bio-physiological sensing and conditioning, Electrodeelectrolyte interface, polarization, electrode skin interface and motion artefact, biomaterial used for electrode, Types of electrodes (body surface, internal, array of electrodes, microelectrodes), Practical aspects of using electrodes, Acquisition of bio-signals (signal conditioning) and Signal conversion (ADC's DAC's) Processing, Digital filtering

Module-2

Biomedical signal processing by Fourier analysis, Biomedical signal processing by wavelet (time frequency) analysis, Analysis (Computation of signal parameters that are diagnostically significant)

Module-3

Classification of signals and noise, Spectral analysis of deterministic, stationary random signals and nonstationary signals, Coherent treatment of various biomedical signal processing methods and applications.

Module-4

Principal component analysis, Correlation and regression, Analysis of chaotic signals Application areas of Bio–Signals analysis Multiresolution analysis (MRA) and wavelets, Principal component analysis (PCA), Independent component analysis (ICA)

Module-5

Pattern classification-supervised and unsupervised classification, Neural networks, Support vector Machines, Hidden Markov models. Examples of biomedical signal classification examples.

References:

1. W. J. Tompkins, "Biomedical Digital Signal Processing", Prentice Hall, 1993.

2. Eugene N Bruce, "Biomedical Signal Processing and Signal Modeling", John Wiley & Son's publication, 2001.

3. Myer Kutz, "Biomedical Engineering and Design Handbook, Volume I", McGraw Hill, 2009._

4. D C Reddy, "Biomedical Signal Processing", McGraw Hill, 2005.

5. Katarzyn J. Blinowska, Jaroslaw Zygierewicz, "Practical Biomedical Signal Analysis Using MATLAB", 1st Edition, CRC Press, 2011.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Course					Progra	am Out	tcomes				
Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	2	2	3	1	1	1	1	1	2	3	3
CO2	3	3	3	1	2	2	2	2	2	3	3
CO3	3	3	3	2	2	2	2	2	2	3	3
CO4	3	3	3	2	2	2	2	2	2	3	3

Mapping of Course Outcomes onto Program Outcomes

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

	Mapping Between COs and Course Delivery (CD) methods							
CD	Course Delivery methods	Course Outcome	Course Delivery Method					
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1	CD1					
CD2	Tutorials/Assignments	CO2	CD1					
CD3	Seminars	CO3	CD1 and CD2					
CD4	Mini projects/Projects							
CD5	Laboratory experiments/teaching aids							
CD6	Industrial/guest lectures							
CD7	Industrial visits/in-plant training							
CD8	Self- learning such as use of NPTEL materials and internets							
CD9	Simulation							

Lecture Wise Lesson Planning Details.

Week	Lect.	Tentative	Ch.	Topics	to	be	Text	COs	Actual	Methodology	Remarks
No.	No.	Date	No.	covered			Book /	mapped	Content	used	by
							Refere		covered		faculty
							nces				if any
1	L1		1	Acquisiti	on,			1		PPT Digi	
				Generatio	on of	Bio-				Class/Chock	
				signals,						-Board	
	L2		1	Origin	of	bio-		1		do	
				signals,	Types	s of					
				bio-signa	ıls,						
	L3		1	Study		of		1		do	
				diagnosti	cally						
				significar	nt	bio-					
				signal pa	ramet	ers,					
2	L4		1	Electrode	es for	bio-		1		do	
				physiolog	gical						

			sensing and conditioning,			
	L5	1	Electrode- electrolyte interface, polarization,	1	do	
	L6	1	electrode skin interface and motion artefact,	1	do	
3	L7	1	biomaterial used for electrode,	1	do	
	L8	1	Types of electrodes (body surface, internal, array of electrodes, microelectrodes),	1	do	
	L9	1	Practical aspects of using electrodes,	1	do	
4	L10	1	Acquisition of bio- signals (signal conditioning) and Signal conversion (ADC's DAC's) Processing,	1	do	
	L11	1	Digital filtering	2	do	
	L12	2	Biomedical signal processing by Fourier analysis,	2	do	
5	L13	2	Biomedical signal processing by Fourier analysis,	2	do	
	L14	2	Biomedical signal processing by wavelet (time frequency) analysis,	2	do	
	L15	2	Biomedical signal processing by wavelet (time frequency) analysis,	2	do	
6	L16	2	Biomedical signal processing by wavelet (time frequency) analysis,	2	do	
	L17	2	Analysis (Computation of signal parameters that are diagnostically significant)	2	do	
	L18	2	Analysis (Computation of signal parameters that are	2	do	

			diagnostically			
			significant)			
7	L19	2	Analysis (Computation of signal parameters that are diagnostically significant)	2	do	
	L20	3	Classification of signals and noise,	2	do	
	L21	3	Spectral analysis of deterministic, stationary random signals and non- stationary signals,	2	do	
8	L22	3	Spectral analysis of deterministic, stationary random signals and non- stationary signals,	2	do	
	L23	3	Coherent treatment of various biomedical signal processing methods and applications.	2	do	
	L24	3	Coherent treatment of various biomedical signal processing methods and applications.	2	do	
9	L25	4	Principal component analysis, Correlation and regression,	3	do	
	L26	4	Analysis of chaotic signals Application areas of Bio–Signals analysis Multiresolution analysis (MRA) and wavelets,	3	do	
	L27	4	Analysis of chaotic signals Application areas of Bio–Signals analysis Multiresolution analysis (MRA) and wavelets,	3	do	
10	L28	4	Principal component analysis (PCA),	3	do	

	L29	4	Dringing	3	do	
	L29	4	Principal component	3	do	
	1.20	4	analysis (PCA),	3	do	
	L30	4	Principal	3	do	
			component			
			analysis (PCA),			
11	L31	4	Independent	3	do	
			component			
			analysis (ICA)			
	L32	4	Independent	3	do	
			component			
			analysis (ICA)			
	L33	4	Independent	3	do	
			component			
			analysis (ICA)			
12	L34	5	Pattern	4	do	
			classification-			
			supervised and			
			unsupervised			
			classification,			
	L35	5	Pattern	4	do	
			classification-			
			supervised and			
			unsupervised			
			classification,			
	L36	5	Neural networks,	4	do	
13	L37	5	Neural networks,	4	do	
	L38	5	Neural networks,	4	do	
		_	,			
	L39	5	Support vector	4	do	
			Machines,			
14	L40	5	Support vector	4	do	
			Machines,			
	L41	5	Support vector	4	do	
		-	Machines,			
	L42	5	Hidden Markov	4	do	
		5	models.			
15	L43	5	Hidden Markov	4	do	
15	113	5	models.	7		
	L44	5	Hidden Markov	4	do	
	L++	5	models.	7	uo	
			1100015.			
	L45	5	Examples of	4	40	
	L43	5	Examples of	4	do	
			biomedical signal			
			classification			
			examples.			

Pre-requisite(s): Fundamental of Data Structure Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objective

This course enables the students to:

A.	Define the concept of the virtual instruments
В.	Analyse the analogue and digital measurement principles
C.	Show the data acquisition operations using LabVIEW
D.	Develop the components of the virtual instruments and the suitable graphical program for practical applications
	practical applications

Course Outcomes

After the completion of this course, students will be able to:

1.	Explain the concept of virtual instrument and components
2.	Recognize the dataflow in the graphical programming environment
3.	Determine the device driver and interface buses to interface an instrument
4.	Create the graphical program using LabVIEW for any application

SYLLABUS

Module -1:

Introduction to Virtual Instrument:

Introduction and Historical perspective, Need of VI, Define VI, Advantages of VI Block diagram & architecture of VI, Data flow techniques, Graphical programming in data flow, Comparison with conventional programming.

Module -2:

Graphical programming components

VIS and sub-VIS, Creating sub-VI, Loops, Case structure sequence structures, formula nodes Arrays, Clusters, charts, graphs String & file input and output graphical Programming in data flow.

Module -3:

Data Acquisition Basics:

Data Acquisition, ADC, DAC, DIO, Counters and timers, Timing, Interrupts, DMA, MAX, NI-DAQmx, PXI, RTSI, SCC, SCXI, SISTA USB, RS232C/ RS485, VISA, GPIB System buses, Interface buses, Analog and Digital I/O, NI-DAQmx Tasks, DAQmx Timing and Trigger, Networking basics, VISA

Module -4:

Advanced LabVIEW Structures and Functions

Local, Global, and Shared Variables, Property Nodes, Invoke Nodes, Event-Driven Programming: The Event Structure, Type Definitions, The State Machine and Queued Message Handler, Messaging and Synchronization, Structures for Disabling Code.

Module -5: Applications Applications of VI. Advanced analysis tools, Correlation methods, windowing & filtering, Application in Process Control projects, Data Visualization, Imaging, and Sound, embedding LabVIEW for Linux in a Virtual Machine

Text books:-

- 1. LabVIEW for Everyone: Graphical Programming Made Easy and Fun, Third Edition, By Jeffrey Travis, Jim Kring.
- 2. Hands-On Introduction to LabVIEW for Scientists and Engineers, Third Edition John Essick
- 3. LABVIEW Graphical Programming, by Gary Johnson, McGraw Hill, 1997, 2nd Edition.

Reference books:-

1. S. Gupta, J.P. Gupta, PC Interfacing for Data Acquisition and Process Control, ISA, 1994, 2nd Edition

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome <u>Mapping between Objectives and Outcomes</u>

Course Outcome #					Prog	gram Ou	itcomes				
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	3	2	3	1	2	2	1	1	2
CO2	3	3	3	3	3	1	1	1	1	1	2
CO3	3	3	2	2	3	2	2	2	1	2	2
CO4	3	3	2	2	3	1	2	1	2	2	2

Mapping of Course Outcomes onto Program Outcomes

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

	Mapping Between COs and Course Deli	very (CD) metho	ods
CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3	CD1
CD1 CD2	Tutorials/Assignments	CO3, CO4	CD1
CD3	Seminars	CO4	CD1 and CD2
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets	CO4	
CD9	Simulation		

Lecture wise Lesson planning Details.

Week	Lect	Tentativ	Ch.	Topics to be covered	Text	COs	Actual	Methodology	Remarks	;
No.		e	No		Book /	map	Content	used	by	
	No.	Date			Refere	ped	covered		faculty	if
					nces				any	
1	L1			Illustration of course				PPT Digi		
				objectives and course				Class/Chock		
				outcomes, besides				-Board		
				detailed introduction						
				of the course syllabus						
	L2		1,2	Introduction and	T1	1, 2		-do-		
				Historical						
				perspective, Need of						
				VI,						
	L3		1,2	Define VI,	T1	1, 2		-do-		
				Advantages of VI						
2	L4		1,3	Block diagram &	T1	1, 2		-do-		
				architecture of VI,						
	L5		1,3	Data flow	T1	1, 2		-do-		
				techniques,						
				Graphical						
				programming in data						
				flow,						

	L6	1	Comparison with conventional	T1	1, 2	-do-
2			programming.	T 1		
3	L7	3,4	VIS and sub-VIS,	T1	1, 2	-do-
	L8	5	Creating sub-VI	T1	1, 2	-do-
	L9	6	Loops, Case structure	T1	1, 2	-do-
4	L10	6	sequence structures, formula nodes	T1	1, 2	-do-
	L11	7	Arrays, Clusters	T1	1, 2	-do-
	L12	7	Arrays, Clusters	T1	2, 3	-do-
5	L13	8	charts, graphs	T1	2, 3	-do-
	L14	8	charts, graphs	T1	2, 3	-do-
	L15	9	String & file input and output graphical Programming in data flow.	T1	2, 3	-do-
6	L16	2, 10	Data Acquisition, ADC, DAC, DIO	T1	2, 3	-do-
	L17	10, 6	Counters and timers,	T1	2, 3	-do-
	L18	10, 6	Timing, Interrupts, DMA, MAX, NI- DAQmx, PXI, RTSI	T1	2, 3	-do-
7	L19	10, 6	SCC, SCXI, SISTA USB, RS232C/ RS485, VISA	T1	2, 3	-do-
	L20	10	GPIB System buses, Interface buses	T1	2, 3	-do-
	L21	11	Analog and Digital I/O, NI-DAQmx Tasks,	T1	2, 3	-do-
8	L22	11	DAQmx Timing and Trigger	T1	2, 3	-do-
	L23	12	Networking basics, VISA	T1	2, 3	-do-
	L24	13	Local, Global, and Shared Variables,	T1	2, 3	-do-
9	L25	13	Property Nodes, Invoke Nodes,	T1	2, 3	-do-
	L26	13	Event-Driven Programming: The Event Structure,	T1	2, 3	-do-
	L27	13	Type Definitions,	T1	3,4	-do-
10	L28	13	The State Machine and Queued Message Handler,	T1	3, 4	-do-
	L29	13	Messaging and Synchronization,	T1	3, 4	-do-
	L30	13	Structures for Disabling Code.	T1	3, 4	-do-
11	L31	18	Applications of VI.	T2	3, 4	-do-
	L32	11	Advanced analysis tools,	T2	3, 4	-do-

	L33	11	Advanced analysis tools,	T2	3, 4	-do-
12	L34	11	Correlation methods,	T2	3, 4	-do-
	L35	11, 12	windowing & filtering,	T2	3, 4	-do-
	L36	11, 12	windowing & filtering,	T2	3, 4	-do-
13	L37	18	ApplicationinProcessControlprojects,	T3	3, 4	-do-
	L38	18	ApplicationinProcessControlprojects,	T3	3, 4	-do-
	L39	20	Data Visualization, Imaging, and Sound	T3	3, 4	-do-
14	L40	20	Data Visualization, Imaging, and Sound	T3	3, 4	-do-
	L41	22	Embedding LabVIEW for Linux in a Virtual Machine	T3	3, 4	-do-
	L42	22	Embedding LabVIEW for Linux in a Virtual Machine	T3	3, 4	-do-

Name of the Subject: Instrumentation System design Course Code: EC612 Course Title: Instrumentation System design Pre-requisite(s): EC518 Advanced Instrumentation System (AIS) Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	Explain the concept and need of Signal Conditioning and impart knowledge on the designing
	of signal conditioning circuit for different application.
B.	To state the design of signal conditioners for different applications
C.	To framework the design of DAS, DATA Loggers and transmitters
D.	To discuss the design of analog and digital controllers and alarm generators and design
	various actuators and final control element.

Course Outcomes:

After the completion of this course, students will be:

CO1	Explain the working of instrumentation systems for the measurement and control of any
	process variable.
CO2	Able to design the signal conditioning circuit for given application.

CO3	Architect and design DAS, DATA Loggers and transmitter
CO4	Able to identify suitable control scheme for given process and design the controller for the
	given requirement and select appropriate actuator according to the process requirement.

SYLLABUS

Module -1:

Introduction to Instrumentation System Design:

Review of Instrumentation System, Sensing Elements, and Signal Conditioners, Transmitters, and Data presentation, Controllers, Actuators and Final Control Elements. Instrumentation system for measuring: Temperature, Level, Pressure and flow.

Module -2:

Design of Signal Conditioners:

Principles of signal conditioning, signal level and bias change, linearization, conversion, filtering and impedance matching, loading, Design of passive signal conditioners, Bridge circuits, RC filters, Design of active signal conditioners, OPAMPS circuits, Design of digital signal conditioners, Comparator, Bipolar DAC, ADC, S/H for different applications.

Module -3:

Design of Data Acquisition system and Data loggers and transmitters:

Design of Microprocessor/microcontroller based DAS and DATA logger, Two wire and 4 wire transmitters, temperature transmitters, Level transmitters, pressure transmitters, flow transmitters, Design of Smart transmitters.

Module -4:

Design and of controllers:

Design of on/off controller using OPAMP, design of Microprocessor/Microcontroller based PID controller, Design of Alarm and Annunciation circuits, Design of PLC, Design of configurable sequential controller using PLDs.

Module -5:

Design of Actuators and Final control elements:

Comparison of Pneumatic, Hydraulic and Electrical/Electronic instrumentation systems and their selection for present process industry requirement, Control Valve and their Selection, Pumps, Motors,

Text Books:

- 1. Process control Instrumentation Technology by CD Johnson, PHI Learning
- 2. John P. Bentley, Principles of Measurement Systems, Addison-Wesley publication,
- 3. T. R. Padmanabhan, Industrial Instrumentation: Principles and Design, Springer-Verlag Publications

Reference Book:

- 1. B. G. Liptak, Instrument Engineers Handbook, Vol. I and II, Third Edition, Chilton and Book Company, 1990.
- 2. D. M. Considine, Process/Industrial Instruments and Control Handbook, Fourth Edition, McGraw-Hill Inc., 1993.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
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CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, **2** for fulfilling less than 70% and **3** for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome #					Prog	ram Ou	itcomes				
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	3	2	3	1	2	2	1	1	2
CO2	3	2	3	3	3	1	1	1	1	1	2
CO3	3	2	2	2	3	2	2	2	1	2	2
CO4	3	3	2	2	3	1	2	1	2	2	2

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Mapping Between COs and Course Delivery (CD) methods

CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1
CD2	Quizzes	CO1, CO2, CO3	CD2
CD3	Assignments/Seminars	CO3	CD3
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets		
CD9	Simulation		

Lecture Wise Lesson Planning Details:

Week	Lect	Tentative	Ch.	Topics to be covered	Text	COs	Actual	Method	Remar
No.		Date	No		Book /	mapped	Content	ology	ks by
	No.				Refere		covered	used	faculty
					nces				if any
1	L1			Discuss the syllabus,	T1			PPT	
				list the various course				Digi	
				objectives and				Class/C	
				outcomes				hock	
								-Board	
	L2			Review of	T1			do	
				Instrumentation					
				System, Sensing					
	.			Elements				1	
	L3			Signal Conditioners	T1			do	
-	T 4			T '44 1	TT 1				
2	L4			Transmitters, and	T1			do	
	1.7			Data presentation,	TT 1				
	L5			Controllers, Actuators and Final	T1			do	
				Control Elements.				•••	
	L6			Control Elements.	T1			do	
	LO			Actuators and Final	11				
				Control Elements.				•••	
3	L7			Instrumentation	T1			do	
5	L/			system for measuring	11				
				Temperature,				•••	
	L8			Instrumentation	T1			do	
	20			system for measuring	11			40	
				Level and Pressure					
	L9			Instrumentation	T1			do	
				system for measuring					
				flow					
4	L10			Principles of signal	T1			do	
				conditioning, signal					
				level and bias change,					
	L11			linearization,	T1			do	
				conversion,					
	L12			filtering and	T1			do	
				impedance matching,					
				loading,					

-				
5	L13	Design of passive	T1	do
		signal conditioners,		
		Bridge circuits, RC		
		filters,		
	L14	Design of active	T1	do
		signal conditioners,		
		OPAMPS circuits,		
	L15	Design of digital	T1	do
	210	signal conditioners, ,	•••	
6	L16	Comparator,	T1	do
0	210	Implementation of	11	
		Boolean functions		
	L17		T1	do
	L1/	Design of Bipolar	11	do
		DAC		
	L18	ADC, S/H for	T1	do
		different applications		
7	L19	Microprocessor/micr		do
		ocontroller based		
		DAS		
	L20	Design of		do
		Microprocessor/micr		
		ocontroller based		
		DAS and DATA		
		logger,		
	L21	Design of		do
	LZI			do
		Microprocessor/micr		
		ocontroller based		
		DAS and DATA		
		logger contd.		
8	L22	Two wire and 4 wire		do
		transmitters		
	L23	temperature		do
		transmitters,		
	L24	Level transmitters,		do
9	L25	pressure transmitters,		do
-				
	L26	flow transmitters,		do
	1.27	Design of Sugart		da
	L27	Design of Smart		do
10		transmitters		1
10	L28	Design of on/off		do
		controller using		
		OPAMP,		
	L29	design of		do
		Microprocessor/Micr		
		ocontroller based PID		
		controller		
	L30	design of		do
		Microprocessor/Micr		
		ocontroller based PID		
		controller contd.		
11	I 21		<u> </u>	
11	L31	Design of Alarm and		do
		Annunciation		
		circuits,		
	L32	Design of PLC		do

	L33	Design of PLC contd.	do
12	L34	Design of PLC contd.	do
	L35	Design of	do
		configurable	
		sequential controller	
		using PLDs	
	L36	Design of	do
		configurable	
		sequential controller	
		using PLDs contd.	
13	L37	Comparison of	do
		Pneumatic, Hydraulic	
		and	
		Electrical/Electronic	
		instrumentation	
		systems and their	
		selection for present	
		process industry	
		requirement,	
	L38	Pneumatic Cylinders	do
	L39	Relays and Solenoids	do
14	L40	Control Valve and	do
		their Selection,	
	L41	Pumps,	do
	L42	Motors	do

Name of the Subject: Applied Industrial Instrumentation Course Code: EC613 **Course Title: Applied Industrial Instrumentation** Pre-requisite(s): EC313 Electronic Measurement, EC377 sensor and Transducer **Co-requisite(s): Credits:** L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 **Branch: ECE** Name of Teacher: **Course Objectives:** This course enables the students:

А.	Explain the role of instrumentation in Industrial Automation and Control
B.	To classify the various control schemes used in industry for process control
C.	To discuss the working of PLC and CNC machines for controlling various Industrial
	processes
D.	To outline the construction and working of commonly used Actuators and Final Control
	Elements in industry.
E.	To state and outline the networking of sensors and actuators.

Course Outcomes:

After the completion of this course, students will be:

CO1	Explain the role of various instruments used in process industry.
CO2	Analyze the select suitable control scheme for controlling a given process.
CO3	Demonstrate the working of PLC and CNC machines.
CO4	Will be able to suggest the suitable actuator and valve for give control action.
CO5	Architect and design networking of sensors and actuators on field bus

SYLLABUS

Module -1:

Industrial Instrumentation:

Introduction to Industrial Automation and Control, Architecture, Sensors for Industrial measurement, Measurement of Temperature, Pressure, Force, Displacement, Speed, Flow, Level, Humidity and PH. Signal conditioning and processing, Estimation of Errors and Calibration.

Module -2:

Process Control:

On /off control, PID control, Controller Tuning, Implementation of PID Controllers, feed forward control, ratio control, Predictive Control, Control of Systems with Inverse Response, Cascade Control, Overriding Control, Selective Control, Split Range Control

Module -3:

Programmable Logic Controller:

Introduction to Sequence Control, PLCs and Relay Ladder Logic, PLC Architecture, Scan Cycle, Structured Design Approach, RLL syntax and programming. Hardware, CNC Machine tools

Module -4:

Actuators and Final Control Elements:

Flow control valves, Hydraulic actuators, Pumps and Motors, Servo valves, Pneumatic controllers, Electric drives, DC motor drives, Induction motor drives, adjustable speed and servo drives.

Module -5:

Introduction to Field bus Network:

Networking of sensors, Actuators and field bus, Communication protocol, Production control

Text Books:

- 1. Industrial Instrumentation, Control and Automation, S. Mukhopadhyay, S.Sen and A.K. Deb, Jaico Publishing House
- 2. Electric Motor Drives, Modelling, Analysis and Control, R.Krishnan, Prentice Hall India,
- 3. Hydraulic Control Systems, Herbert E. Merritt, Wiley

Reference Book:

- 1. Process control Instrumentation Technology by CD Johnson, PHI Learning
- 2. D. M. Considine, Process/Industrial Instruments and Control Handbook, Fourth Edition, McGraw-Hill Inc., 1993.

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
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CDM 2	Quizzes
CDM 3	Assignments/Seminars

CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

					Progra	am Outc	omes				
Course Outcome #	DO1	DOG	DO2	DO 4	DOS	DOC	D07	DOO	DOG	DO 10	DO11
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	2	1	1		1	1	1	1	1	1
CO2	3	3	1	2		1	2	2	1	1	1
CO3	3	3	2	2		1	2	2	2	1	1
CO4	3	3	2	2	1	2	2	2	2	2	2

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Mapp	Mapping Between COs and Course Delivery (CD) methods					
CD	Course Delivery methods	Course Outcome	Course Delivery Method			
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO1, CO2, CO3, CO4	CD1			

CD2	Quizzes	CO1, CO2, CO3	CD2		
CD3	Assignments/Seminars	CO3	CD3		
CD4	Mini projects/Projects				
CD5	Laboratory experiments/teaching aids				
CD6	Industrial/guest lectures				
CD7	Industrial visits/in-plant training				
CD8	Self- learning such as use of NPTEL materials and internets				
CD9	Simulation				

Lecture Wise Lesson Planning Details:

Week	Lect.	Tentative	Ch.	Topics to be	Text	COs	Actual	Methodology	Remarks
No.	No.	Date	No.	covered	Book / Refere nces	mapped	Content covered	used	by faculty if any
1	L1				T1			PPT Digi Class/Chock -Board	
	L2			Introduction to Industrial Instrumentation	T1			do	
	L3			Measurement of Force.	T1			do	
2	L4			Measurement of Torque	T1			do	
	L5			Measurement of Velocity, Acceleration,	T1			do	
	L6			Measurement of Pressure	T1			do	
3	L7			Measurement of, Temperature	T1			do	
	L8			Measurement of Flow, Level,	T1			do	
	L9			Measurement of Viscosity, Humidity & Moisture	T1			do	
4	L10			Measurements in thermal power plant	T2			do	
	L11			Installation and maintenance of Instruments used for the measurement of fuel flow, Air flow, Drum level in thermal power plant.	T2			do	
	L12			Installation and maintenance of Instruments used for the measurement of Steam pressure,	T2			do	

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$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	5	L13	Analyzers.	T2	do
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$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			processing		
		L20	Estimation of	T2	do
			Errors and		
		L.21		Т2	do
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$ \begin{array}{ c c c c c c c } \hline \begin{tabular}{ c c c c } \hline \end{tabular} \\ \hline \end{tabular}$		X 00			
$ \begin{array}{ c c c c c c } \hline \begin{tabular}{ c c c c } \hline \end{tabular} \\ \hline \end{tabular} \\$		L23		T2	do
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			-		
Image: second			Controllers		
9 L25 ratio control, Predictive Control T2 do L26 Control of Systems with Inverse Response T2 do L27 Cascade Control T2 do 10 L28 Overriding Control T2 do L29 Selective Control T2 do L30 Flow control valves T2 do 11 L31 Hydraulic actuators T2 do L33 Pneumatic T2 do		L24	feed forward	T2	do
Image: height of the system			control		
Image: height of the system	9	L25	ratio control,	T2	do
Image: Control Control Image: Control Control of Systems with Inverse Response T2 Image: Control of Systems with Inverse Response Image: Control Image: Control of Control of Control T2 Image: Control of Control of Control of Control T2 Image: Control of Control of Control of Control T2 Image: Control of Control of Control T2 Image: Control of Control of Control of Control T2 Image: Control of Control of Control of Control, Split Range Control T2 Image: Control of Control of Control of Control, Split Range Control T2 Image: Control of Cont					
$ \begin{array}{ c c c c c c c c } \hline L26 & & Control & of & T2 & & \dots & do \dots & \\ \hline Systems & with & Inverse & \\ \hline Response & & & & & & & & & & \\ \hline L27 & & Cascade Control & T2 & & \dots & do \dots & \\ \hline L28 & & Overriding & T2 & & \dots & do \dots & \\ \hline L29 & & Selective & T2 & & \dots & do \dots & \\ \hline L29 & & Selective & T2 & & \dots & do \dots & \\ \hline L30 & & Flow & control & T2 & & \dots & do \dots & \\ \hline 11 & L31 & & Hydraulic & T2 & & \dots & do \dots & \\ \hline L32 & & Pumps & and & Motors, & Servo & valves & & & & & & \\ \hline L33 & & Pneumatic & T2 & & \dots & do \dots & \\ \hline \end{array}$					
Image: L27 Image: Control Image: Co		L26		T2	do
Inverse Response Inverse Response<		120			
L27Response do10L28Overriding ControlT2 do10L28Overriding ControlT2 doL29Selective Control, Split Range ControlT2 doL30Flow control valvesT2 do11L31Hydraulic actuatorsT2 doL32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 doL33PneumaticT2 do			-		
L27Cascade ControlT2 do10L28Overriding ControlT2 doL29Selective Control, Split Range ControlT2 doL30Flow control valvesT2 do11L31Hydraulic actuatorsT2 doL32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 do					
10L28Overriding ControlT2 doL29Selective Control, Split Range ControlT2 doL30Flow control valvesT2 do11L31Hydraulic actuatorsT2 doL32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 do		1.07		T-2	 1.
L29ControlT2 doL29Selective Control, Split Range ControlT2 doL30Flow control valvesT2 do11L31Hydraulic actuatorsT2 doL32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 do	10				
L29Selective Control, Split Range ControlT2 Control, Split Range ControlT2 Control, Split Range Control doL30Flow control valvesT2 do11L31Hydraulic actuatorsT2 doL32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 do	10	L28		12	do
L30Control, Split Range ControlT2 do11L31Hydraulic actuatorsT2 doL32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 do					
Range ControlRange ControlL30Flow control valvesT211L31Hydraulic actuatorsT2L32Pumps Motors, Servo valvesT2L33PneumaticT2		L29			do
L30Range ControlT2 do11L31Hydraulic actuatorsT2 doL32Pumps Motors, Servo valvesT2 doL33PneumaticT2 do			Control, Split		
L30Flow control valvesT2 do11L31Hydraulic actuatorsT2 doL32Pumps Motors, Servo valvesT2 doL33PneumaticT2 do					
Image: space of the systemvaluestesttesttest11L31Hydraulic actuatorsT2 doL32Pumps Motors, Servo valuesT2 doL33PneumaticT2 do		L30		T2	do
11L31Hydraulic actuatorsT2 doL32Pumps Motors, Servo valvesT2 doL33PneumaticT2 do		-			
L32Pumps and Motors, Servo valvesT2 doL33PneumaticT2	11	L31		T2	do
L32Pumps and Motors, Servo valvesT2 doL33PneumaticT2 do	11	1.51		12	
Motors, Servo valves Servo ralves L33 Pneumatic		1.22		T2	
valves valves L33 Pneumatic T2 do		L32		12	do
L33 Pneumatic T2 do					
controllers		L33		T2	do
			controllers		

12	L34	Electric drives	T2	do
	L35	DC motor drives	T2	do
	L36	Induction motor drives	T2	do
13	L37	adjustable speed and servo drives		do
	L38	Networking of sensors	T3	do
	L39	Actuators and field bus	T3	do
14	L40	Communication protocol	T3	do
	L41	Production control	T3	do
	L42	Concluding Lecture	T3	do

Name of the Subject: Adaptive System and Signal Processing Course Code: EC614 Course Title: Adaptive Signal Processing Pre-requisite(s): EC 305 Signal Processing Techniques Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objectives:

This course aims is

1	To help to understand the concept of adaptive systems and its characteristics.
2	To impart knowledge on adaptive algorithms and adaptive filter for optimal control.
3	To help to understand the concept of adaptive filters such as LMS algorithm, RLS algorithm
	and their applications for adaptive noise cancellation, adaptive line enhancement and
	interference cancellation
4	To help to design and apply adaptive filters for real- time applications.

Course Outcomes

On the completion of this course, the students will be able to:

CO1	Demonstrate the adaptive systems and its characteristics
CO2	Devise filtering solutions for optimising the cost function indicating error in estimation of
	parameters and appreciate the need for adaptation in design.

CO3	Evaluate the performance of various methods for designing adaptive filters through estimation
	of different parameters of stationary random process clearly considering practical application
	specifications. Analyse convergence and stability issues associated with adaptive filter design
CO4	Be able to design adaptive filters for adaptive noise cancellation, adaptive line enhancement
	and interference cancellation, prediction considering present day challenges and recent research
	development.

SYLLABUS

Module 1: Introduction to adaptive systems - definitions and characteristics, Adaptive linear combiner : input signal and weight vector, the performance function, gradient and minimum mean square error, alternative expression of gradient, LMS, NLMS, sign-error, sign-data and FXLMS algorithms, transform domain LMS.

Module 2: Recursive least square algorithm, windowed RLS, computational complexity, Block adaptive filter (time and DFT domains), adaptive lattice filters, Adaptive filters with Orthogonal signals, Kalman Filter

Module 3: Adaptive model control, Adaptive inverse control and model reference controls. Plant noise and the filtered-X LMS Algorithm, Inverse control using Filtered-X LMS algorithm.

Module 4: Adaptive array and adaptive beam forming: Sidelobe cancellation, Beam forming with a Pilot signal, Narrowband experiments, Broadband experiments, Characteristics of receiving arrays, Griffiths LMS Beamformer, Adaptive beamformer with pole and zeros, signal cancellation and distortion.

Module 5: Applications of Adaptive Filters: Adaptive Noise Cancelling, Adaptive Line Enhancement, System identification, Channel equalization, Cancelling antenna side lobe Interference, Adaptive self tuning filter

Text Books:

1. B.Widrow and S. D. Sterns, Adaptive Signal Processing, Pearson Education, 2nd Indian reprint, 2002.

2. D. G. Manolokis, V. K. Ingle and S. M. Kogar, "Statistical and Adaptive Signal Processing", Mc Graw Hill International Edition, 2000.

3. S. Haykin and T. Kailath, Adaptive Filter Theory, Pearson Education, 4th Edition, 2005.

Reference Books:

- 1. Digital Signal Processing 3/E by S.K.Mitra TMH Edition.
- 2. Fundamentals of adaptive filtering, A. H. Sayed, Wiley, 2003.
- 3. Monson H. Hayes, Statistical Digital Signal Processing and Modelling, Wiley, 2002

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids

CDM 6	Industrial/guest lectures
CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1. Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

					Progra	am Outc	omes				
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	2	2	1	1		1	1	1	1	1	1
CO2	3	2	1	2		1	2	2	1	1	1
CO3	3	3	2	2		1	2	2	2	1	1
CO4	3	3	2	2	1	2	2	2	2	2	2

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Lecture	Wise	Lesson	Plan	Details	

Wee	Lect	Tentativ	Modul	Topics to be covered	Text	COs	Actual	Methodo	Remar
k		e	e		Book /	mappe	Content	logy	ks by
No.	No.	Date	No.		Refere	d	covered	used	faculty
					nces				if any
1	1		1	Introduction to adaptive	1	CO1		PPT and	
				systems				Chock-	
								Board	
	2			adaptive systems - definitions	1	CO1		Do	
				and characteristics					
	3			Adaptive linear combiner	1,3	CO1		Do	
2	4			input signal and weight vector,	1,3	CO1		Do	
	5			the performance function,	1	CO1		Do	
	6			gradient andminimum mean	1,3	CO1		Do	
				square error,					

3	7	2	LMS,	1,3	CO1	Do
	8		NLMS, sign-error, sign-data LMS	1,3	CO1	Do
	9	-	FXLMSalgorithms,	1,3	CO1	Do
4	10	-	Transform domain LMS.	1,3	CO1	Do
	11		Recursive least square algorithm,	1,3	CO1	Do
	12		windowed RLS, computational complexity,	1,3	CO1	Do
5	13		Block adaptive filter(time and DFT domains)	1	CO1	Do
	14		adaptive lattice filters,	1	CO1	Do
	15		Adaptive filters with Orthogonal signals	1	CO1	Do
6	16		Kalman Filter	1	CO1	Do
	17		Kalman Filter	1	CO2	Do
	18	3	Adaptive model control	1	CO2, CO3	Do
7	19		Adaptive inverse control	1	CO2, CO3	Do
	20		model reference controls	1	CO2, CO3	Do
	21		Plant noise and the filtered-X LMS Algorithm	1	CO2, CO3	Do
8	22		Inverse control using Filtered- X LMS algorithm.	1	CO2, CO3	Do
	23	4	Adaptive array,	1,2	CO2	Do
	24		adaptive beam forming	1,2	CO2	Do
9	25		Sidelobe cancellation	1,2	CO2, CO3	Do
	26		Beam forming with a Pilot signal,	1,2	CO2, CO3	Do
	27		Narrowband experiments	1	CO2, CO3	
10	28		Broadband experiments,	1	CO2, CO3	Do
	29		Characteristics of receiving arrays,	1	CO2	Do
	30		Griffiths LMS Beamformer	1	CO2, CO3	Do
11	31		Adaptive beamformer with pole and zeros	1	CO2	Do
	32		signal cancellation and distortion.	1	CO2	Do
	33	 5	Adaptive Noise Cancelling,	1	CO3	Do
12	34		Adaptive Line Enhancement	1	CO3	Do
	35	-	System identification	1	CO3	Do
10	36	-	Channel equalization	1	CO3	Do
13	37		System identification	1	CO4	Do
	38		Channel equalization	1	CO4	Do
	39		Cancelling antenna side lobe Interference	1	CO4	Do
14	40		Adaptive self-tuning filter	1	CO4	Do

Name of the Subject: Modern Instrumentation System Course Code: EC549 Course Title: Modern Instrumentation System Pre-requisite(s): Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	The knowledge about Silicon Sensors and its application for measurement of pressure, level,
	flow and Temperature. Biosensors
B.	The knowledge about DAS, Controller and Components involved in implementation of
	Automation system
C.	The knowledge about Distributed Control Systems and Artificial Intelligent Based Systems
D.	The knowledge about microcontroller and Telemetry

Course Outcomes:

After the completion of this course, students will be:

CO1	Gain knowledge of Silicon Sensors and its application for measurement of pressure, level,
	flow and Temperature. Biosensors
CO2	Gain knowledge of DAS, Controller and Components involved in implementation of
	Automation system
CO3	Gain knowledge of Distributed Control Systems and Artificial Intelligent Based Systems
CO4	Gain knowledge of about microcontroller and Telemetry

SYLLABUS

Module – 1 :

Review of Transducer, Principles of operations and its classification, Characteristics, Technological trends in making transducers, Silicon sensors for the measurement of pressure, level, flow and Temperature. Biosensors, application and types.

Module – 2:

Introduction about Instrumentation system. Types of Instrumentation system. Data acquisition system and its uses in intelligent Instrumentation system. Detail study of each block involved in making of DAS, Signal conditioners as DA, IA, signal converters (ADC), Sample and hold. Designing application for Pressure, Temperature measurement system using DAS. Data logger.

Module – 3 :

Introduction about Automation system. Concepts of Control Schemes, Types of Controllers. Components involved in implementation of Automation system i.e., DAS, DOS, Converter (I to P) and Actuators: Pneumatic cylinder, Relay, solenoid (Final Control Element), Computer Supervisory Control System (SCADA), Direct Digital Control's Structure and Software.

Module – 4 :

Introduction about Distribution Digital Control, Functional requirements of process control system, system architecture, Distributed Control systems, Configuration, Some popular Distributed Control Systems. Industrial control applications like cement plant, thermal power plant.

Introduction about Intelligent controllers, Model based controllers, Predictive control, Artificial Intelligent Based Systems, Experts Controller, Fuzzy Logic System and Controller, Artificial Neural Networks, Neuro-Fuzzy Control system.

Module –6 :

Introduction to microcontroller 8051, its architecture, register, pin descriptions, addressing modes, instruction set and simple programs. Industrial application of micro controller- measurement applications, automation and control applications.

Module –7 :

Introduction to telemetry, telemetry links, signal characterisations in time and frequency domain, analog and digital signals. Data transmission systm, Advantages and disadvantages of digital transmission over analog one. Time division multiplexing ,pulse modulation, Digital modulation ,Pulse code modulation and Modem.

Text Books:

- 1. Computer Based Industrial Control By Krishna Kant, PHI
- 2. Process Control Instrumentation By Curtis D. Johnson, Pearson Education

Ref. Books:

- 1. Electrical & Electronics Measurements and Instrumentation By A.K.Shawhney, Dhanpat Rai & Sons.
- 2. Electronics instrumentation By H. S. Kalsi [TMH]

Gaps in the SYLLABUS (to meet Industry/Profession requirements):

POs met through Gaps in the SYLLABUS:

Topics beyond SYLLABUS/Advanced topics/Design:

POs met through Topics beyond SYLLABUS/Advanced topics/Design:

S. No.	Course Delivery Methods
CDM 1	Lecture by use of boards/LCD projectors/OHP projectors
CDM 2	Quizzes
CDM 3	Assignments/Seminars
CDM 4	Mini projects/Projects
CDM 5	Laboratory experiments/teaching aids
CDM 6	Industrial/guest lectures

CDM 7	Industrial visits/in-plant training
CDM 8	Self- learning such as use of NPTEL materials and internets
CDM 9	Simulation

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	2	2	2	2
Assignment Marks	1	1	1	1
End Sem Examination Marks	3	3	3	3

Note: 1 for fulfilling less than 40%, 2 for fulfilling less than 70% and 3 for fulfilling above 70 %

Indirect Assessment

1.Student Feedback on Faculty

2. Student Feedback on Course Outcome

Mapping between Course Outcomes and Program Outcomes

		Program Outcomes									
Course Outcome #	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11
CO1	3	3	2	3		3	1	3	3	3	3
CO2	3	3	2	3		3	1	3	3	3	3
CO3	2	2	3	3	1	3	1	2	3	3	3
CO4	3	3	2	3	2	3	1	3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

	Mapping Between COs and Course Delivery (CD) methods						
			Course				
		Course	Delivery				
CD	Course Delivery methods	Outcome	Method				
		CO1, CO2,					
CD1	Lecture by use of boards/LCD projectors/OHP projectors	CO3	CD1				
CD2	Tutorials/Assignments	CO3, CO4	CD1				

CD3	Seminars	CO4	CD1 and CD2
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
CD8	Self- learning such as use of NPTEL materials and internets	CO4	
CD9	Simulation		

Lecture wise Lesson planning Details.

Lecture wise Lesson planning Details.

Week No.	Lect	Tentativ e	Ch. No	Topics to be covered	Text Book /	COs map	Actual Content	Methodology used	Remarks by
	No.	Date	•		Refere nces	ped	covered		faculty if any
1	L1			Illustration of course objectives and course outcomes, besides detailed introduction of the course syllabus				PPT Digi Class/Chock -Board	
	L2		1,2	ReviewofInstrumentationSystem,SensingElements, and SignalConditioners	T1	1, 2		-do-	
	L3		1,2	Transmitters, and Data presentation	T1	1, 2		-do-	
2	L4		1,3	Controllers	T1	1, 2		-do-	
	L5		1,3	Actuators and Final Control Elements	T1	1, 2		-do-	
	L6		1	Instrumentation system for measuring: Temperature	T1	1, 2		-do-	
3	L7		3,4	Instrumentation system for measuring: Level	T1	1, 2		-do-	
	L8		5	Instrumentation system for measuring: Pressure	T1	1, 2		-do-	
	L9		6	Instrumentation system for measuring: flow	T1	1, 2		-do-	
4	L10		6	Principles of signal conditioning	T1	1, 2		-do-	
	L11		7	signal level and bias change,	T1	1, 2		-do-	
	L12		7	linearization, conversion filtering	T1	2, 3		-do-	
5	L13		8	impedance matching, loading	T1	2, 3		-do-	
	L14		8	Design of passive signal conditioners	T1	2, 3		-do-	
	L15		9	Bridge circuits, RC filters	T1	2, 3		-do-	

6	L16	2, 10	Design of active signal conditioners	T1	2, 3	-do-	
	L17	10, 6	OPAMPS circuits,	T1	2, 3	-do-	
	L18	10, 6	Design of digital signal conditioners	T1	2, 3	-do-	
7	L19	10, 6	Comparator	T1	2, 3	-do-	
	L20	10	Bipolar DAC, ADC	T1	2, 3	-do-	
	L20	11	S/H for different applications	T1	2, 3	-do-	
8	L22	11	Design of Microprocessor/micr ocontroller based DAS	T1	2, 3	-do-	
	L23	12	Design of DATA logger	T1	2, 3	-do-	
	L24	13	Two wire and 4 wire transmitters,	T1	2, 3	-do-	
9	L25	13	temperature transmitters	T1	2, 3	-do-	
	L26	13	Level transmitters, pressure transmitters	T1	2, 3	-do-	
	L27	13	flow transmitters	T1	3, 4	-do-	
10	L28	13	Design of Smart transmitters.	T1	3, 4	-do-	
	L29	13	Design of on/off controller using OPAMP	T1	3, 4	-do-	
	L30	13	design of Microprocessor/Micr ocontroller based PID controller	T1	3, 4	-do-	
11	L31	18	Design of Alarm and Annunciation circuits	T2	3, 4	-do-	
	L32	11	Design of PLC	T2	3, 4	-do-	
	L33	11	Design of configurable sequential controller using PLDs	T2	3, 4	-do-	
12	L34	11	Comparison of Pneumatic	T2	3, 4	-do-	
	L35	11, 12	Hydraulic and Electrical instrumentation systems	T2	3, 4	-do-	
	L36	11, 12	Hydraulic and Electronic instrumentation systems	T2	3, 4	-do-	
13	L37	18	Electrical/Electronic instrumentation systems selection for present process industry requirement	Τ3	3, 4	-do-	
	L38	18	Control Valve and their Selection	Т3	3, 4	-do-	

La	39	20	Pumps and Selection	their	T3	3, 4	-do-	
14 L4	40	20	Motors and Selection	their	T3	3, 4	-do-	

Course code: EC617 Course title: Nanoelectronic Devices & Materials Pre-requisite(s): EC201 Electronic Devices Co- requisite(s): Credits: L: 0 T: 0 P: 0 C: 2 Class period per week: 0 Class: M. Tech. Semester / Level: 3/6 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

•••••••	
A.	The objective of this course is to present the state of the art in the areas of semiconductor
	device physics and materials technology to enable the Nanoelectronics.
B.	The fundamentals of classical CMOS technology will be discussed and the issue in scaling
	MOSFET in the sub-100nm regime will be elaborated.
C.	In this context the need for non-classical transistors with new device structure and
	nanomaterials will be elucidated.
D.	The issues in realizing Germanium and compound semiconductor MOSFET will be
	presented.
E.	Extensive materials characterization techniques will also be discussed, which help in
	engineering high performance transistors.

Course Outcomes:

After the completion of this course, students will be able to:

CO1	Infer the semiconductor device physics and materials technology.
CO2	Interpret The fundamentals of classical CMOS technology and the issue in scaling MOSFET
	in the sub-100nm regime.
CO3	Appraise the theory of non-classical transistors with new device structure and
	nanomaterials.
CO4	Infer the issues in realizing Germanium and compound semiconductor MOSFET and
	materials characterization.

SYLLABUS

Overview: Nano devices, Nano materials, Nano characterization, Definition of Technology node, Basic CMOS Process flow, MOS Scaling theory, Issues in scaling MOS transistors: Short channel effects, Description of a typical 65 nm CMOS technology, Requirements for Non-classical MOS transistor.

Module – 2:

Module – 1:

MOS capacitor, Role of interface quality and related process techniques, Gate oxide thickness scaling trend, SiO2 vs High-k gate dielectrics. Integration issues of high-k.

Interface states, bulk charge, band offset, stability, possible candidates, CV and IV techniques, Metal gate transistor: Motivation, requirements, Integration Issues., Transport in Nano MOSFET, velocity saturation, ballistic transport, injection velocity, velocity overshoot.

Module – 3:

SOI - PDSOI and FDSOI, Ultrathin body SOI - double gate transistors, integration issues, Vertical transistors - FinFET and Surround gate FET, Metal source/drain junctions - Properties of Schottky junctions on Silicon, Germanium and compound semiconductors -Work function pinning.

Module – 4:

Germanium Nano MOSFETs: strain, quantization, Advantages of Germanium over Silicon, PMOS versus NMOS. Compound semiconductors - material properties, MESFETs Compound semiconductors MOSFETs in the context of channel quantization and strain, Hetero structure MOSFETs exploiting novel materials, strain, quantization, Synthesis of Nanomaterials: CVD, Nucleation and Growth, ALD, Epitaxy, MBE.

Model – 5:

Compound semiconductor hetero-structure growth and characterization: Quantum wells and Thickness measurement techniques: Contact - step height, Optical - reflectance and ellipsometry. AFM, Characterization techniques for nanomaterials: FTIR, XRD, AFM, SEM, TEM, EDAX etc. Applications and interpretation of results. Emerging nanomaterials: Nanotubes, nanorods and other nanostructures, LB technique, Soft lithography etc. Microwave assisted synthesis, Self-assembly etc.

Text Books:

- 1. Fundamentals of Modern VLSI Devices, Y. Taur and T. Ning, Cambridge University Press.
- 2. Silicon VLSI Technology, Plummer, Deal, Griffin, Pearson Education India.
- 3.

Reference Book:

1. Encyclopedia of Materials Characterization, Edited by: Brundle, C.Richard; Evans, Charles A. Jr.; Wilson, Shaun ; Elsevier.

Gaps in the syllabus (to meet Industry/Profession requirements): N/A

POs met through Gaps in the Syllabus: PO8 will be met through report-writing/presentationbased assignment

Topics beyond syllabus/Advanced topics/Design: Learning from papers

POs met through Topics beyond syllabus/Advanced topics/Design: Learning from papers

CD #	Course Delivery methods
CD1	Lecture by use of boards/LCD projectors/OHP projectors
CD2	Quizzes
CD3	Assignments/Seminars
CD4	Mini projects/Projects
CD5	Laboratory experiments/teaching aids

CD6	Industrial/guest lectures
CD7	Industrial visits/in-plant training
CD8	Self- learning such as use of NPTEL materials and internets
CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

CO1	CO2	CO3	CO4
3	3	3	
			3
3	3	3	3
	CO1 3 3	CO1 CO2 3 3 3 3	CO1 CO2 CO3 3 3 3 3 3 3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Indirect Assessment -

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome		Program Outcomes									
#	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO	PO
						6				10	11
CO1	1	1	1	1	1				2	1	1
CO2	2	1	2	1	2				2	1	1
CO3	1	1	1						1	1	1
CO4		2	3	3	2			2	2	1	1

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

CD	Course Delivery methods	Course Outcome	Course Delivery Method
CD1	Lecture by use of boards/LCD projectors/OHP projectors		
CD2	Quizzes	CO1, CO2, CO3	CD2
CD3	Assignments/Seminars	CO3	CD3
CD4	Mini projects/Projects		
CD5	Laboratory experiments/teaching aids		
CD6	Industrial/guest lectures		
CD7	Industrial visits/in-plant training		
	Self- learning such as use of NPTEL materials and	CO1, CO2, CO3,	CD8
CD8	internets	CO4	
CD9	Simulation		

Course code: EC618 Course title: Boiphotonics Pre-requisite(s): EC201 Electronic Devices, EC257 Electromagnetic field and waves Co- requisite(s): Credits: L: 0 T: 0 P: 0 C: 2 Class period per week: 0 Class: M. Tech. Semester / Level: 3/6 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

А.	EM and Quantum Picture of Light
B.	Light-matter interactions
C.	Explain optical imaging
D.	Optical manipulation of biological materials

Course Outcomes:

After the completion of this course, students will be able to:

CO1	Explain EM and Quantum Picture of Light
CO2	Justify the interaction of Light and matter
CO3	Write down the application of optical imaging
CO4	Manipulate biological material for optical use

SYLLABUS

Module:1 Introductory Optics.

Geometric, Wave, EM and Quantum Picture of Light., Concept of phase, polarization and coherence, Diffraction and Interference.

Module:2 Light-matter interactions.

Energy level picture of materials, Photons, Photoelectric effect, Interaction of photons with materials, Phosphorescence and fluorescence, Stimulated emission of photons, Principle of laser action, Laser types and applications (CW, Pulsed, Ultra-fast, Solid state, Gas, Dye ...), Spectroscopy: Types and applications (UV-Vis, Infrared, Raman, FTIR ...).

Module 3: Optical Imaging I.

Basic imaging theory, concept of diffraction limit, Optical microscope, Methods for contrastgeneration (Dark-field, Phase contrast, DIC, Polarization), Fluorescence microscopy, Fluorescence techniques (FRET, FLIM, FRAP, FCS ...), Nanoparticle fluorescence, 3D sectioning: Confocal and multi-photon imaging. Nanoparticle fluorescence.Super-resolution techniques (STED, STEM, STORM, PALM ...), Super-resolution image reconstruction methods.

Module4: Optical Imaging II

Biomedical (Physiological Imaging), Light Scattering phenomena, Tomographic techniques: OCT, Image reconstruction techniques.

Module:5 Other applications.

Optical biosensors, Optical manipulation of biological materials, Optical tweezers, Laser dissection and surgery. Neural excitation.

Text Books:

1. Bahaa Saleh and Malvin Teich, Fundamentals of Photonics, Wiley & Sons, (1991). **Reference Book:**

1. Paras N. Prasad, Introduction to Biophotonics, Wiley & Sons (2003).

Gaps in the syllabus (to meet Industry/Profession requirements): N/A

POs met through Gaps in the Syllabus: PO8 will be met through report-writing/presentationbased assignment

Topics beyond syllabus/Advanced topics/Design: Learning from papers

POs met through Topics beyond syllabus/Advanced topics/Design: Learning from papers

CD #	Course Delivery methods
CD1	Lecture by use of boards/LCD projectors/OHP projectors
CD2	Quizzes

CD3	Assignments/Seminars
CD4	Mini projects/Projects
CD5	Laboratory experiments/teaching aids
CD6	Industrial/guest lectures
CD7	Industrial visits/in-plant training
CD8	Self- learning such as use of NPTEL materials and internets
CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment
Assignment Marks	10
Quizzes	30
End Sem Examination Marks	60

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	3	3	3	
Assignment Marks				3
End Sem Examination Marks	3	3	3	3

If satisfying and < 34% = 1, 34-66% = 2, > 66% = 3

Indirect Assessment -

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

Course Outcome		Program Outcomes									
#	PO1	PO2	PO3	PO4	PO5	PO	PO7	PO8	PO9	PO	PO
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CO2	2	1	2	1	2				2	1	1
CO3	1	1	1						1	1	1
CO4		2	3	3	2			2	2	1	1

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Mapj	ping Between COs and Course Delivery (CD) methods			
CD	Course Delivery methods	Course Outcome	Course Delivery Method	
CD1	Lecture by use of boards/LCD projectors/OHP projectors			
CD2	Quizzes	CO1, CO2, CO3	CD2	
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CD5	Laboratory experiments/teaching aids			
CD6	Industrial/guest lectures			
CD7	Industrial visits/in-plant training			
CD8	Self- learning such as use of NPTEL materials and internets	CO1, CO2, CO3, CO4	CD8	
CD9	Simulation			

Name of the Subject: Neural Networks and Applications Course Code: EC619 Course Title: Neural Networks and Applications Pre-requisite(s): Co-requisite(s): Credits: L:3 T:0 P:0 C: 3 Class schedule per week: 03 Class: M. Tech (Instrumentation) Semester / Level: 02 Branch: ECE Name of Teacher:

Course Objectives:

This course enables the students:

A.	Define the fundamental concepts of artificial neuron
B.	Analyze the different neural network algorithms
C.	Show the application of neural network and its functionality
D.	Recognize the constraints and suitable algorithms for classification using ANN

Course Outcomes:

After the completion of this course, students will be:

CO1	Recognize the fundamental concepts of ANN
CO2	Design the different ANN algorithms
CO3	Analyze the constraint of ANN for solving the complex problems
CO4	Outline the suitable algorithms for artificial intelligent system & its functionality

SYLLABUS

Module -1:

Introduction to Artificial Neural Networks, Artificial Neuron Model and Linear Regression, Gradient Descent Algorithm, Nonlinear Activation Units and Learning Mechanisms.Learning Mechanisms-Hebbian, Competitive, Boltzmann

Module -2:

Associative memory, Associative Memory Model, Condition for Perfect Recall in Associative Memory, Statistical Aspects of Learning, V.C. Dimensions: Typical Examples.

Module -3:

Single-Layer Perceptions, Unconstrained Optimization: Gauss-Newton's Method, Linear Least Squares Filters, Least Mean Squares Algorithm, Perceptron Convergence Theorem, Bayes Classifier & Perceptron: An Analogy, Bayes Classifier for Gaussian Distribution,

Module -4:

Back Propagation Algorithm, Practical Consideration in Back Propagation Algorithm, Solution of Non-Linearly Separable Problems Using MLP, Heuristics For Back-Propagation, Multi-Class Classification Using Multi-layered Perceptrons,

Module -5:

Radial Basis Function Networks: Cover's Theorem, Radial Basis Function Networks: Separability & Interpolation, Posed Surface Reconstruction, Solution of Regularization Equation: Greens Function, Use of Greens Function in Regularization Networks, Regularization Networks and Generalized RBF

Text Books:

Simon Haykin, "Neural Networks and Learning Machines", , Third Edition, Pearson

Reference Book:

Gaps in the syllabus (to meet Industry/Profession requirements): N/A

POs met through Gaps in the Syllabus: PO8 will be met through report-writing/presentationbased assignment

Topics beyond syllabus/Advanced topics/Design: Learning from papers

POs met through Topics beyond syllabus/Advanced topics/Design: Learning from papers

CD #	Course Delivery methods
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CD9	Simulation

Course Outcome (CO) Attainment Assessment tools & Evaluation procedure

Direct Assessment

Assessment Tool	% Contribution during CO Assessment					
Assignment Marks	10					
Quizzes	30					
End Sem Examination Marks	60					

Assessment Components	CO1	CO2	CO3	CO4
Quizzes	3	3	3	
Assignment Marks				3
End Sem Examination Marks	3	3	3	3

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Indirect Assessment -

- 1. Student Feedback on Faculty
- 2. Student Feedback on Course Outcome

Mapping between Objectives and Outcomes

Mapping of Course Outcomes onto Program Outcomes

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CD8	internets	CO4				
CD9	Simulation					